Model-Based Evolutionary Algorithms Part 2: Linkage Tree Genetic Algorithm

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MBEA

Evolutionary Algorithms

- Population-based, stochastic search algorithms
- Exploitation: selection
- Exploration: mutation & crossover

Model-Based Evolutionary Algorithms

- Population-based, stochastic search algorithms
- Exploitation: selection
- Exploration:
 - Learn a (probabilistic) model from selected solutions
 - ② Generate new solutions from the model (& population)

GOMEA

Gene-pool Optimal Mixing Evolutionary Algorithm

- Population-based, stochastic search algorithms
- Exploitation: selection (by replacement)
- Exploration:
 - Learn a Family-Of-Subsets model
 - ② Generate new solutions through optimal mixing

GOMEA: design objectives

- Be able to efficiently learn dependency information (= linkage) between variables
- Be able to efficiently decide between competing building blocks
- Transfer all optimal building blocks from the parents to the offspring solution

Family Of Subsets (FOS) model

- Key idea is to identify groups of problem variables that together make an important contribution to the quality of solutions.
- These variable groups are interacting in a non-linear way and should be processed as a block = building block

FOS \mathcal{F}

Dependency structure generally called a Family Of Subsets (FOS).

- Let there be ℓ problem variables $x_0, x_1, \ldots, x_{\ell-1}$.
- Let *S* be a set of all variable indices $\{0, 1, \dots, \ell 1\}$.
- A FOS \mathcal{F} is a set of subsets of the set S.
- FOS \mathcal{F} is a subset of the powerset of S ($\mathcal{F} \subseteq \mathcal{P}(S)$).

Example Family Of Subsets (FOS) models:

• Univariate FOS structure

 $\mathcal{F} = \{\{0\}, \{1\}, \{2\}, \{3\}, \{4\}, \{5\}, \{6\}, \{7\}, \{8\}, \{9\}\}$

• Marginal Product FOS Structure

$$\mathcal{F} = \{\{0,1,2\},\{3\},\{4,5\},\{6,7,8,9\}\}$$

• Linkage Tree FOS Structure

$$\mathcal{F} = \{\{7, 5, 8, 6, 9, 0, 3, 2, 4, 1\}, \\ \{7, 5, 8, 6, 9\}, \{0, 3, 2, 4, 1\}, \{7\}, \{5, 8, 6, 9\}, \\ \{0, 3, 2, 4\}, \{1\}, \{5, 8, 6\}, \{9\}, \{0, 3\}, \{2, 4\}, \\ \{5, 8\}, \{6\}, \{0\}, \{3\}, \{2\}, \{4\}, \{5\}, \{8\}\} \end{cases}$$

Linkage Tree

- Problem variables in subset are considered to be dependent on each other but become independent in a child subset.
- \approx Path through dependency space, from univariate to joint.
- Linkage tree has ℓ leaf nodes (= single problem variables) and $\ell 1$ internal nodes.



Linkage Tree Learning

- Start from univariate structure.
- Build linkage tree using bottom-up hierarchical clustering algorithm.
- Similarity measure:
 - **9** Between individual variables *X* and *Y*: mutual information I(X, Y).

$$I(X, Y) = H(X) + H(Y) - H(X, Y)$$

2 Between cluster groups X_{F^i} and X_{F^j} : average pairwise linkage clustering (= unweighted pair group method with a arithmetic mean: UPGMA).

$$I^{UPGMA}(X_{F^{i}}, X_{F^{j}}) = rac{1}{|X_{F^{i}}||X_{F^{j}}|} \sum_{X \in X_{F^{i}}} \sum_{Y \in X_{F^{j}}} I(X, Y).$$

(H(X), H(Y), H(X, Y)) are the marginal and joint entropies)

Linkage Tree Learning

- This agglomerative hierarchical clustering algorithm is computationally efficient.
- Only the mutual information between pairs of variables needs to be computed once, which is a $O(\ell^2)$ operation.
- The bottom-up hierarchical clustering can also be done in $O(\ell^2)$ computation by using the *reciprocal nearest neighbor chain* algorithm.
- note: commonly used bottom-up hierarchical clustering algorithms (*hclust* and *agnes* in R) have $O(\ell^3)$ complexity.

Optimal Mixing EA

- FOS linkage models specify the linked variables.
- A subset of the FOS is used as crossover mask
- Crossover is greedy: only improvements (or equal) are accepted.
- Each generation a new FOS model is build from selected solutions.
- For each solution in the population, all subsets of the FOS are tried with a donor solution randomly picked from the population
- Recombinative OM (ROM) and Gene-pool OM (GOM)
 - ROM is GA-like: select single donor solution to perform OM with
 - GOM is EDA-like: select new donor solution for each subset in OM

Gene-pool Optimal Mixing EA

```
GOMEA()
Pop ← InitPopulation()
while NotTerminated(Pop)
FOS ← BuildFOS(Pop)
forall Sol ∈ Pop
forall SubSet ∈ FOS
Donor ← Random(Pop)
Sol ← GreedyRecomb(Sol,Donor,Subset,Pop)
return Sol
```

GreedyRecomb(Sol,Donor,SubSet,Pop)

NewSol ← ReplaceSubSetValues(Sol,SubSet,Donor)
if ImprovementOrEqual(NewSol,Sol)
 then Sol ← NewSol
return Sol

Recombinative Optimal Mixing EA

```
ROMEA()
Pop ← InitPopulation()
while NotTerminated(Pop)
FOS ← BuildFOS(Pop)
forall Sol ∈ Pop
Donor ← Random(Pop)
forall SubSet ∈ FOS
Sol ← GreedyRecomb(Sol,Donor,Subset,Pop)
return Sol
```

GreedyRecomb(Sol,Donor,SubSet,Pop)

NewSol ← ReplaceSubSetValues(Sol,SubSet,Donor)
if ImprovementOrEqual(NewSol,Sol)
 then Sol ← NewSol
return Sol

Optimal Mixing

- Characteristic of Optimal Mixing is the use of intermediate function evaluations (inside variation)
- Can be regarded as greedy improvement of existing solutions
- Coined Optimal Mixing because better instances for substructures are immediately accepted and not dependent on noise coming from other parts of the solution
- Building block competition no longer a stochastic decision making problem that requires a sizable minimal population size
- Population sizes in GOMEA much smaller than in GAs or EDAs.

Linkage Tree Genetic Algorithm

- The LTGA is an instance of GOMEA that uses a Linkage Tree as FOS model
- Each generation a new hierarchical cluster tree is build.
- For each solution in population, traverse tree starting at the top.
- Nodes (= clusters) in the linkage tree used as crossover masks.
- Select random donor solution, and its values at the crossover mask replace the variable values from the current solution.
- Evaluate new solution and accept if better/equal, otherwise reject.

Convergence model

Univariate FOS model on onemax problem

- *l*: string length
- *n*: population size
- *p*(*t*): proportion bit '1' at generation *t*
- q(t): proportion bit '0' at generation t

Bit '0' only survive if parent and donor both have a '0' at that index:

•
$$q(t+1) = q^2(t)$$

•
$$p(t) = 1 - [1 - p(0)]^{2^t}$$

Number of function evaluations FE:

• In 1 generation:

$$FE = 2 p(t)([1 - p(t)] \times \ell \times n$$

• After *g* generations:

$$FE = \sum_{t=0}^{g} 2 p(t) ([1-p(t)] \times \ell \times n)$$

• After convergence *g*_{conv}:

$$FE = 2 \left[1 - p(0) \right] \times \ell \times n$$

• Initial random population (p(0) = 0.5):

$$FE = \ell \times n \qquad \Rightarrow \qquad O(\ell \, \log \ell)$$

$$\begin{split} &\sum_{t=0}^{g} p(t)([1-p(t)]) \\ &= \sum_{t=0}^{g} q(t)([1-q(t)]) \\ &= q(0)[1-q(0)] + q(1)[1-q(1)] + \dots + q(g)[(1-q(g)]) \\ &= q(0) - q(1) + q(1) - q(2) + \dots - q(g) + q(g) - q^2(g) \\ &= q(0) - [q(0)]^{2^{(g+1)}} \\ g_{conv}: &\to q(0) \end{split}$$

Minimal population size

Need to have at least one bit '1' at each index:

$$\begin{array}{rcl} Prob[success] &=& [1 - (1 - p(0))^n]^{\ell} \\ &\approx& 1 - \ell \; [1 - p(0)]^n \\ 1 - 0.01 &=& 1 - \ell \; [1 - \frac{1}{2}]^n \\ n &=& \log_2(100\ell) \\ n &=& O(\log \ell) \end{array}$$

Deceptive Trap Function

Interacting, non-overlapping, deceptive groups of variables.

$$f_{ ext{DT}}(x) = \sum_{i=0}^{l-k} f_{ ext{DT}}^{ ext{sub}} \left(x_{(i,\dots,i+k-1)}
ight)$$





Nearest-neighbor NK-landscape

• Overlapping, neighboring random subfunctions

$$f_{\text{NK-S1}}(x) = \sum_{i=0}^{l-k} f_{\text{NK}}^{\text{sub}} \left(x_{(i,\dots,i+k-1)} \right) \text{ with } f_{\text{NK}}^{\text{sub}} \left(x_{(i,\dots,i+k-1)} \right) \in [0..1]$$

• eg. 16 subsfcts, length k = 5, overlap $o = 4 \Rightarrow$ stringlength $\ell = 20$



• Global optimum computed by dynamic programming

- Benchmark function: structural information is not known !
- \Rightarrow Randomly shuffled variable indices.

Experiments

- Compare GA, EDA, and GOMEA while each are learning the Marginal Product (MP) *FOS* structure, and GOMEA learning the Linkage Tree (LT) as *FOS* structure.
- Note:
 - EDA using MP = Extended Compact GA (ECGA).
 - GOMEA using LT = Linkage Tree Genetic Algorithm (LTGA).
 - hBOA = EDA learning a Bayesian network each generation.

Experiments - Onemax





Number of variables

Experiments - Deceptive trap

Time to optimum (seconds)



Number of variables

Experiments - Overlapping NK

Time to optimum (seconds)



Number of variables

Experiments



Figure: LTGA vs. ILS: 100 NK problems

Iterated Local Search: perturbation size each time randomly picked between 2 and 10 bits (= better than any fixed value).

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Model-Based Evolutionary Algorithms

Experiments - HIFF

Time to optimum (seconds)



Number of variables

Experiments - HTrap

Time to optimum (seconds)



Number of variables

Experiments - MAX-CUT 2D square grid

Time to optimum (seconds)



Number of variables

Conclusions¹

- "Blind" Evolutionary Algorithms are limited in their capability to detect and exploit partial solutions (building blocks).
- Optimal Mixing Evolutionary Algorithms efficiently learn important building blocks and efficiently decide between competing building blocks
- Linkage Tree appears to be good compromise between FOS model complexity and search efficiency.

¹http://homepages.cwi.nl/~bosman/source_code.php