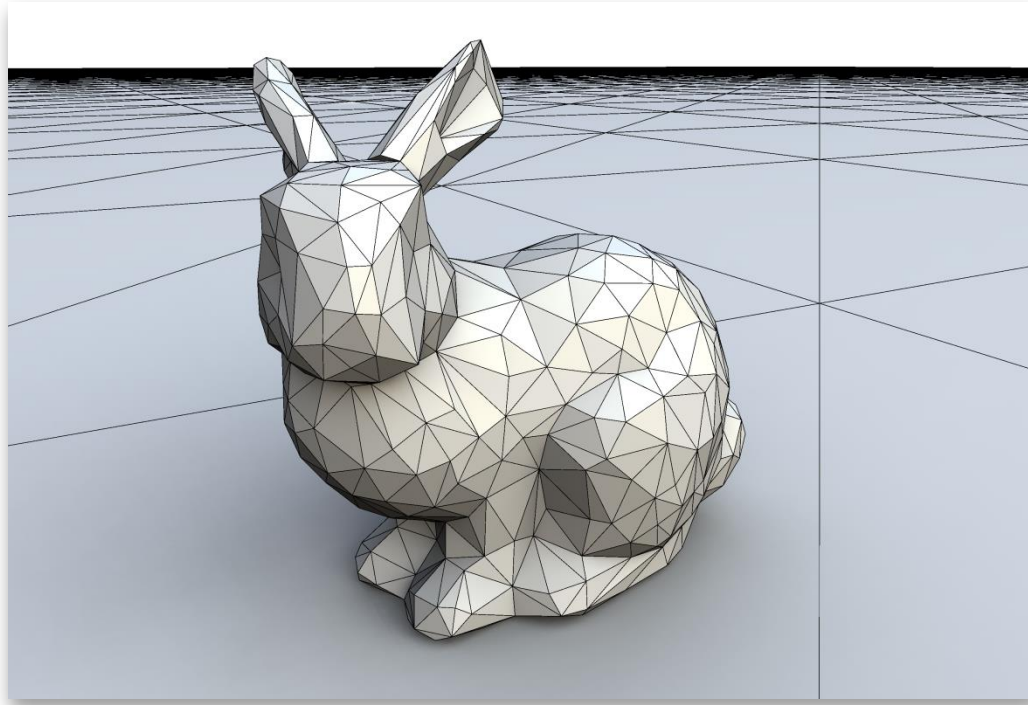


Graphics 2014



Introduction

Computer Graphics

Different Types of Graphics

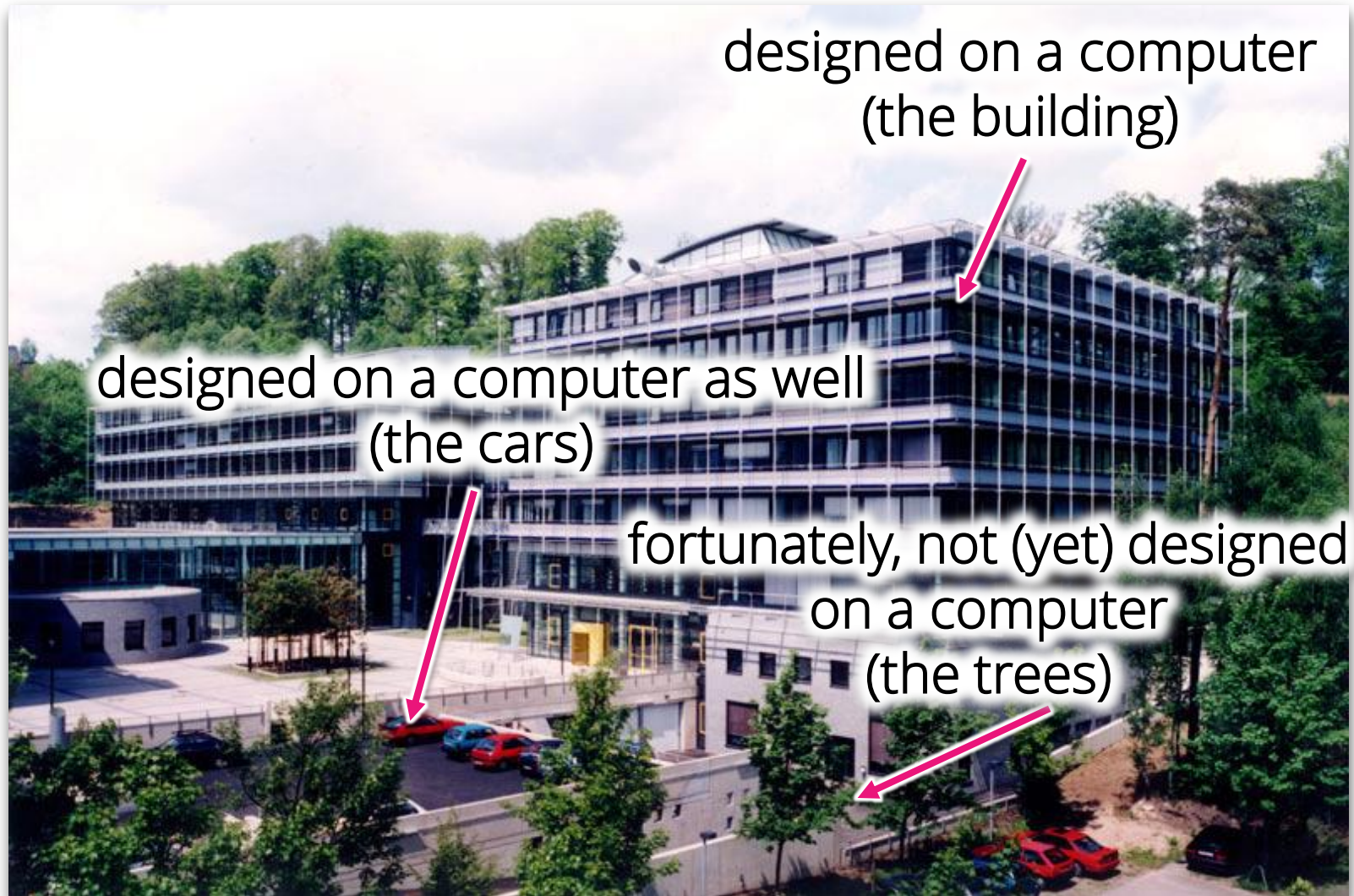
CAD / CAM

- Precision Guarantees
- Geometric constraints (e.g. exact circles)
- Modeling guided by rules and constraints



[aimatshape.net]

The Modern World...

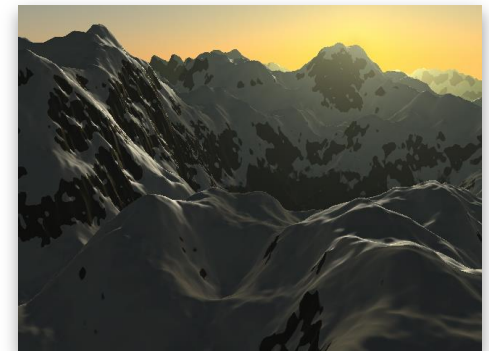
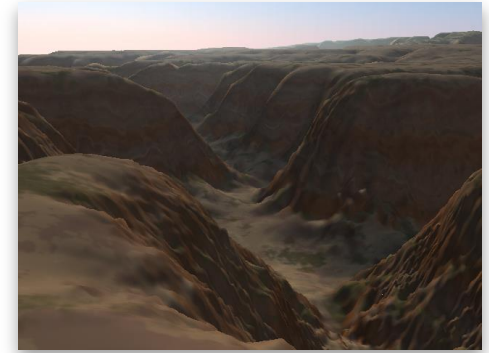


[c.f. Danny Hillis, Siggraph 2001 keynote]

Different Types of Graphics

Games & Movies

- Has to “look” good
- Natural Phenomena
- Ad-hoc techniques are ok
- For example:
textures & shaders
to “fake” details
- More complexity, but
less rigorous



Different Types of Graphics

Scientific Visualization

- Understanding data
- Simulation, medicine, empirical sciences, ...
- Focus on analysis or presentation of insights
- Human perception plays a role, too.



[S. Guthe et al., IEEE Visualization 2002]

Data-Driven Graphics

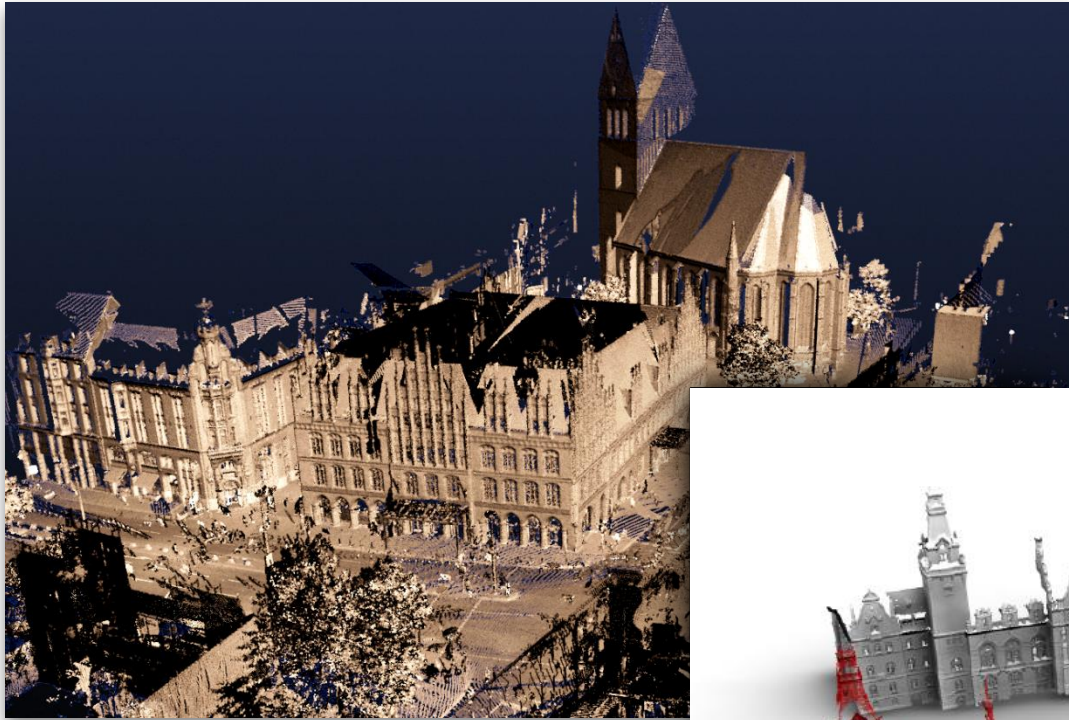
Learning from real-world data

- Complexity of reality
- Machine learning + physical measurement

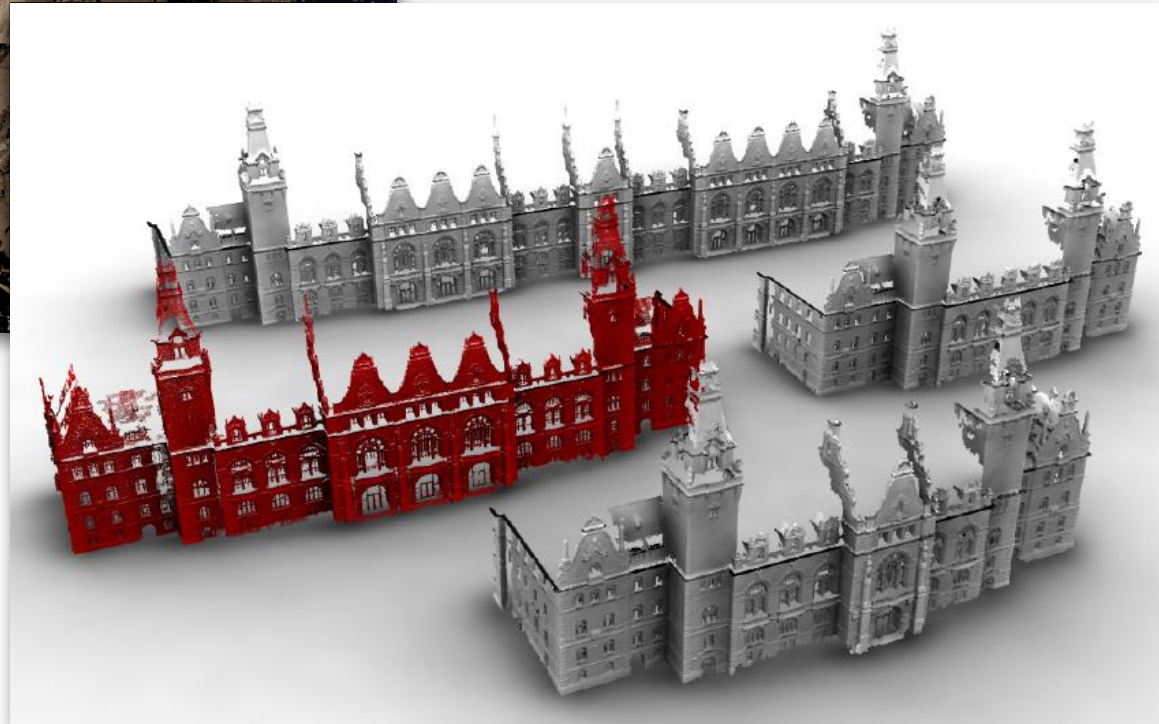


[Ihrke et al., CCD 2012]

Data-Driven Graphics



[courtesy of Claus Brenner,
IKG Hannover]



[M. Bokeloh et al., Siggraph 2010]

New Directions

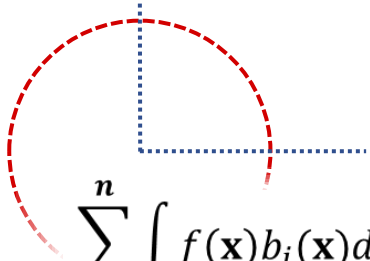
New challenges ahead

- Computational photography
- Fabrication
- Smart image/video editing
- 3D computer vision / scene understanding

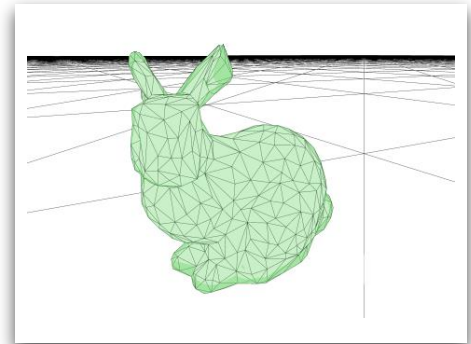
Topics Covered in This Lecture

Topics

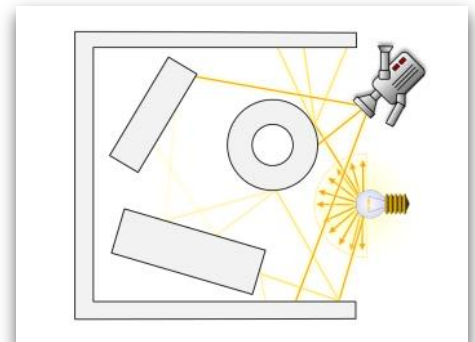
Mathematics ($\approx 50\%$)


$$\sum_{i=1}^n \int_{\Omega} f(\mathbf{x}) b_i(\mathbf{x}) d\mathbf{x}$$

Core Graphics ($\approx 40\%$)



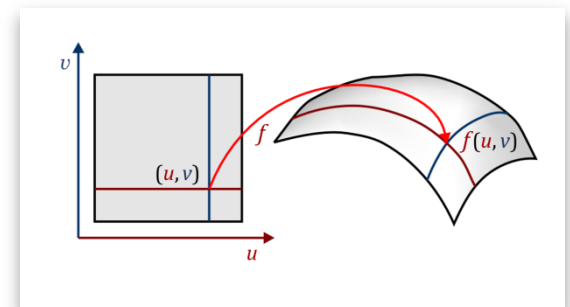
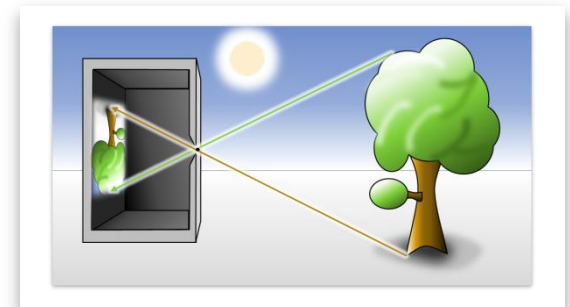
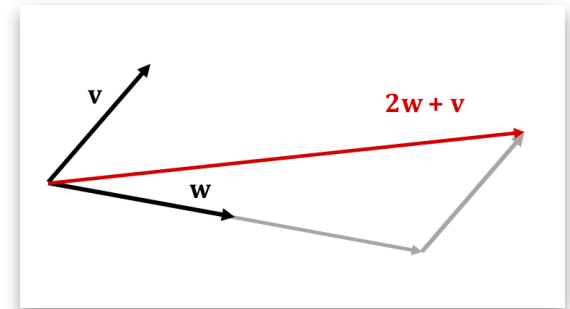
Advanced Graphics ($\approx 10\%$)



Mathematics

Mathematics

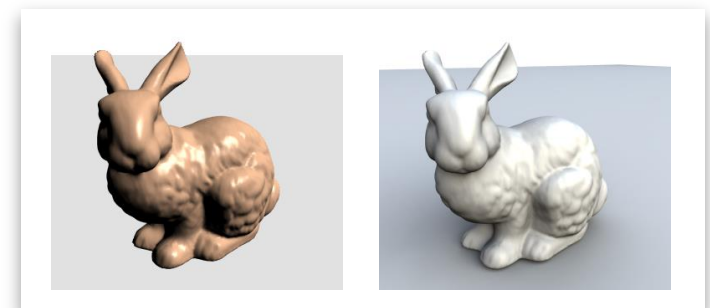
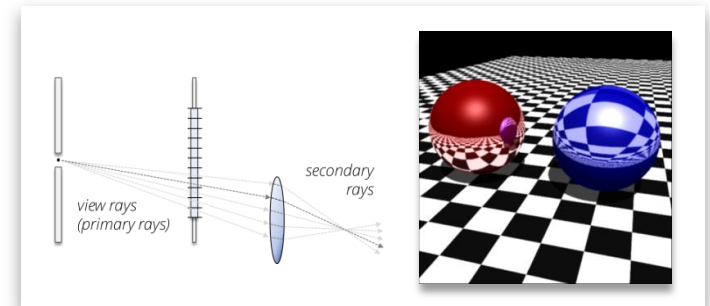
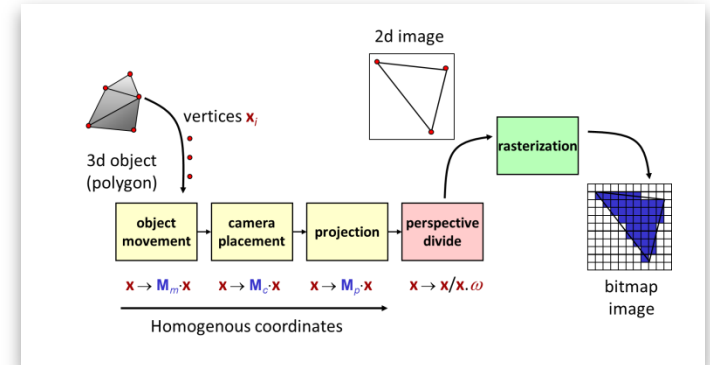
- Linear algebra
 - vectors / points
 - linear maps / matrices
 - linear systems of equations
- Projective geometry
 - Homogeneous coordinates
 - Perspective transformations
- Geometric modeling
 - Primitives (triangles, spheres, etc.)
 - Curves and surfaces
 - Differential properties / normals



Core Graphics

Core Graphics

- Rasterization
 - Camera models / perspective
 - Visibility algorithms
 - Rasterization pipeline
- Raytracing
 - Ray visibility queries
 - Data structures
 - Recursive raytracing
- Special effects
 - Basic materials
 - Shadows

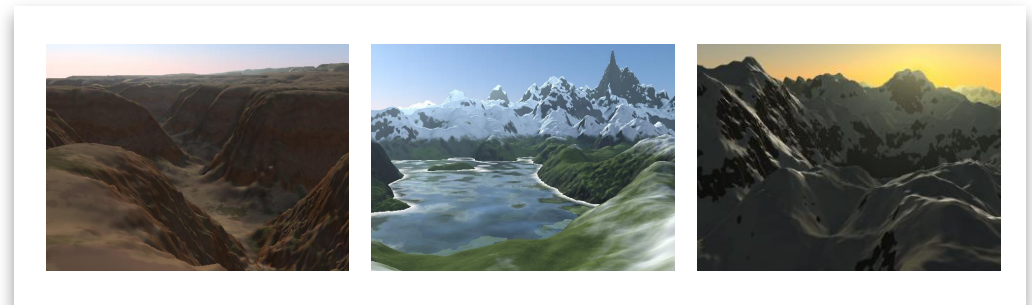
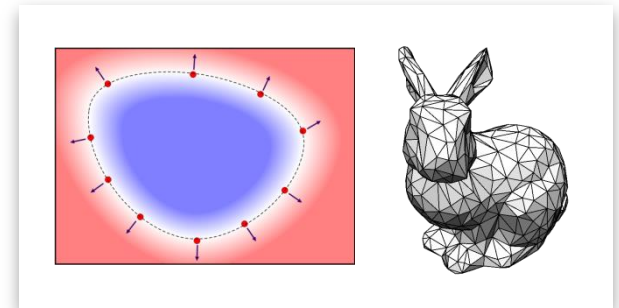
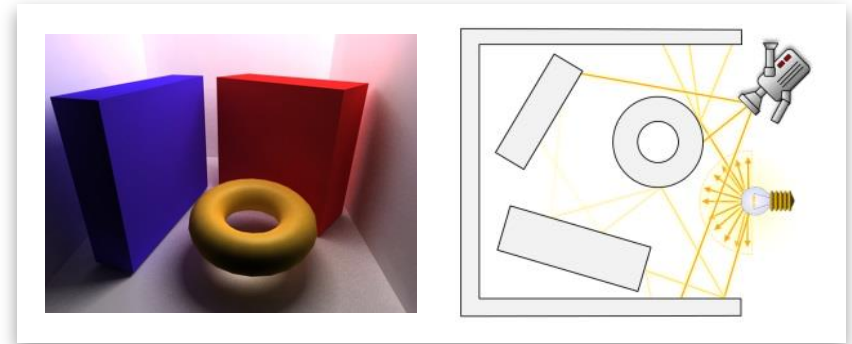


Advanced Graphics

Advanced Topics

- Global Illumination
- Advanced modeling
- GPUs & Shaders

(as time permits...)



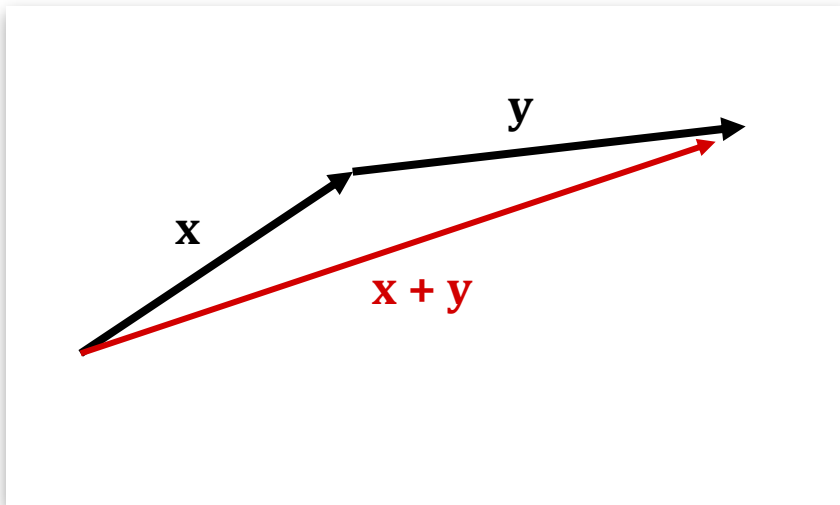
Lecture Fast-Forward

UU Graphics 2014

Step 1: Setting the stage

- We need to describe 2D and 3D geometry
- Language: *Vector spaces*

UU Graphics 2014

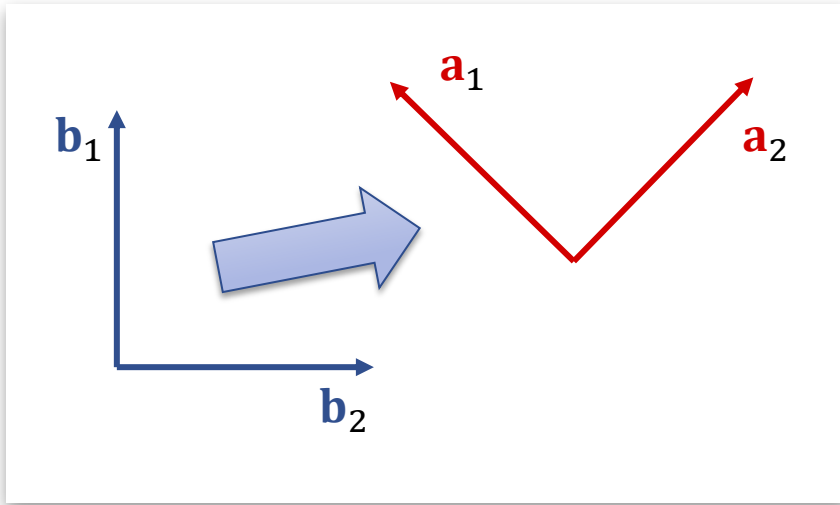


$$\mathbf{x} + \mathbf{y} = \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ x_3 + y_3 \end{pmatrix}$$

Vectors

- Points / arrows in d -dimensional space
- Operation: concatenation (+) and scaling (*)
- Columns of numbers

UU Graphics 2014

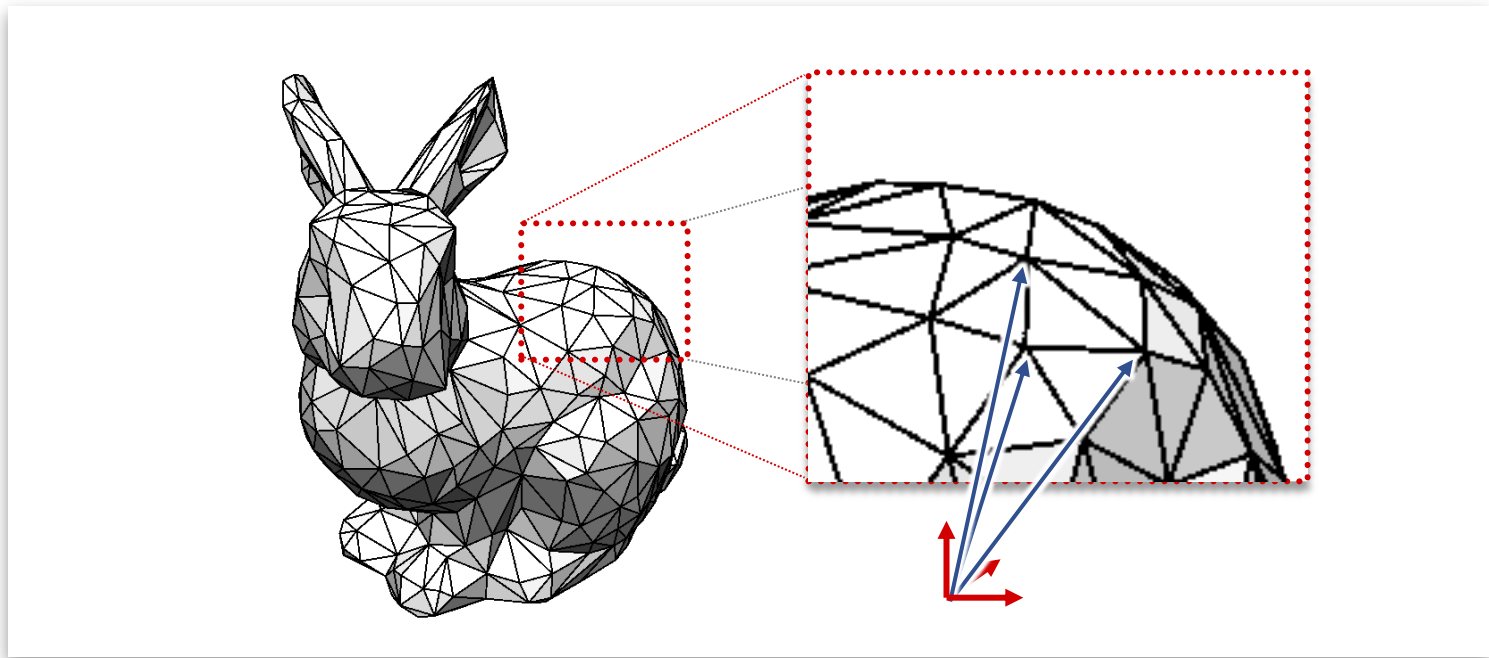


$$\mathbf{a} = \left(\begin{array}{c} \text{red axes} \end{array} \right) \cdot \mathbf{b}$$
$$= \mathbf{M} \cdot \mathbf{b}$$

Matrices

- Changing coordinate systems
- Write new coordinates in $d \times d$ array of numbers
- Transformations: scaling, rotation, etc...

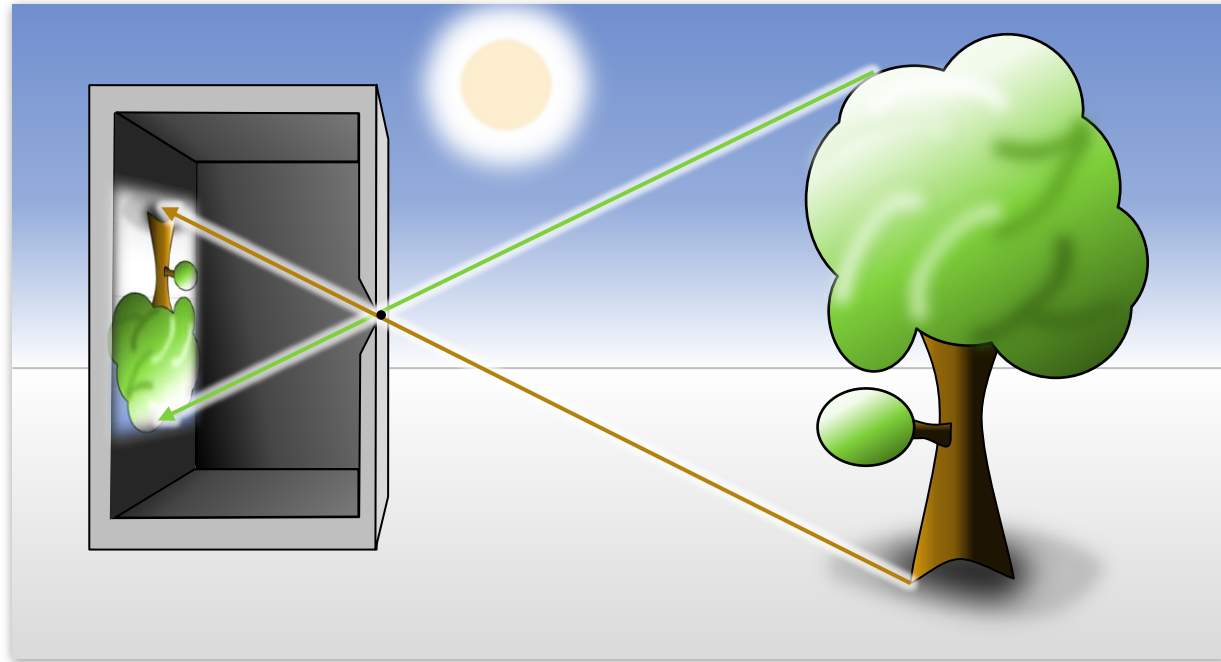
UU Graphics 2014



Modeling

- Primitives: **Triangles**, spheres, boxes, etc...
- 3 position vectors = 1 triangle
- Transformations

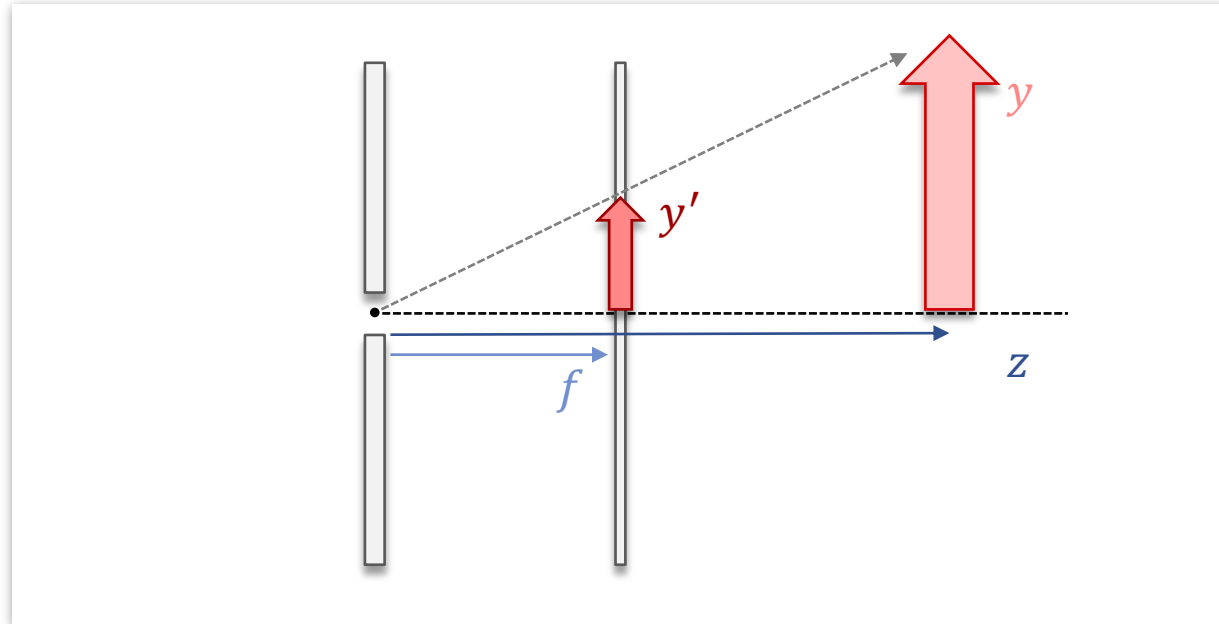
UU Graphics 2014



Perspective projection

- Mapping images to the screen
- Pinhole camera
- Visibility problem

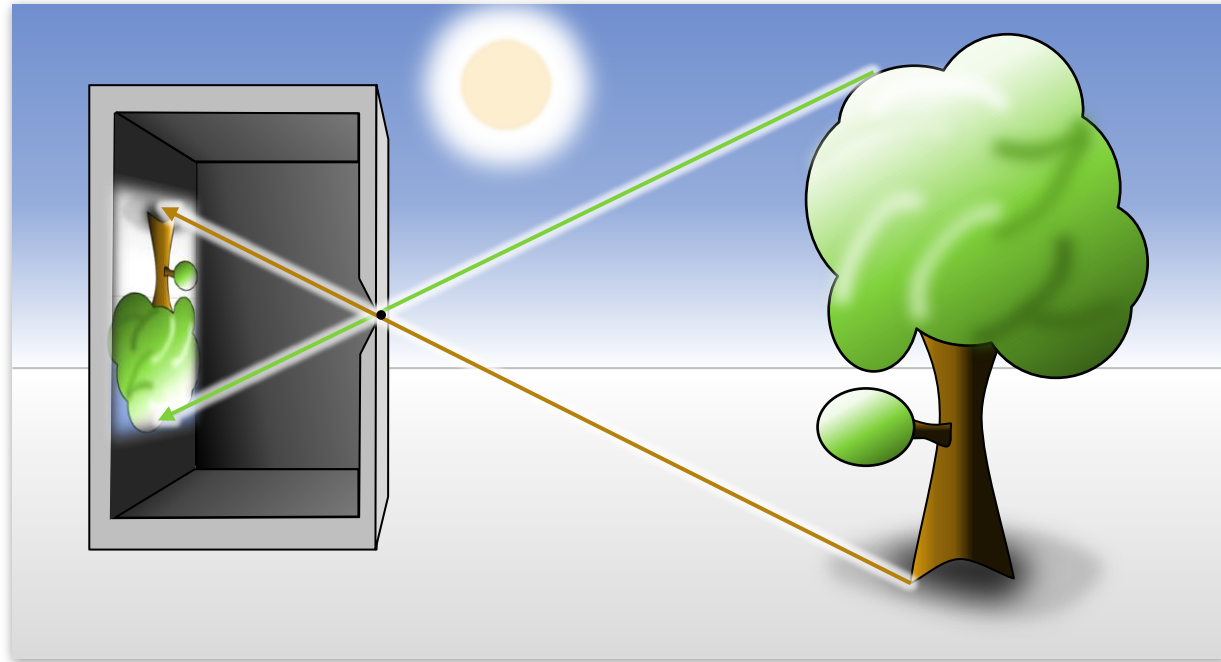
UU Graphics 2014



Mathematics

- Projective geometry
- Homogeneous coordinates

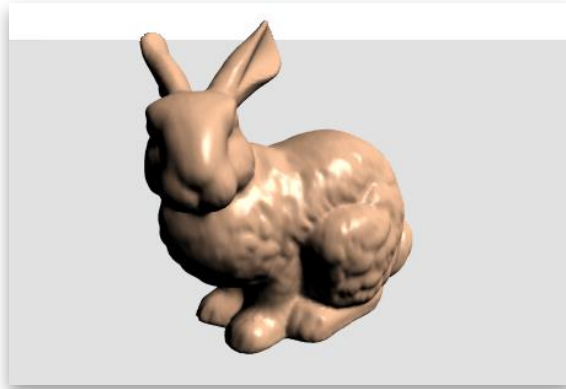
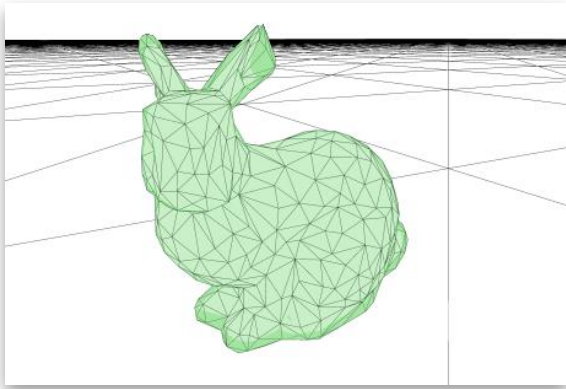
UU Graphics 2014



Computer science

- Visibility algorithms & data structures
- z-Buffer, raytracing

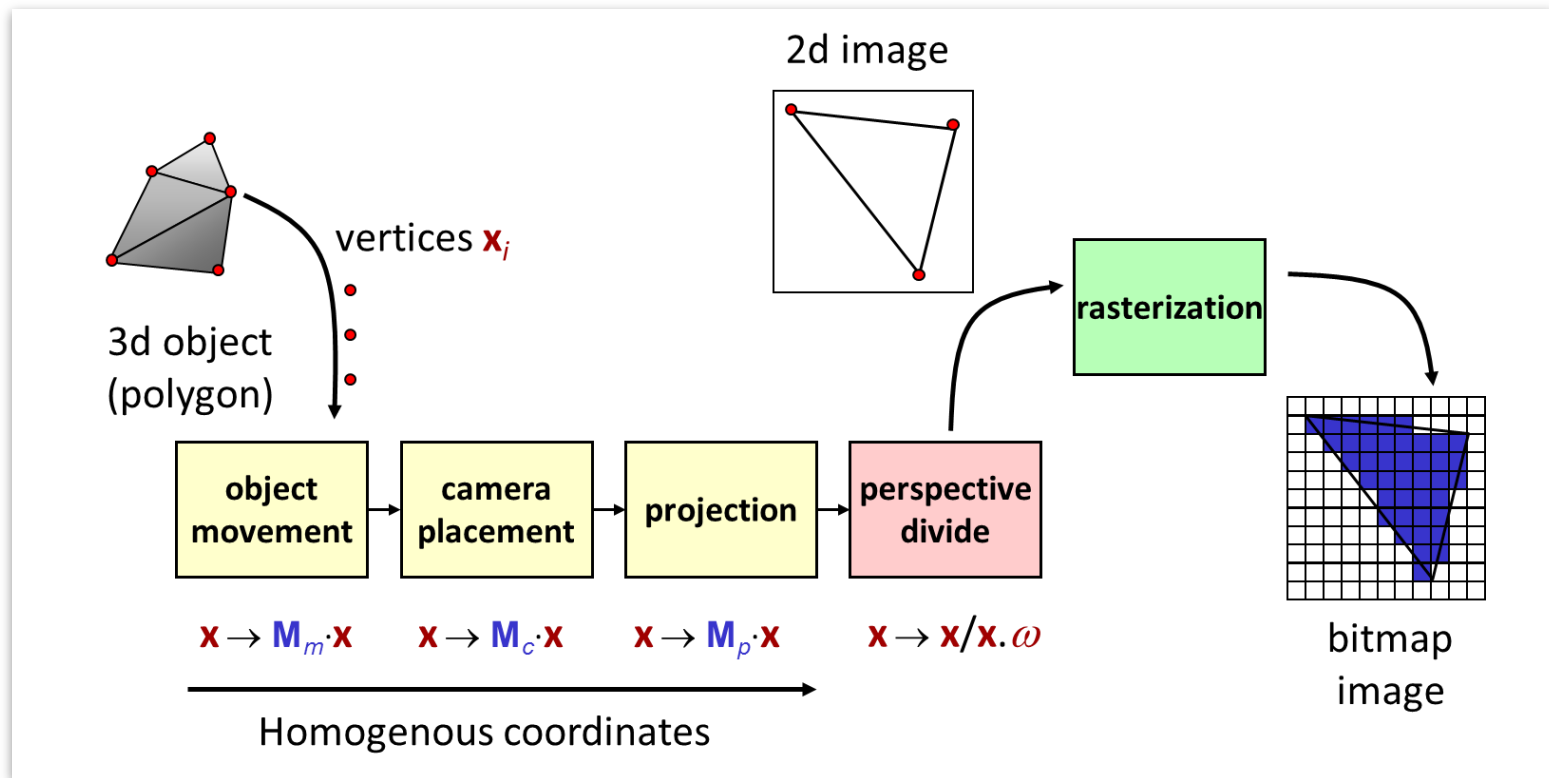
UU Graphics 2014



Shading Models

- Shading models & algorithms
- Normals / surface differentials
- Global effects: Shadows, radiosity, etc...

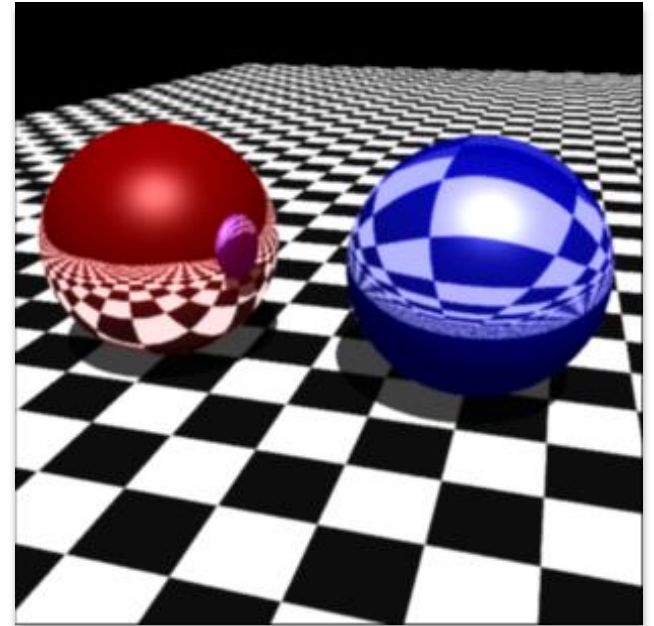
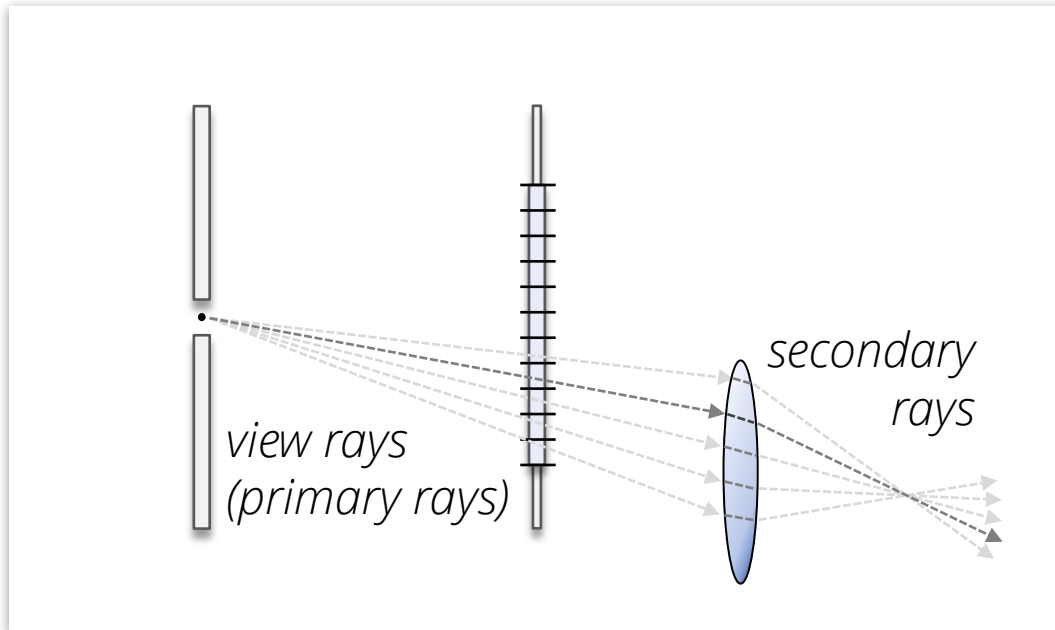
UU Graphics 2014



Rasterization Pipeline

- Draw triangles to screen
- Keep closest pixels, apply local shading

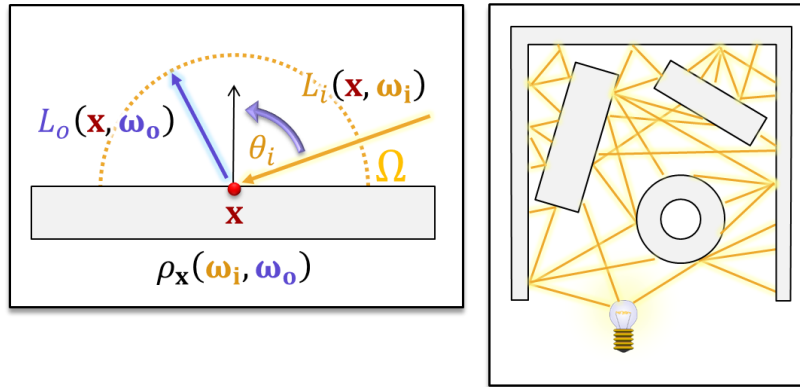
UU Graphics 2014



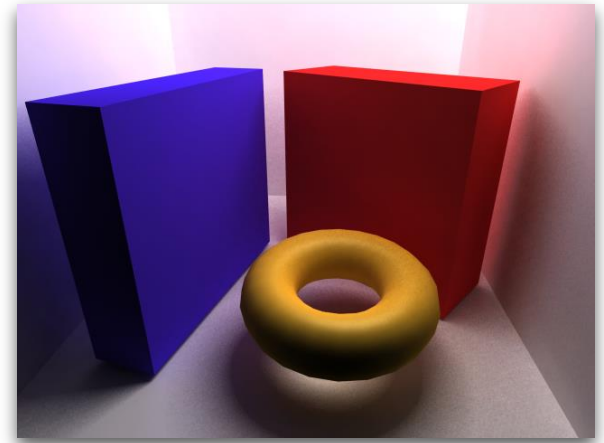
Raytracing Pipeline

- Follow view rays backwards from eye to object
- Includes reflection, transparency, shadows, etc...

UU Graphics 2014



$$L_o(\mathbf{x}, \omega_o) = \underbrace{E_o(\mathbf{x}, \omega_o)}_{\text{emission}} + \underbrace{\int_{\omega_i \in \Omega} [L_i(\mathbf{x}, \omega_i) \cdot \rho_x(\omega_i, \omega_o) \cdot \cos \theta_i] d\omega_i}_{\text{reflection}}$$

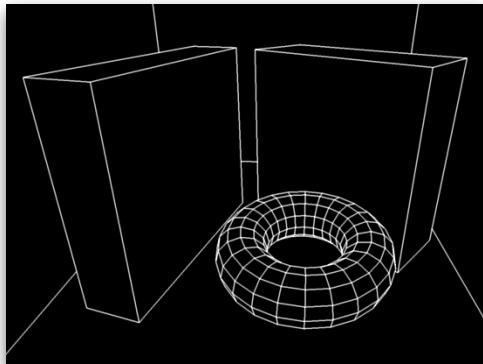


Global Illumination

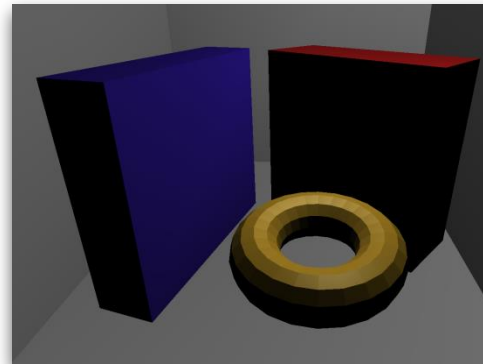
- Radiation Equilibrium:
Outgoing light = reflected light + emission
- Physically accurate simulation

3D Graphics Summary

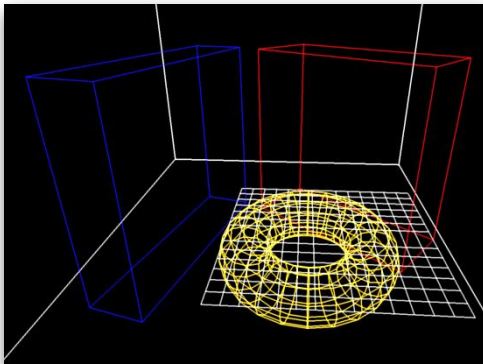
Summary



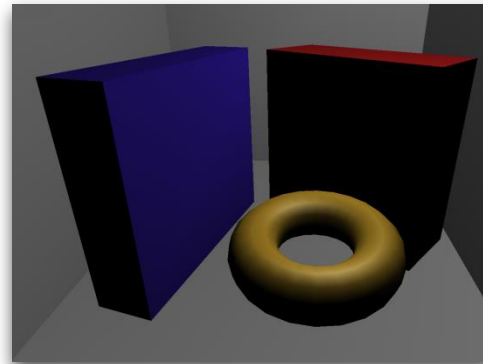
**geometric
modeling**



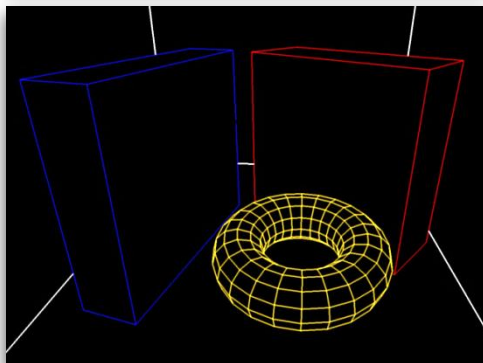
**local
illumination**



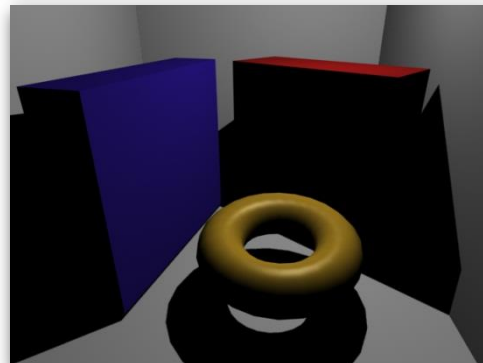
perspective



shading

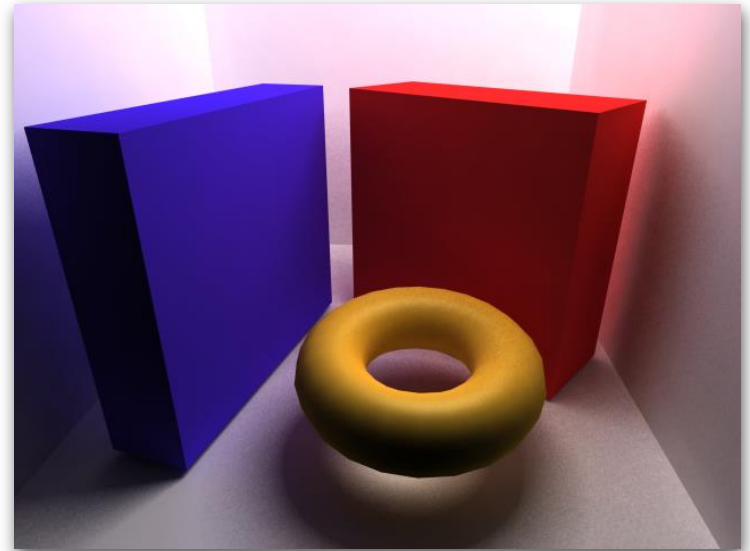
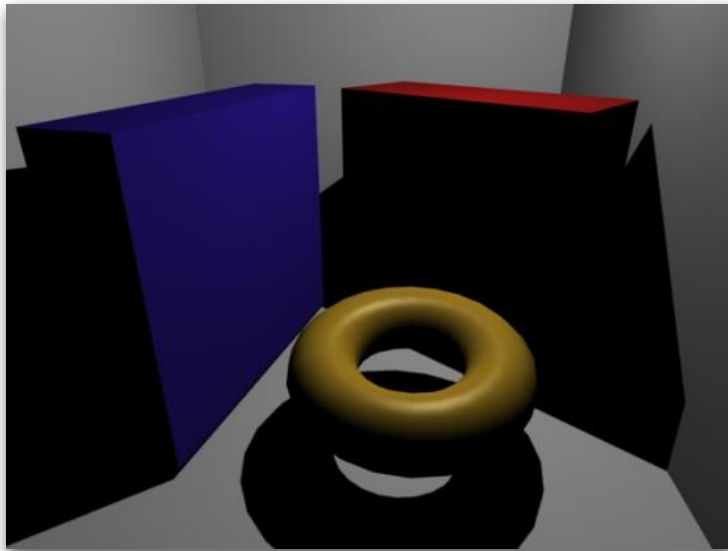


**visibility
calculation**



**shadows
(global)**

Advanced Graphics



Correct global radiance exchange:

- Physical simulation
- We will only take a brief look
- More in master course “Advanced Graphics” (MAGR)