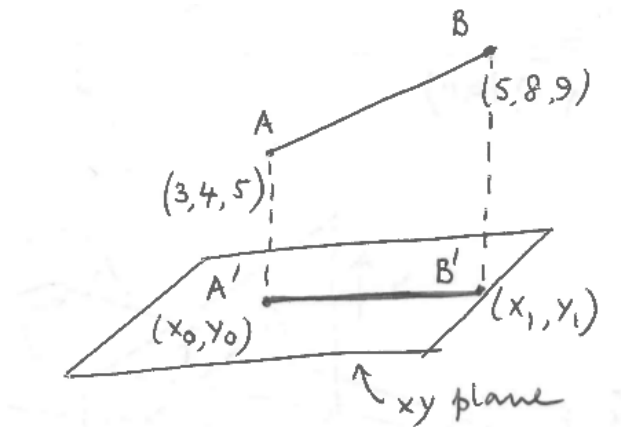


## Tutorial 3 – vectors, coordinate systems, primitives and projections in 3D

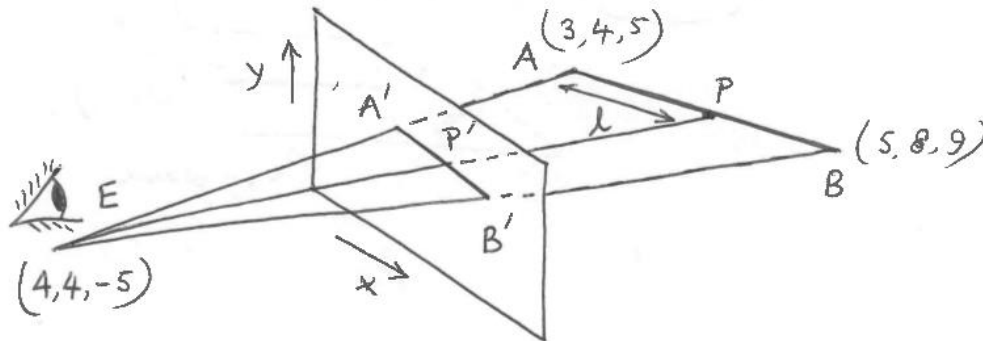
### Exercise 1.

Express the equation of a line on the xy-plane (screen)  $z = 0$  of a bar connecting  $(3,4,5)$  and  $(5,8,9)$  in *parametric form*. See figure. What are the values of  $(x_0, y_0)$  and  $(x_1, y_1)$ ?



### Exercise 2.

Consider the previous problem, but this time the bar is being looked at by the eye located at  $(4,4,-5)$ . See figure. What are the co-ordinates of  $A'$  and  $B'$  on the xy-plane (screen)  $z = 0$ ? Obtain the co-ordinates of the point  $P'$ , projection of the point P on the bar, where  $AP = l$ .



### Exercise 3.

Given: a sphere in  $\mathbb{R}^3$  with radius  $r = 3.14$  and center  $c = (3, 5, 1)$ .

- What is the parametric representation of the sphere?
- Using the parametric representation, calculate two opposing points on the sphere.

- c) What is the distance between the points calculated in b)?

### Eercise 4.

Given: a sphere in  $\mathbb{R}^3$ , with center  $c = (3,3,3)$  and a point on the surface of the sphere,  $p = (2,5,1)$ .

- Determine the implicit representation of the sphere.
- Calculate the distance of the sphere to point  $q = (4,9,-1)$  (note: this is not the distance to the centre of the sphere).
- Define a plane that has  $p$  as the only intersection point with the sphere (i.e., the tangent plane of the sphere at position  $p$ ).
- Define two perpendicular unit vectors in this plane, which are both also perpendicular to the normal of the sphere in  $p$ .

The vectors found in exercise 2, together with the normal of the sphere in  $p$  span up an orthonormal basis, which we call *tangent space*. We operate in this space e.g. for doing normal mapping.

### Eercise 5.

Given: a sphere in  $\mathbb{R}^3$ , with center  $c = (3,3,3)$  and radius 3.

- Find the range of parametric angles  $(\theta, \varphi)$  that represents the part of the sphere viewed from  $(3,3,3 - 3\sqrt{2})$ .
- For the same viewing position as in part (a) find the location of the point on the xy-plane (screen)  $z = 0$  corresponding to the projection of a point on the sphere given by the parametric angles  $(\theta, \varphi)$ . Follow the derivation provided in the class.