TUTORIAL 1 - SOLUTIONS VECTORS, COORDINATE SYSTEMS AND PROJECTIONS IN 2D

PART 1: THEORY

EXERCISE 1

We start with some theoretical questions.

- (a) Explain in your own words the difference between a scalar, a point and a vector, using an example in daily life.
- (b) What is a unit vector?
- (c) What is a 'basis' for a coordinate system?
- (d) What is the 'norm' of a vector?
- (e) Write down Pythagoras' theorem and explain it in your own words.

Solutions:

- (a) A scalar is just a number, e.g. '3'. A point is a set of numbers, defined on a coordinate system, e.g., 1m away from both the bottom and the left edges of the table. A vector is an entity that specifies a direction and magnitude, e.g. wind velocity (speed + direction) in De uithof.
- (b) A vector with length 1.
- (c) A basis is a set of vectors, in terms of which every vector in a coordinate system can be expressed as a linear combination.
- (d) The length of that vector.
- (e) Draw a triangle. Call the hypotenuse *c*, the base *a* and height *b*. Then $a^2 + b^2 = c^2$. In the context of vectors, the length of the vector \vec{c} can be calculated using this theorem.

PART 2: TWO-DIMENSIONAL VECTORS, INNER PRODUCTS

EXERCISE 2

Given two vectors $\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$. Use the regular 2D Cartesian coordinate system (the *x*, *y*-system you know from highschool).

- (a) Draw \vec{a} and \vec{b} .
- (b) Draw $\vec{a} + \vec{b}$.
- (c) Draw $\vec{a} \vec{b}$.
- (d) Draw $2(\vec{a} \vec{b})$.

Solutions:

- (a) *
- (b) *

(c) *

(d) *

EXERCISE 3

Given the following vectors:
$$\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
, $\vec{b} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$, $\vec{c} = \begin{bmatrix} 6 \\ 8 \end{bmatrix}$, $\vec{d} = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$, $\vec{e} = \begin{bmatrix} 1 \\ 6 \\ 2 \end{bmatrix}$, $\vec{f} = \begin{bmatrix} 0 \\ 2 \\ 4 \end{bmatrix}$, $\vec{g} = \begin{bmatrix} 5 \\ 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}$, $\vec{h} = \begin{bmatrix} 2 \\ 3 \\ 8 \\ 1 \\ 2 \end{bmatrix}$, $\vec{i} = \begin{bmatrix} 1 \\ 5 \\ 2 \\ 1 \\ 6 \end{bmatrix}$.

Calculate the following vector problems:

(a)
$$\vec{a} + \vec{b}$$
 (c) $\vec{a} + \vec{b} - \vec{c}$
(b) $\vec{g} - \vec{h}$ (d) $||\vec{a} - \vec{b}||^2$

Solutions:

(c)
$$\begin{bmatrix} -3\\ -3 \end{bmatrix}$$

(d) 2
(e) $(82^{5/2} - 67^{3/2}) \cdot \begin{bmatrix} 1\\ 4\\ -2 \end{bmatrix}$

(e) $(||\vec{h}||^5 - ||\vec{i}||^3) (\vec{e} - \vec{f})$

EXERCISE 4

Given: two vectors in \mathbb{R}^2 : $\vec{a} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$ and $\vec{c} = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$. Calculate the following: (a) $\vec{a} + \vec{b}$ (b) $\vec{b} - \vec{c}$ (c) $5\vec{b}$ (d) $||\vec{c}||^2$ (e) $||\vec{a}||$ Now in general form, set $\vec{a} = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix}$ and $\vec{c} = \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$. Redo exercises (a)-(e).

Solutions



(a) $\begin{bmatrix} a_1 + b_1 \\ a_2 + b_2 \end{bmatrix}$ (b) $\begin{bmatrix} b_1 - c_1 \\ b_2 - c_2 \end{bmatrix}$ (c) $\begin{bmatrix} 5b_1 \\ 5b_2 \end{bmatrix}$ (d) $c_1^2 + c_2^2$ (e) $\sqrt{a_1^2 + a_2^2}$

EXERCISE 5

Given: two vectors in \mathbb{R}^2 : $\vec{a} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$ and $\vec{c} = \begin{bmatrix} -3 \\ -1 \end{bmatrix}$. Calculate the following, and explain your answer geometrically.

- (a) The length of \vec{a}, \vec{b} and \vec{c} . For each of these calculations, draw an *xy*-plane and draw the triangles you implicitly use with Pythagoras' theorem.
- (b) $\vec{a} + \vec{c}$
- (c) Normalize \vec{a}, \vec{b} and \vec{c} .

Solutions:

- (a) For the calculation of $||\vec{a}||$, you implicitly use $||\vec{a}|| = \sqrt{a_x^2 + a_y^2}$, so use the triangles that can be made by drawing the *x* and *y* coordinates of the points. This gives $||\vec{a}|| = \sqrt{10}$, $||\vec{b}|| = \sqrt{10}$ and $||\vec{c}|| = \sqrt{10}$.
- (b) $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$. This cannot be drawn because it does not have a length that is larger than 0.

(c)
$$\hat{a} = \frac{1}{||\vec{a}||} \vec{a} = \begin{bmatrix} 3/\sqrt{10} \\ 1/\sqrt{10} \end{bmatrix}, \hat{b} = \frac{1}{||\vec{b}||} \vec{b} = \begin{bmatrix} -1/\sqrt{10} \\ 3/\sqrt{10} \end{bmatrix}, \hat{c} = \frac{1}{||\vec{c}||} \vec{c} = \begin{bmatrix} -3/\sqrt{10} \\ -1/\sqrt{10} \end{bmatrix}$$

PART 3: NORMS, UNIT VECTORS AND ANGLES

EXERCISE 6

Draw the following vectors, then calculate the norm of each of them and write down the corresponding unit vectors:



EXERCISE 7

Given: three vectors in \mathbb{R}^2 : $\vec{a} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $\vec{c} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$.

- (a) Draw the vectors on a sheet of paper (using a regular 2D-Cartesian x,y-grid)
- (b) Compute the sum of \vec{a} and \vec{b} . Draw the result.
- (c) Scale vector \vec{a} by the factors 1, 2, -1 and $\sqrt{2}$. Draw the results.
- (d) Determine $\vec{b} \vec{c}$ graphically, using the rule from the lecture: first, join the starting points of *b* and *c*, then draw an arrow from the tip \vec{c} to the tip of \vec{b} , which gives you the result.
- (e) Compute and draw $2(\vec{a} + \vec{c})$ and $2\vec{a} + 2\vec{c}$. Visualize how this gives the same result (this is called the distributive rule).
- (f) Build a linear combination \vec{v} of the vectors \vec{a} , \vec{b} and \vec{c} . That is, $\vec{v} = \lambda_1 \vec{a} + \lambda_2 \vec{b} + \lambda_3 \vec{c}$.

Solutions:

- (a) *
- (b) $\vec{a} + \vec{b} = \begin{bmatrix} 2\\5 \end{bmatrix}$
- (c) Scaling with a scalar λ means $\lambda \cdot \vec{a} = \begin{bmatrix} \lambda \\ 3\lambda \end{bmatrix}$. Drawing all these scaled vectors results in a series of parallel vectors.
- (d) $\vec{b} \vec{c} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$. Your drawn vectors should point towards the upper right.
- (e) Computing both gives $\begin{bmatrix} 2\\ 8 \end{bmatrix}$. They are equal.
- (f) Take $\lambda_1 = \lambda_2 = \lambda_3 = 1$, then $\vec{v} = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$. You can check this geometrically.