TUTORIAL 3 - SOLUTIONS VECTORS, PRIMITIVES AND PROJECTIONS IN **3D**

PART 1: THEORY

EXERCISE 1

We start with some theoretical questions.

- (a) Explain in your own words the geometric interpretation of a cross product of two vectors (in 3D).
- (b) Given a normal \hat{n} of a plane, what is the general equation for the plane?
- (c) Is the dot product a vector or a scalar? And what about the cross product?
- (d) Write down the formula for the cross-product and for the inner product of vectors $\vec{u} = \begin{bmatrix} u_x \\ u_y \\ u_z \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} v_x \\ v_y \\ v_z \end{bmatrix}$ in terms of their

elements and the angle θ between them.

(e) Given vectors $\vec{a} = \begin{bmatrix} \vec{0} \\ 0 \end{bmatrix}$ and $\vec{b} = \begin{bmatrix} \vec{0} \\ 0 \end{bmatrix}$, without any calculation, which direction do you think $\vec{c} = \vec{a} \times \vec{b}$ heads? Visualize this using

the right-hand-rule (for example, say that the x direction is to your right, the y in front of you, and z upward). Now check which direction $\vec{d} = \vec{b} \times \vec{a}$ points to.

(f) Write the formula of a circle and of an ellipse. Show that the ellipse is a more general form of a circle.

Solutions:

- (a) the cross product \vec{w} of two vectors \vec{u} and \vec{v} is a vector that is perpendicular to both \vec{u} and \vec{v} and has magnitude $||\vec{w}|| =$ $\|\vec{u}\|\|\vec{v}\|\sin\theta$
- (b) $(x x_0)n_x + (y y_0)n_y + (z z_0)n_z = 0$, where (x_0, y_0, z_0) is a point on the plane.
- (c) The dot product is indeed a scalar, while cross product is a vector

(d)
$$\vec{w} = \vec{u} \times \vec{v} = \begin{bmatrix} u_y v_z - u_z v_y \\ u_z v_x - u_x v_z \\ u_z v_z + u_z v_z \end{bmatrix}$$
 and $||\vec{w}|| = ||\vec{u}|| ||\vec{v}|| \sin \theta$

- $\begin{bmatrix} u_x v_y u_y v_x \end{bmatrix}$
- (e) \vec{c} points towards your back (negative y), \vec{d} points towards your front (positive y). (f) Circle: $(x x_c)^2 + (y y_c)^2 = r^2$, with (x_c, y_c) the center of the circle and *r* its radius.
- ellipse $\frac{(x-x_c)^2}{a^2} + \frac{(y-y_c)^2}{b^2} = 1$, with (x_c, y_c) the center of the ellipse, *a* and *b* are the lengths of the two semi-axes. If a = b:

$$\frac{(x-x_c)^2}{a^2} + \frac{(y-y_c)^2}{a^2} = \frac{(x-x_c)^2 + (y-y_c)^2}{a^2} = 1$$
$$(x-x_c)^2 + (y-y_c)^2 = a^2$$

which is a circle of radius a.

PART 2: CIRCLES AND ELLIPSES

EXERCISE 2

Given a circle in \mathbb{R}^2 with radius r = 4 and center c = (5, 1):

- (a) What is the implicit representation of the circle?
- (b) What is the parametric representation of the circle? (i.e. with the circular co-ordinate system)
- (c) Shooting a ray from the origin in the direction $\vec{v} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$, where does it intersect the circle?
- (d) Represent your answer of (c) in the parametric co-ordinate for the circle.

Solutions:

- (a) $(x-5)^2 + (y-1)^2 = 16$
- (b) $x = 5 + 4\cos\theta$, $y = 1 + 4\sin\theta$
- (c) Writing the ray in a parametric form:

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} + l \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow x = l, \quad y = l$$

by placing this result inside the implicit representation of the circle we get:

$$(l-5)^2 + (l-1)^2 = 16 \Rightarrow 2l^2 - 12l + 10 = 0 \Rightarrow l^2 - 6l + 5 = 0$$

this equation has two solutions: $P_1 = (5,5)$ and $P_2 = (1,1)$.

(d) For *P*₁:

For P₂:

$$\begin{bmatrix} x_1 \\ y_1 \end{bmatrix} = \begin{bmatrix} 5+4\cos\theta_1 \\ 1+4\sin\theta_1 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \end{bmatrix} \Rightarrow \begin{bmatrix} \cos\theta_1 \\ \sin\theta_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow \theta_1 = \pi/2$$
$$\begin{bmatrix} x_2 \\ y_2 \end{bmatrix} = \begin{bmatrix} 5+4\cos\theta_2 \\ 1+4\sin\theta_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \Rightarrow \begin{bmatrix} \cos\theta_2 \\ \sin\theta_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix} \Rightarrow \theta_2 = \pi$$

EXERCISE 3

Given a circle C_1 in \mathbb{R}^2 with radius $r_1 = 5$ and center $c_2 = (4, 6)$:

- (a) What is the implicit representation of the circle?
- (b) What is the parametric representation of the cycle?
- (c) A ray is shot from (0,7) along the vector $\bar{v} = \begin{pmatrix} 1 \\ 1/3 \end{pmatrix}$. Determine the points P_1 and P_2 where the ray passes through the circle.
- (d) What is the length of the segment P that connects P_1 and P_2 ?
- (e) What is the length of the parallel projection of P on the *x*-axis?

Solutions:

- (a) $(x-4)^2 + (y-6)^2 = 25$.
- (b) $x = 4 + 5\cos\theta$, $y = 6 + 5\sin\theta$.
- (c) We can write the ray as y = 1/3x + 7. We can insert this inside the implicit representation of C_1 :

$$25 = (x-4)^2 + (x/3+7-6)^2 = (x-4)^2 + (1/3x+1)^2 = \frac{10}{9}x^2 - \frac{22}{3}x + 17$$
$$0 = \frac{10}{9}x^2 - \frac{22}{3}x - 8 \implies x_{1,2} = \frac{33}{10} \pm \frac{3\sqrt{201}}{10}$$

and therefore:

$$P_1 = \left(\frac{33}{10} + \frac{3\sqrt{201}}{10}, \frac{81 + \sqrt{201}}{10}\right) \quad P_2 = \left(\frac{33}{10} - \frac{3\sqrt{201}}{10}, \frac{81 - \sqrt{201}}{10}\right)$$

(d)

$$l = |P_2 - P_1| = \sqrt{\left(\frac{6\sqrt{201}}{10}\right)^2 + \left(\frac{2\sqrt{201}}{10}\right)^2} = \sqrt{\frac{(36+4)\,201}{100}} = 2\sqrt{\frac{2010}{100}} = \frac{\sqrt{2010}}{5}.$$

(e) The length of the projection *t* can be easily found from \hat{v} :

$$t = l v_x = \frac{l}{\sqrt{10/9}} = \frac{3}{5}\sqrt{201}.$$

EXERCISE 4

Given a circle C_2 in \mathbb{R}^2 with radius r = 2 and center c = (3, 2):

- (a) What is the implicit representation of the circle?
- (b) What is the parametric representation of the circle? (i.e. with the circular co-ordinate system)
- (c) Find the points of intersection P_1 and P_2 between this circle and C_1 , the circle of Exercise 3. This was not shown in class, but think about it!
- (d) What is the length of the segment P that connects P_1 and P_2 ?
- (e) What is the length of the projection of P on the *y*-axis?

Solutions:

- (a) $(x-3)^2 + (y-2)^2 = 4$
- (b) $x = 3 + 2\cos\theta$ $y = 2 + 2\sin\theta$
- (c) Solving the system of equations:

$$\begin{cases} (x-3)^2 + (y-2)^2 = 4\\ (x-4)^2 + (y-6)^2 = 25 \end{cases} \Rightarrow 2x + 8y = 18 \Rightarrow x = 9 - 4y$$

We put this result in C_2 and we solve the second degree equation:

$$(9-4y-3)^2 + (y-2)^2 = 4 \implies 17y^2 - 52y + 36 = 0 \implies y_{1,2} = \begin{cases} 2\\ 18/17 \end{cases}$$

The two points are $P_1 = (1, 2)$ and $P_2 = (81/17, 18/17)$.

(d)

$$l = \sqrt{\left(\frac{81}{17} - 1\right)^2 + \left(\frac{18}{17} - 2\right)^2} = \sqrt{\frac{4096}{289} + \frac{256}{289}} = \sqrt{\frac{4352}{289}} = \frac{16}{\sqrt{17}}.$$

(e) We already have the equation of the line connecting the two points (x + 4y - 9 = 0), which can be rewriten in a parametric form by considering two points on it. We will use two simple points: (0, 9/4) and (1, 2):

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 9/4 \end{bmatrix} + t\hat{v} = \begin{bmatrix} 0 \\ 9/4 \end{bmatrix} + \frac{t}{\sqrt{17/16}} \begin{bmatrix} 1 \\ -1/4 \end{bmatrix}$$

And then:

$$l_y = |\hat{v} \cdot \hat{y}| \, l = \frac{\sqrt{16}}{4\sqrt{17}} \frac{16}{\sqrt{17}} = \frac{16}{17}.$$

EXERCISE 5

Given the equation

$$x^2 + y^2 - 4y - 5 = 0$$

- (a) Is it a circle or an ellipse? Why?
- (b) Write the corresponding implicit form.
- (c) Where is the center? If it's a circle, what is the radius? If it's an ellipse, what are the lengths of its semi-axes?

Solutions:

- (a) It is a circle; see below.
- (b) Let us rearrange the terms and
 - as $x^2 + y^2 - 4y = 5$ $x^2 + (y - 2)^2 = 9$
- (c) It is a circle with center (0, 2) and radius 3.

EXERCISE 6

Given a circle C_3 with center c = (1,3) and radius 2.

- (a) Write down the implicit and parametric representations of the circle.
- (b) What's the maximum radius that a circle C_4 centered on the origin can have without intersecating C_3 ?
- (c) If C_4 (still centered on the origin) passes through the center of C_3 , what is its radius? Write down its implicit representation.
- (d) Compute the coordinates of the points of intersection between C_3 and C_4 .

Solutions:

(a)
$$(x-1)^2 + (y-3)^2 = 4$$
.
 $x = 1 + 2\cos\theta, y = 3 + 2\sin\theta$.

- (b) We could write down the equation of C_4 and compute the intersection, determining for which value of r we have a single point of intersection and take that as our maximus radius. Or we could be smart about it: the distance between the center of C_3 and the origin is $\sqrt{10}$, its radius is 2, so the distance between the origin and C_3 is $\sqrt{10} 2$: this will be our maximum radius for C_4 .
- (c) As we have seen before, $\sqrt{10}$. $x^2 + y^2 = 10$.
- (d) Solving the system:

$$\begin{cases} x^2 + y^2 = 10 \\ (x-1)^2 + (y-3)^2 = 4 \end{cases} \Rightarrow x + 3y = 8$$

By placing this inside the equation of C_4 we get the two points of intersection: (-1,3) and (13/5,9/5).

PART 3: DOT AND CROSS PRODUCTS IN 3D

EXERCISE 7

Given coordinates A = (1, 2, 3) and B = (4, 5, 6).

- (a) Calculate the equation for the line *l* going through *A* and *B*.
- (b) Obtain a unit normal vector \hat{n} to this line. Check your answer by explicitly calculating the distance of line *l* to point *B*.
- (c) Calculate the distance of line *l* to point C = (7, 8, 9).

Solutions:

(a) Direction vector $\vec{v} = \begin{bmatrix} 4\\5\\6 \end{bmatrix} - \begin{bmatrix} 1\\2\\3 \end{bmatrix} = \begin{bmatrix} 3\\3\\3 \end{bmatrix}$, so parametric form of line $l: \frac{x-1}{3} = \frac{y-2}{3} = \frac{z-3}{3}$

(b) The unit normal vector is perpendicular to \vec{v} , for example $\hat{n} = \frac{1}{\sqrt{6}} \begin{bmatrix} 1\\ 1\\ -2 \end{bmatrix}$ (check that $\hat{n} \cdot \vec{v} = 0$. Now shoot a ray from *B* to *l* and

from A along l and see where they intersect:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x_b \\ y_b \\ z_b \end{bmatrix} + t\hat{n}_b$$
(1)
$$\begin{bmatrix} x \\ z \end{bmatrix} \begin{bmatrix} x_a \end{bmatrix}$$

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x_a \\ y_a \\ z_a \end{bmatrix} + k\hat{v}$$
(2)

where \hat{n}_b is the normal vector from the line through *B*. Now we need to solve this for *t* and *k*. For arbitrary \hat{n}_b it is already visible that this only has a solution for t = 0, so distance between *B* and the line is indeed 0. (c) We see that *C* already holds the line equation $\frac{x-1}{3} = \frac{y-2}{3} = \frac{z-3}{3}$, so *C* is on the line: distance 0.

EXERCISE 8

Given are the following vectors: $\vec{a} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$, $\vec{b} = \begin{bmatrix} 3 \\ 4 \\ 5 \end{bmatrix}$, $\vec{c} = \begin{bmatrix} 1 \\ 3 \\ 1 \end{bmatrix}$, $\vec{d} = \begin{bmatrix} 0 \\ 2 \\ 2 \end{bmatrix}$, $\vec{e} = \begin{bmatrix} 5 \\ 3 \\ 1 \end{bmatrix}$, $\vec{f} = \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix}$, $\vec{g} = \begin{bmatrix} 6 \\ 2 \\ 4 \end{bmatrix}$. Calculate and draw the following vectors in a 3D Cartesian coordinate system:

 $\begin{array}{ll} \text{(e)} & \vec{d} - \vec{e} + \vec{a} \times \vec{f} \\ \text{(f)} & (\vec{a} \times \vec{b}) \times (\vec{c} \times \vec{d}) \\ \text{(g)} & ((\vec{g} \times \vec{a}) \cdot (\vec{d} \times \vec{e}))\vec{c} \\ \text{(h)} & (\vec{a} \times \vec{a} + \vec{a} \times \vec{a}) \cdot ||\vec{a}||^2 \end{array}$ (a) $\vec{a} + \vec{b}$ (i) $(\vec{b} \times \vec{c}) + \vec{d} - \vec{a}$ (b) $\vec{c} + \vec{d}$ (c) $\vec{f} - \vec{g}$ (d) $\vec{e} \times \vec{a}$ (i) $(5\vec{a}\times\vec{a})\times\vec{a}$

Solutions:



EXERCISE 9

Given vectors $\vec{u} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

- (a) Draw these vectors.
- (b) Calculate and draw the dot product of these vectors. What is the angle between vectors \vec{u} and \vec{v} ?
- (c) Calculate and draw the cross product of these vectors. What is the angle between the newly attained vector and \vec{u} ?

Solutions:

- (a) *
- (b) $\vec{u} \cdot \vec{v} = 1 + 0 + 6 = 7$. This is a scalar and does not have a direction, unlike a vector. Therefore, we do not draw it here. You can, however, relate the magnitude of this scalar to the angle between \vec{u} and \vec{v} via $||\vec{w}|| = ||\vec{u}|| ||\vec{v}|| \cos\theta$, meaning $\theta =$ $\operatorname{arccos}(\frac{7}{\sqrt{5}\sqrt{11}}) \approx 19.3^{\circ}.$
- (c) $\vec{u} \times \vec{v} =$. The angle between this vector and \vec{u} is 90°, by definition (cross product is perpendicular to the two vectors). In

your drawings, it should be visible that the cross product is perpendicular to \vec{u} and \vec{v} .

PART 4: PLANES AND NORMALS IN 3D

EXERCISE 10

Given coordinates A = (0, 2, 0), B = (1, 3, 4) and C = (-2, -2, 3).

- (a) Determine the normalized vector going from A in the direction of B. Call this \hat{u} .
- (b) Determine the normalized vector going from A in the direction of C. Call this \hat{v} .

- (c) Determine a normal vector to the plane derived through *A*, *B* and *C*.
- (d) Determine the equation of this plane in the implicit form.
- (e) Determine the equation of this plane in the parametric form.

Solutions:

(a)
$$\hat{u} = \frac{1}{\sqrt{18}} \begin{bmatrix} 1\\ 1\\ 4 \end{bmatrix}$$

(b) $\hat{v} = \frac{1}{\sqrt{29}} \begin{bmatrix} -2\\ -4\\ 3 \end{bmatrix}$

- (c) The cross product of $\hat{u} \times \hat{v}$ provides us with the normal to the sought plane. $\hat{u} \times \hat{v} = \frac{1}{\sqrt{522}} \begin{bmatrix} 19\\ -11\\ -2 \end{bmatrix}$.
- (d) Then the implicit form of the plane is 19x 11y 2z + 22 = 0 (obtained by filling in the coordinates of *A*). (e) The parametric form is $\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix} + \frac{\alpha}{\sqrt{18}} \begin{bmatrix} 1 \\ 1 \\ 4 \end{bmatrix} + \frac{\beta}{\sqrt{29}} \begin{bmatrix} -2 \\ -4 \\ 3 \end{bmatrix}$.