

```

ics
& (depth < MAXDEPTH) {
    if (nt < 0) {
        nt = inside ? 1 + 1.2f * exp(-0.5f * ddh * ddh) : 0;
        nt = nt / nc, ddh = ddh * nc;
        nnt = nnt * nt, nnt2t = 1.0f - nnt * nnt;
        D, N );
    }
    if (nt > 0) {
        at a = nt - nc, b = nt + nc;
        at Tr = 1 - (R0 + (1 - R0) * nnt);
        Tr) R = (D * nnt - N * (ddh < 0));
        E * diffuse;
        = true;
        -
        refl + refr)) && (depth < MAXDEPTH) {
            D, N );
            refl * E * diffuse;
            = true;
        }
    }
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following Small's
    if;
    radiance = SampleLight( &rand, I, &L, &lightDir );
    e.x + radiance.y + radiance.z) > 0) && (dot( N, L ) > 0) {
        w = true;
        at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
        at3 factor = diffuse * INVPI;
        at weight = Mis2( directPdf, brdfPdf );
        at cosThetaOut = dot( N, L );
        E * ((weight * cosThetaOut) / directPdf) * (radiance.x + radiance.y + radiance.z);
    }
    random walk - done properly, closely following Small's
    vive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}

```



INFOGR – Computer Graphics

Jacco Bikker & Debabrata Panja - April-July 2019

Lecture 9: “OpenGL”

Welcome!

```
ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0.25)
    {
        nt = nt / nc; ddn = ddn * 0.5;
        cos2t = 1.0f - nnt * nnt;
        D, N );
    }
    at a = nt - nc, b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) * ddn);
    Tr) R = (D * nnt - N * (ddn * nnt));
    E * diffuse;
    = true;
    defl + refr)) && (depth < MAXDEPTH)
    {
        D, N );
        refl * E * diffuse;
        = true;
    }
    MAXDEPTH)
    survive =
    estimati
    df;
    radiance
    e.x + rad
    w = true;
    at brdfPd
    at3 facto
    at weight
    at cosThe
    E * ((we
    random wal
    vive)
    ;
    at3 brdf
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
```



Today's Agenda:

- Introduction
- OpenGL
- GPU Model
- Upcoming
- Assignment P3



Introduction

Topics covered so far:

Basics:

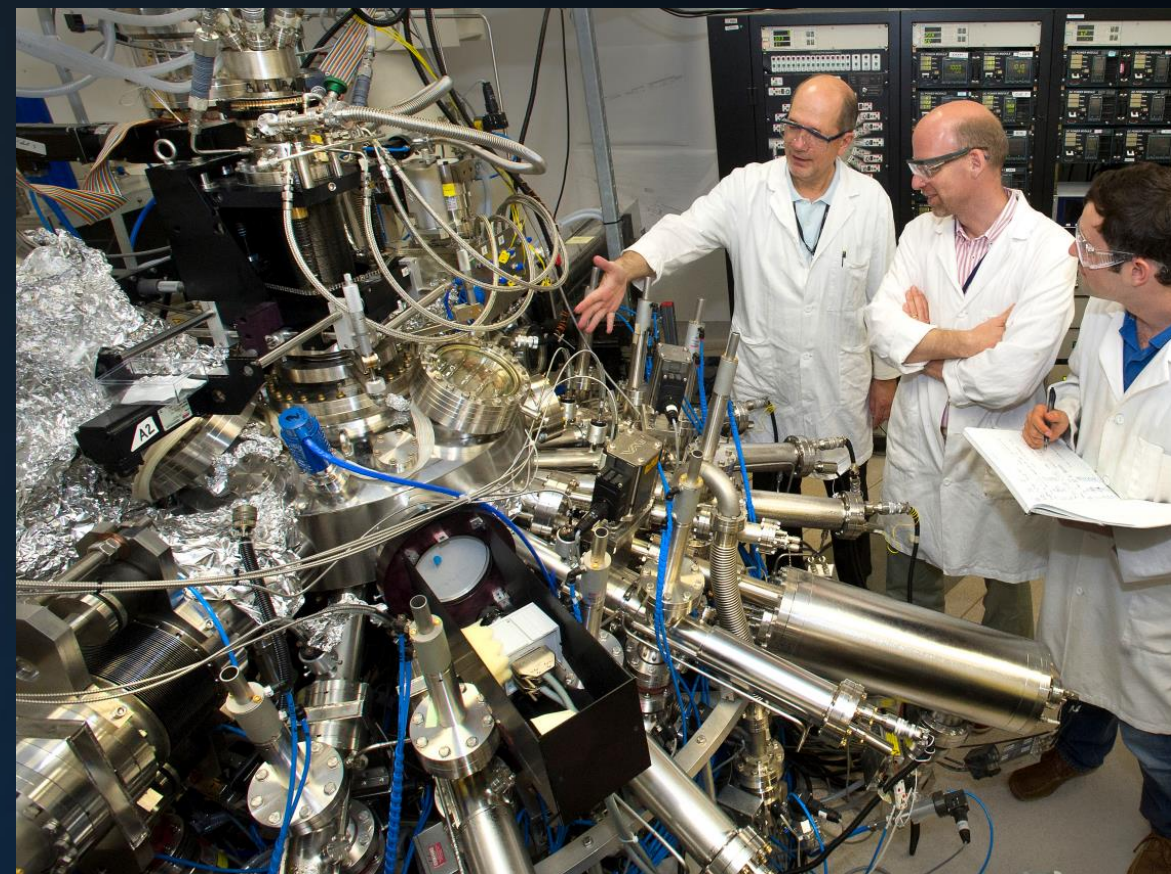
- Rasters
- Vectors
- Color representation

Ray tracing:

- Light transport
- Camera setup
- Textures

Shading:

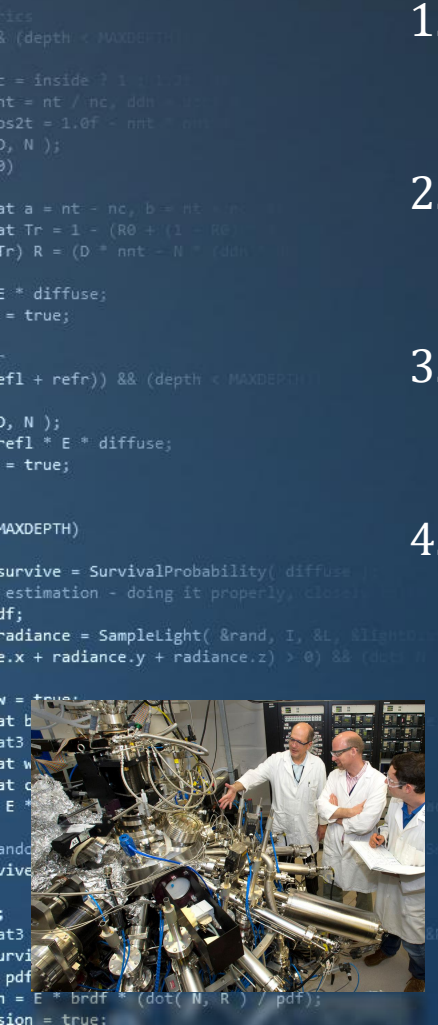
- $N \cdot L$
- Distance attenuation
- Pure specular



Introduction

Rendering – Functional overview

1. Transform:
translating / rotating / scaling meshes
2. Project:
calculating 2D screen positions
3. Rasterize:
determining affected pixels
4. Shade:
calculate color per affected pixel



Animation, culling,
tessellation, ...

meshes

Transform

vertices

Project

vertices

Rasterize

fragment positions

Shade

pixels

Postprocessing



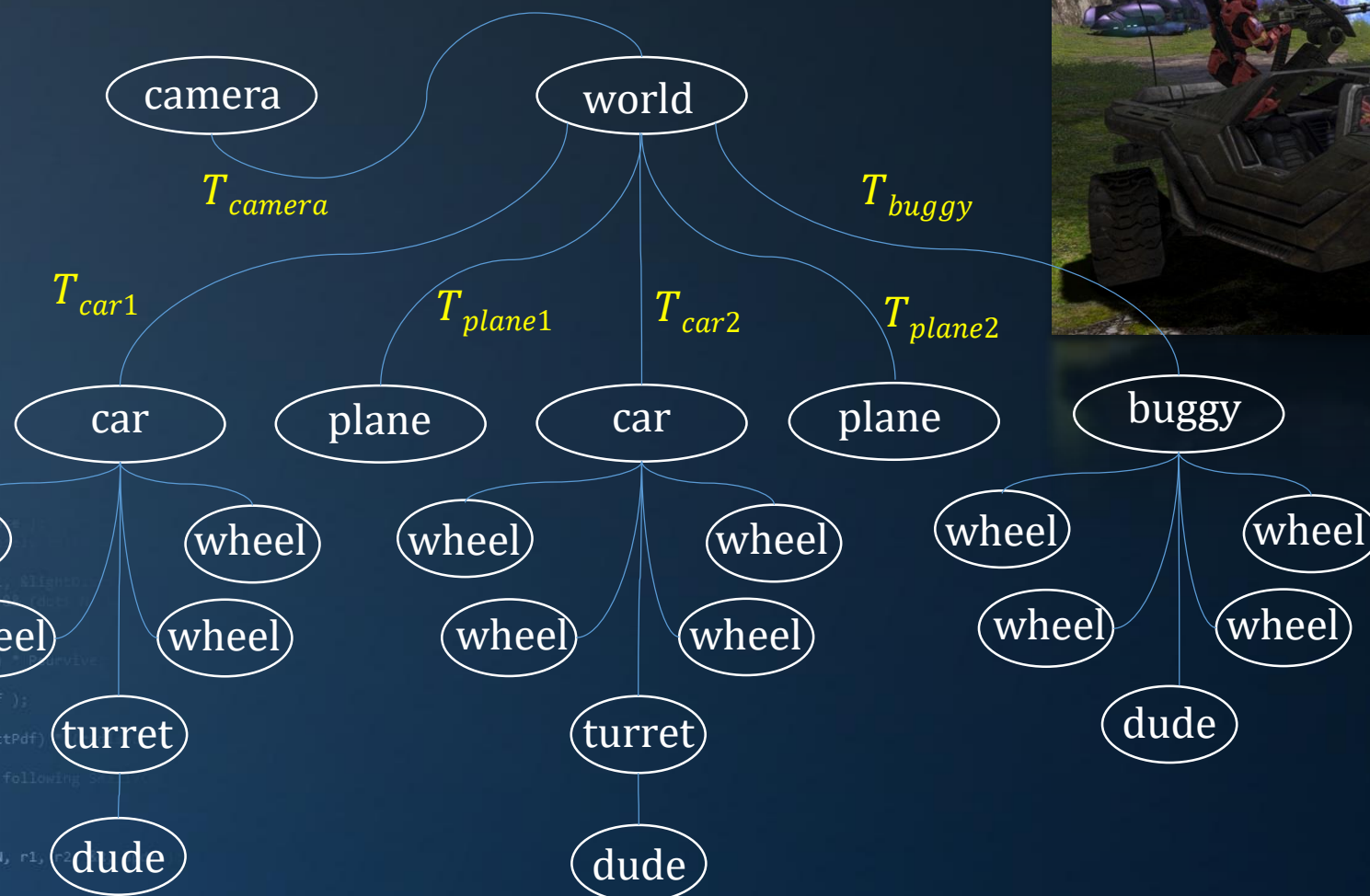


Introduction

Rendering – Data Overview

```
ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
    at a = nt - nc, b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) *
    Tr) R = (D * nnt - N * (ddn
    E * diffuse;
    = true;
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diff
    estimation - doing i
    if;
    radiance = SampleLight( &rand, L, &L, Alignm
    e.x + radiance.y + radiance.z)
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N );
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf)
    random walk - done properly, closely following
    ve)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2,
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;

```



Introduction

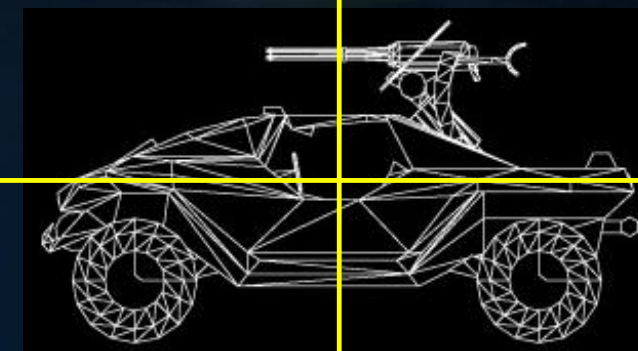
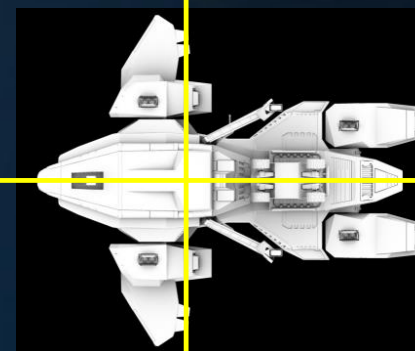
Rendering – Data Overview

Objects are organized in a hierarchy: the *scenegraph*.

In this hierarchy, objects have translations and orientations relative to their parent node.

Relative translations and orientations are specified using matrices.

Mesh vertices are defined in a coordinate system known as *object space*.



Introduction

Writing a 3D Engine
(before the summer holiday)

3D engine raison d'être: *it's a visualizer for a scene graph.*

We typically build 3D engines for GPUs. A GPU is not a CPU.

For real-time graphics, we use rasterization, rather than ray tracing.

We still want realistic images.

- Math: matrices
- OpenGL
- GPU architecture
- Shading
- Post processing
- Visibility



Today's Agenda:

- Introduction
- OpenGL
- GPU Model
- Upcoming
- Assignment P3



Introduction

A Brief History of OpenGL

OpenGL: based on Silicon Graphics IRIS GL (~1985).

1992: OpenGL Architecture Review Board (ARB)

1995: Direct3D

1997: Fahrenheit (☠️ 1999)

Purpose: generic API for 2D and 3D graphics.

- Platform-independent
- Language-agnostic
- Designed for hardware acceleration



```
ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0.25)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
    else
    {
        at a = nt - nc, b = nt + nc;
        at Tr = 1 - (R0 + (1 - R0) * ddn);
        Tr) R = (D * nnt - N * (ddn * cos2t));
    }
    E * diffuse;
    = true;
}
refl + refr)) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;
}
MAXDEPTH)
survive = SurvivalProbability( diffu
estimation - doing it properly, cl
df;
radiance = SampleLight( &rand, I, &L
e.x + radiance.y + radiance.z) > 0);
w = true;
at brdfPdf = EvaluateDiffuse( L, N );
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / direc
random walk - done properly, closely
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```



Introduction

A Brief History of OpenGL

OpenGL: based on Silicon Graphics IRIS GL (~1985).

1992: OpenGL Architecture Review Board (ARB)

1995: Direct3D

1997: Fahrenheit (☠️ 1999)

1997: Glide / 3Dfx

2006: ARB → Khronos Group



Introduction

A Brief History of OpenGL

OpenGL 1.0 – 1992 (initial version)

1995: Windows 95

OpenGL 1.1 – 1997 - Textures

1996: Direct3D 2.0 & 3.0

1997: GLQuake

OpenGL 1.2 – 1998 - 3D textures

1998: Direct3D 6.0

OpenGL 1.3 – 2001- Environment maps, texture compression

1999: Direct3D 7.0: HW T&L, vertex buffers in device mem

OpenGL 1.4 – 2002 - Blending, stencils, fog

OpenGL 1.5 – 2003 - Vertex buffers



Introduction

A Brief History of OpenGL

OpenGL 2.0 – 2004 - Shaders

2001: GeForce 3,
vertex/pixel shaders



OpenGL 3.0 – 2008 – Updated shaders, framebuffers, floating point textures

OpenGL 3.1 – 2009 – Instanced rendering

OpenGL 3.2 – 2009 – Geometry shaders

2009: GeForce 8,
geometry shaders

OpenGL 3.3 – 2010 – Support Direct3D 10 hardware

OpenGL 4.0 – 2010 – Direct3D 11 hardware support



Introduction

A Brief History of OpenGL

OpenGL 4.1 – 2010

OpenGL 4.2 – 2011 – Support for atomic counters in shaders

OpenGL 4.3 – 2012 – Compute shaders

OpenGL 4.4 – 2013

OpenGL 4.5 – 2014

Vulkan – 2016

Apple Metal - 2014

AMD Mantle - 2015

MS DirectX 12 - 2016



Vulkan:

- “OpenGL next”
- Support for multi-core CPUs
- Derived from AMDs Mantle
- Low-level GPU control
- Cross-platform



Introduction



PSGL
PlayStation Graphics Library

Microsoft®
DirectX[®] 11



Introduction

A Brief History of OpenGL

Digest:

- Open standard graphics API, governed by large body of companies
- Initially slow to follow hardware advances
- After transfer to Khronos group: closely following hardware
- Currently more or less ‘the standard’, despite DirectX / Metal
- Moving towards ‘close to the metal’ → Vulkan.



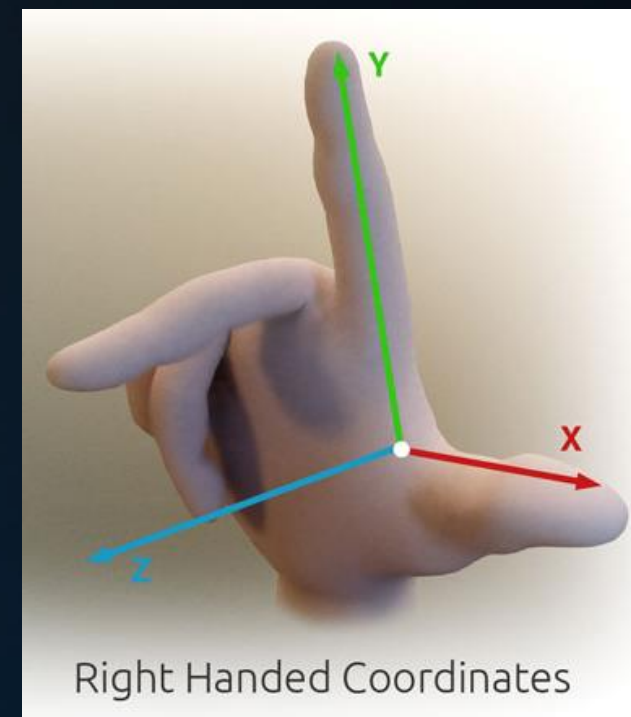
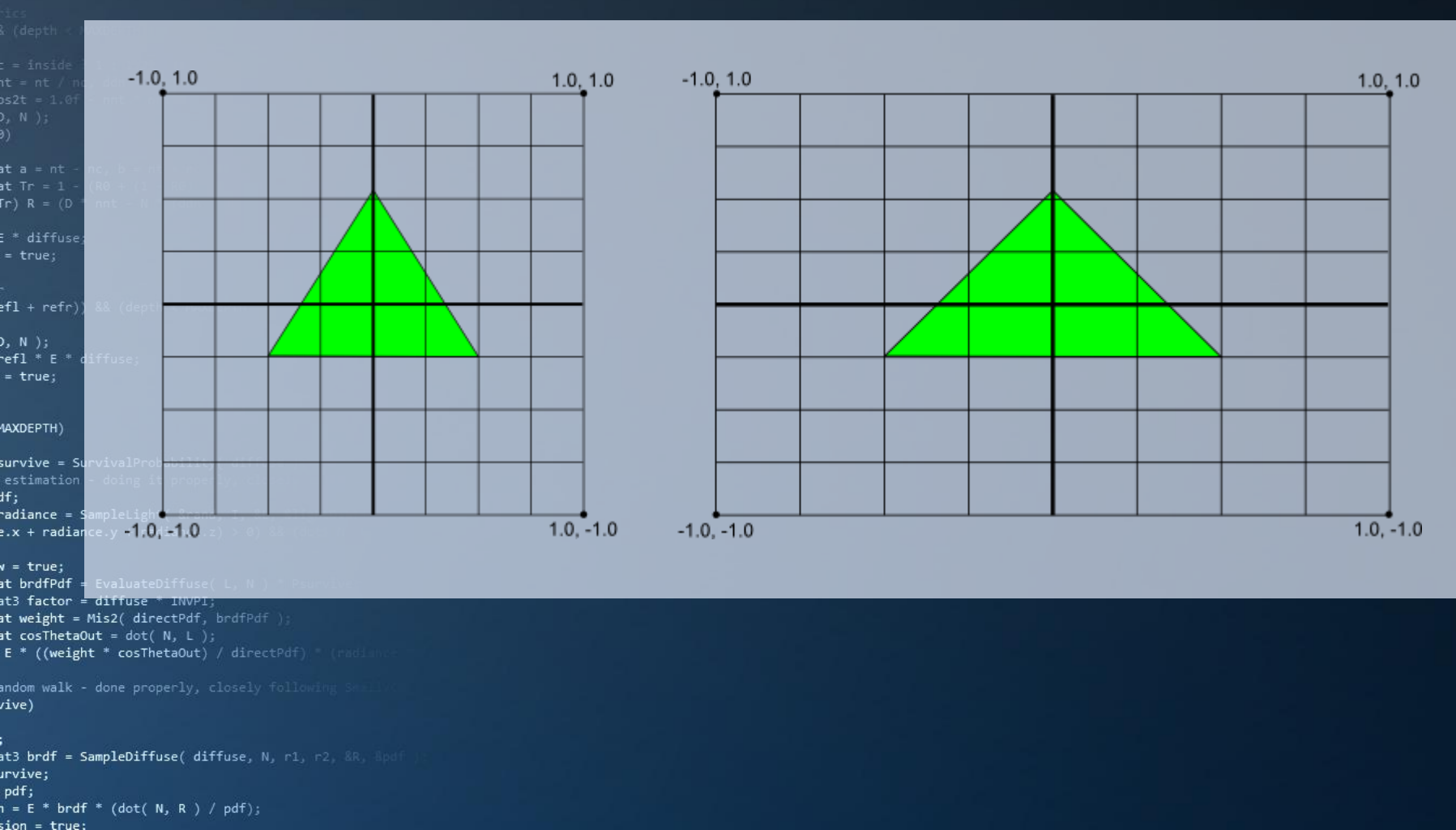
Today's Agenda:

- Introduction
- OpenGL
- GPU Model
- Upcoming
- Assignment P3



OpenGL

OpenGL Coordinates



OpenGL

OpenGL Basics

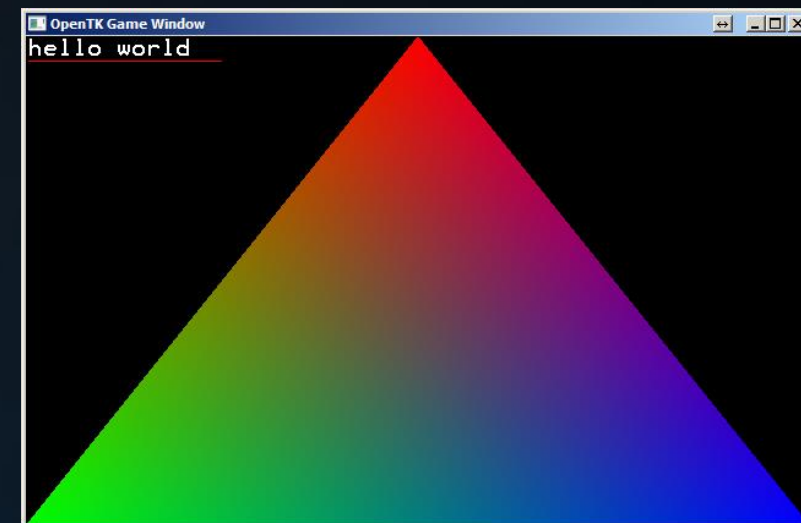
C# / OpenTK:

```
public void TickGL()
{
    GL.Begin( PrimitiveType.Triangles );
    GL.Color3( 1.0f, 0, 0 ); GL.Vertex2( 0.0f, 1.0f );
    GL.Color3( 0, 1.0f, 0 ); GL.Vertex2( -1.0f, -1.0f );
    GL.Color3( 0, 0, 1.0f ); GL.Vertex2( 1.0f, -1.0f );
    GL.End();
}
```

C++:

```
glBegin( GL_TRIANGLES );
glColor3f( 1.0f, 0, 0 ); glVertex2f( 0.0f, 1.0f );
glColor3f( 0, 1.0f, 0 ); glVertex2f( -1.0f, -1.0f );
glColor3f( 0, 0, 1.0f ); glVertex2f( 1.0f, -1.0f );
glEnd();
```

Points
Lines
LineLoop
LineStrip
Triangles
TriangleStrip
TriangleFan
Quads
QuadsExt
...



OpenGL

OpenGL Basics

```
static float depth = -1.0f;
```

```
public void TickGL()
```

```
{
```

```
    GL.Frustum( -1.0f, 1.0f, -1.0f, 1.0f, 1.0f, 10.0f );
```

```
    GL.Begin( PrimitiveType.Triangles );
```

```
    GL.Color3( 1.0f, 0, 0 ); GL.Vertex3( 0.0f, 1.0f, depth );
```

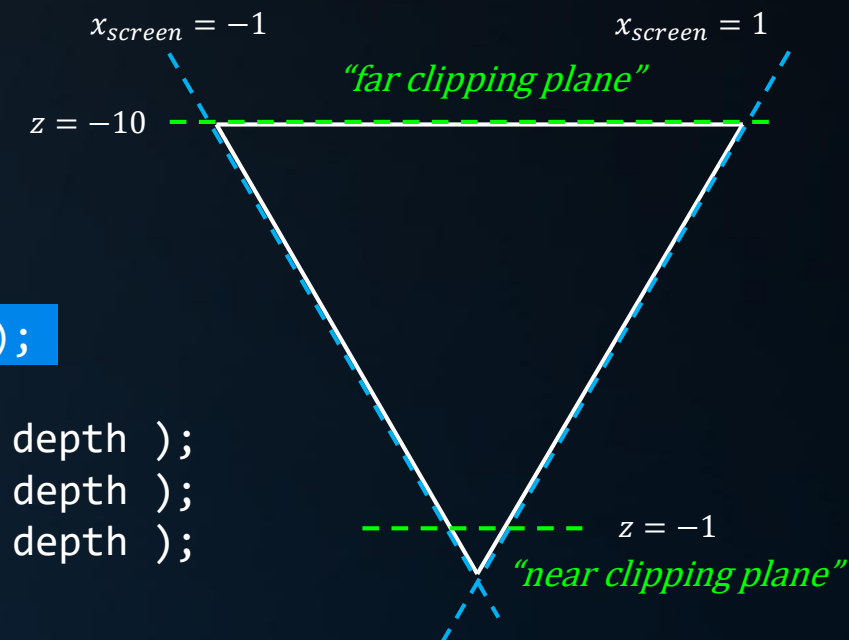
```
    GL.Color3( 0, 1.0f, 0 ); GL.Vertex3( -1.0f, -1.0f, depth );
```

```
    GL.Color3( 0, 0, 1.0f ); GL.Vertex3( 1.0f, -1.0f, depth );
```

```
    GL.End();
```

```
    depth += 0.01f;
```

```
}
```



OpenGL

OpenGL Basics

Apply perspective to:

A translated object:

That we rotated.

Here are it's original vertices.

```
static float r = 0.0f;
```

```
public void TickGL()
{
```

```
    // set model view matrix
```

```
    GL.Frustum( -1.0f, 1.0f, -1.0f, 1.0f, 1.0f, 15.0f );
```

```
    GL.Translate( 0, 0, -2 );
```

```
    GL.Rotate( r, 0, 1, 0 );
```

```
    // render primitives
```

```
    GL.Begin( PrimitiveType.Triangles );
```

```
    GL.Color3( 1.0f, 0, 0 ); GL.Vertex3( 0.0f, -0.3f, 1.0f );
```

```
    GL.Color3( 0, 1.0f, 0 ); GL.Vertex3( -1.0f, -0.3f, -1.0f );
```

```
    GL.Color3( 0, 0, 1.0f ); GL.Vertex3( 1.0f, -0.3f, -1.0f );
```

```
    GL.End();
```

```
    r += 0.1f;
```



OpenGL

OpenGL Basics

```
static int textureID;
```

```
public void TickGL()
```

```
{
```

```
    GL.BindTexture( TextureTarget.Texture2D, textureID );
```

```
    GL.Begin( PrimitiveType.Triangles );
```

```
    GL.TexCoord2( 0.5f, 0 ); GL.Vertex2( 0.0f, 1.0f );
```

```
    GL.TexCoord2( 0, 1 ); GL.Vertex2( -1.0f, -1.0f );
```

```
    GL.TexCoord2( 1, 1 ); GL.Vertex2( 1.0f, -1.0f );
```

```
    GL.End();
```

```
}
```

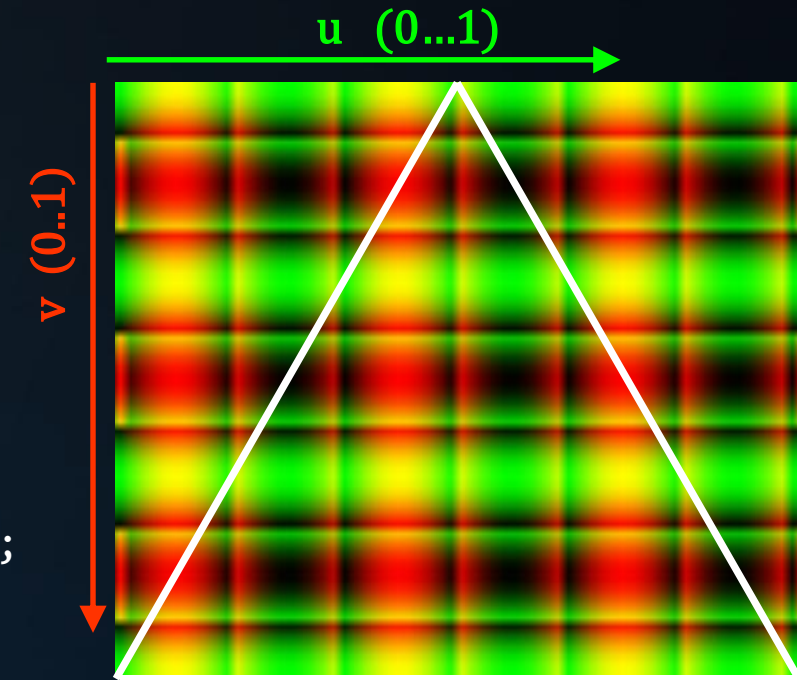
```
textureID = screen.GenTexture();
```

```
GL.BindTexture( TextureTarget.Texture2D, textureID );
```

```
uint [] data = new uint[64 * 64];
```

```
for( int y = 0; y < 64; y++ ) for( int x = 0; x < 64; x++ ) data[x + y * 64] =
    ((uint)(255.0f * Math.Sin( x * 0.3f )) << 16) +
    ((uint)(255.0f * Math.Cos( y * 0.3f )) << 8);
```

```
GLTexImage2D( TextureTarget.Texture2D, 0, PixelInternalFormat.Rgba, 64, 64, 0,
    OpenTK.Graphics.OpenGL.PixelFormat.Bgra, PixelType.UnsignedByte, data );
```



OpenGL

OpenGL State

OpenGL is a *state machine*:

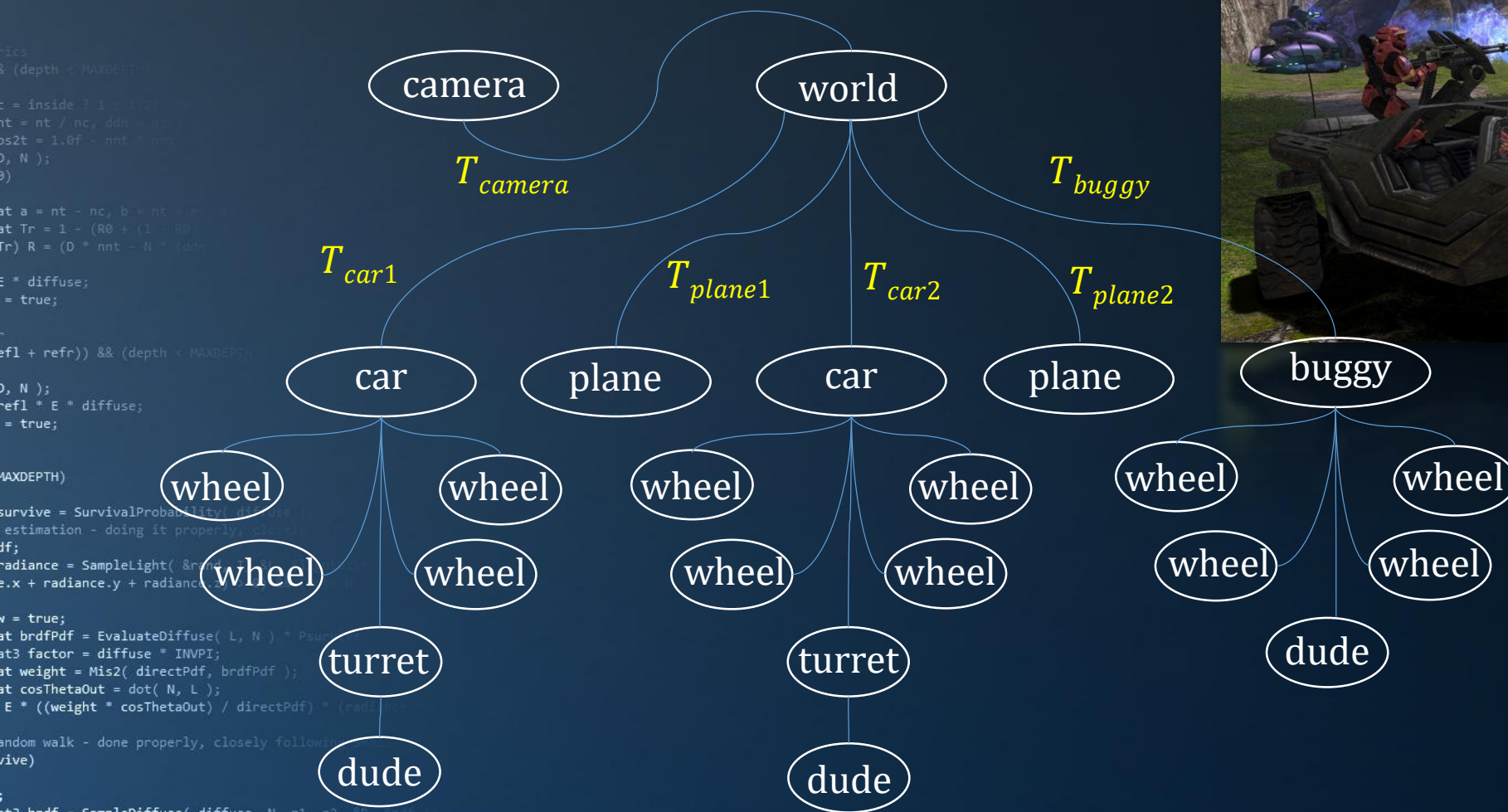
- We set a texture, and all subsequent primitives are drawn with this texture;
- We set a color ... ;
- We set a matrix ... ;
- ...

Related to this:

- A scene graph matches this behavior.
- A GPU expects this behavior.



OpenGL



Today's Agenda:

- Introduction
- OpenGL
- GPU Model
- Upcoming
- Assignment P3

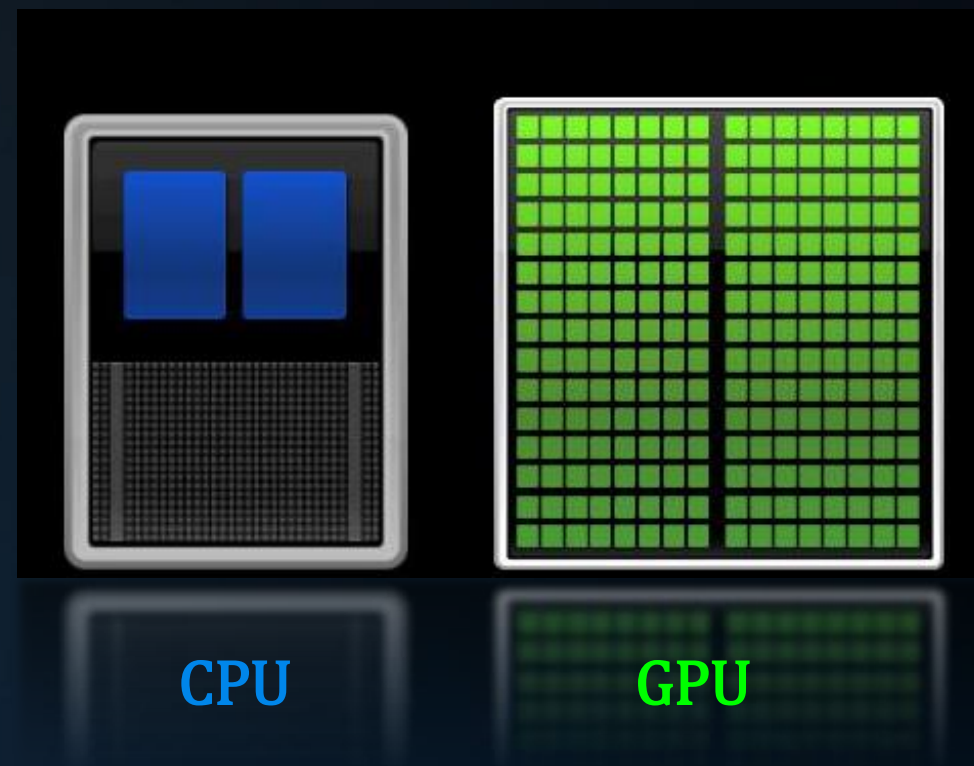


GPU Model

GPU: Streaming Processor

A GPU is designed to work on many uniform tasks in parallel.

- It has (vastly) more cores
- The cores must all execute identical code
- It does not rely on caches



CPU

GPU

A CPU is optimized to execute a few complex tasks.

- It uses caches to benefit from patterns in data access
- It uses complex cores to maximize throughput for complex algorithms.



```

        &(depth < MAXDEPTH)
        {
            int inside = 0;
            int nt = nt / nc;
            double cos2t = 1.0f -
                (double) D, N );
            double R = (D * n
            + a = nt - nc;
            double Tr = 1 - (R
            + R) R = (D * n
            + E * diffuse;
            double = true;
            double refl + refr) &
            double D, N );
            double refl * E * dif
            = true;
            double MAXDEPTH)
            double survive = Surv
            estimation -
            diff;
            double radiance = Sam
            double x + radiance
            double w = true;
            double brdfPdf = E
            double at3 factor = d
            double at weight = Mi
            double cosThetaOut
            double E * ((weight
            double random walk - d
            double survive)

```

- ```

survive = SurvivalProbability(diffuse, L, N);
estimation - doing it properly, closely following Survival
if;
 radiance = SampleLight(&rand, I, &L, &diffuse);
 if(rand.x + radiance.y + radiance.z > 0) && (do
w = true;
at brdfPdf = EvaluateDiffuse(L, N) * Pdf
at3 factor = diffuse * INVPI;
at weight = Mis2(directPdf, brdfPdf);
at cosThetaOut = dot(N, L);
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following Survival
ive)
;
at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R, &pdf
survive;
pdf;
n = E * brdf * (dot(N, R) / pdf);
sion = true;

```



# GPU Model

## Switching State

A state change requires:

- Data transfer from CPU to GPU
- Setting pipeline parameters
- Restarting the pipeline
- Invalidating texture caches

We will want to minimize state changes.

We will want to send large jobs to prevent GPU under-utilization.

We will want to use data that is already on the GPU.

*We will want to avoid using immediate mode.*



# GPU Model

## Immediate Mode

In immediate mode, everything between `GL.Begin()` and `GL.End()` is pushed through the pipeline *right away*.

To make things worse, all parameters are passed from the CPU to the GPU.

We get:

- Expensive data transfer with severe latency
- A tiny render task for the massively parallel graphics processor.

We can improve on this using *retained mode* and *Vertex Buffer Objects*.



# GPU Model

## Retained Mode

In retained mode, we create a ‘list’ of commands:

```
GL.NewList(out listID, ListMode.Compile);
 GL.Begin(PrimitiveType.Triangles);
 GL.Vertex2(0.0f, 1.0f);
 GL.Vertex2(-1.0f, -1.0f);
 GL.Vertex2(1.0f, -1.0f);
 GL.End();
GL.EndList();
```

We can now execute the list of commands using GL.CallList:

```
GL.CallList(listID);
```

‘Compiling’ here means: optimizing for fast execution on the GPU.



# GPU Model

## Vertex Buffer Objects

VBOs allow us to store vertex data in GPU memory.

```
static int vboID;
public void TickGL()
{
 GL.BindBuffer(BufferTarget.ArrayBuffer, vboID);
 GL.DrawArrays(PrimitiveType.Triangles, 0, 9);
}

GL.GenBuffers(1, out vboID);
float [] vertexData = { 0, 1, depth, -1, -1, depth, 1, -1, depth };
GL.BindBuffer(BufferTarget.ArrayBuffer, vboID);
GL.BufferData<float>(BufferTarget.ArrayBuffer, (IntPtr)(vertexData.Length * 4),
 vertexData, BufferUsageHint.StaticDraw);
GL.EnableClientState(ArrayCap.VertexArray);
GL.VertexPointer(3, VertexPointerType.Float, 9, 0);
```



# GPU Model

## Vertex Buffer Objects

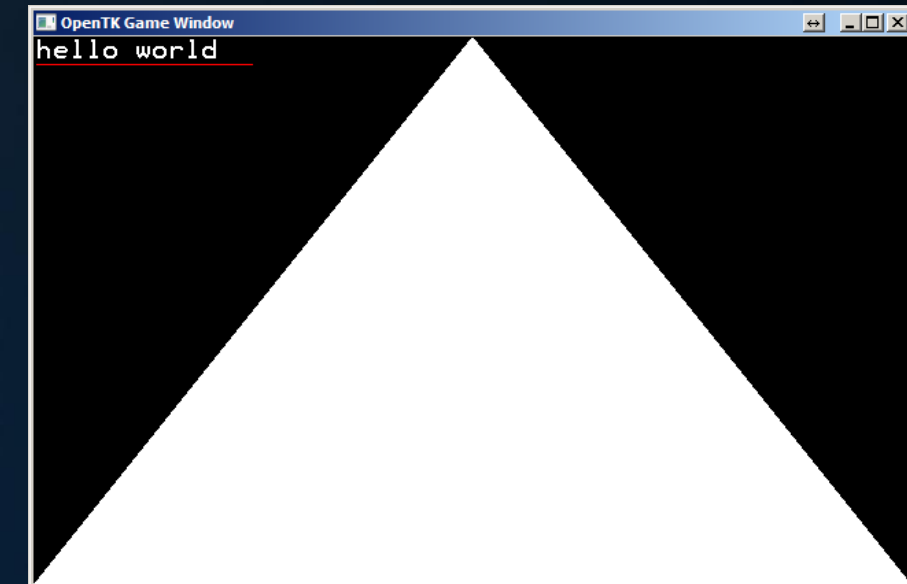
```
static int vboID;
public void TickGL()
{
 GL.BindBuffer(BufferTarget.ArrayBuffer, vboID);
 GL.DrawArrays(PrimitiveType.Triangles, 0, 9);
}
```

equals:

```
public void TickGL()
{
 GL.Begin(PrimitiveType.Triangles);
 GL.Vertex2(0.0f, 1.0f);
 GL.Vertex2(-1.0f, -1.0f);
 GL.Vertex2(1.0f, -1.0f);
 GL.End();
}
```

Colors / texture coordinates / etc.:

1. Pass additional data in the vertex array, enable it using `GL.EnableClientState`.
2. Start using shaders, see P1.



# GPU Model

## Optimizing GPU Usage

We don't send individual commands to the GPU, but we batch them in lists.

We don't send the texture to the GPU for each frame, we just use the 'ID' of a texture, managed by OpenGL.

We now also don't send vertex data to the GPU anymore: the data is already on the device.

### Problem:

What happens when we want to change variable depth?

```
GL.NewList(out listID, ListMode.Compile);
 GL.Begin(PrimitiveType.Triangles);
```

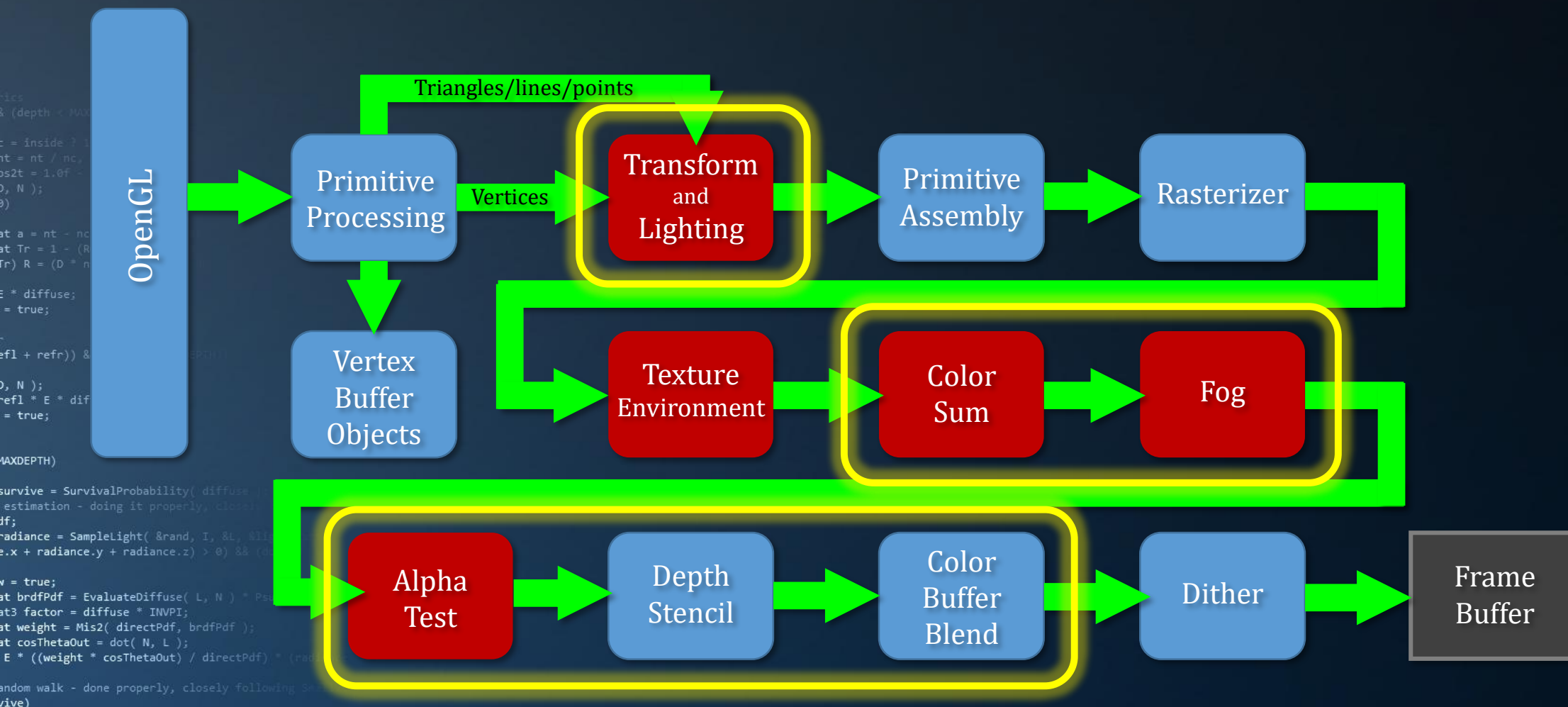
```
 ...
GL.End();
GL.EndList();
```

```
textureID = screen.GenTexture();
GL.BindTexture(TextureTarget.Texture2D, textureID);
uint [] data = new uint[64 * 64];
...
GL TexImage2D(TextureTarget.Texture2D, ... , data);
```

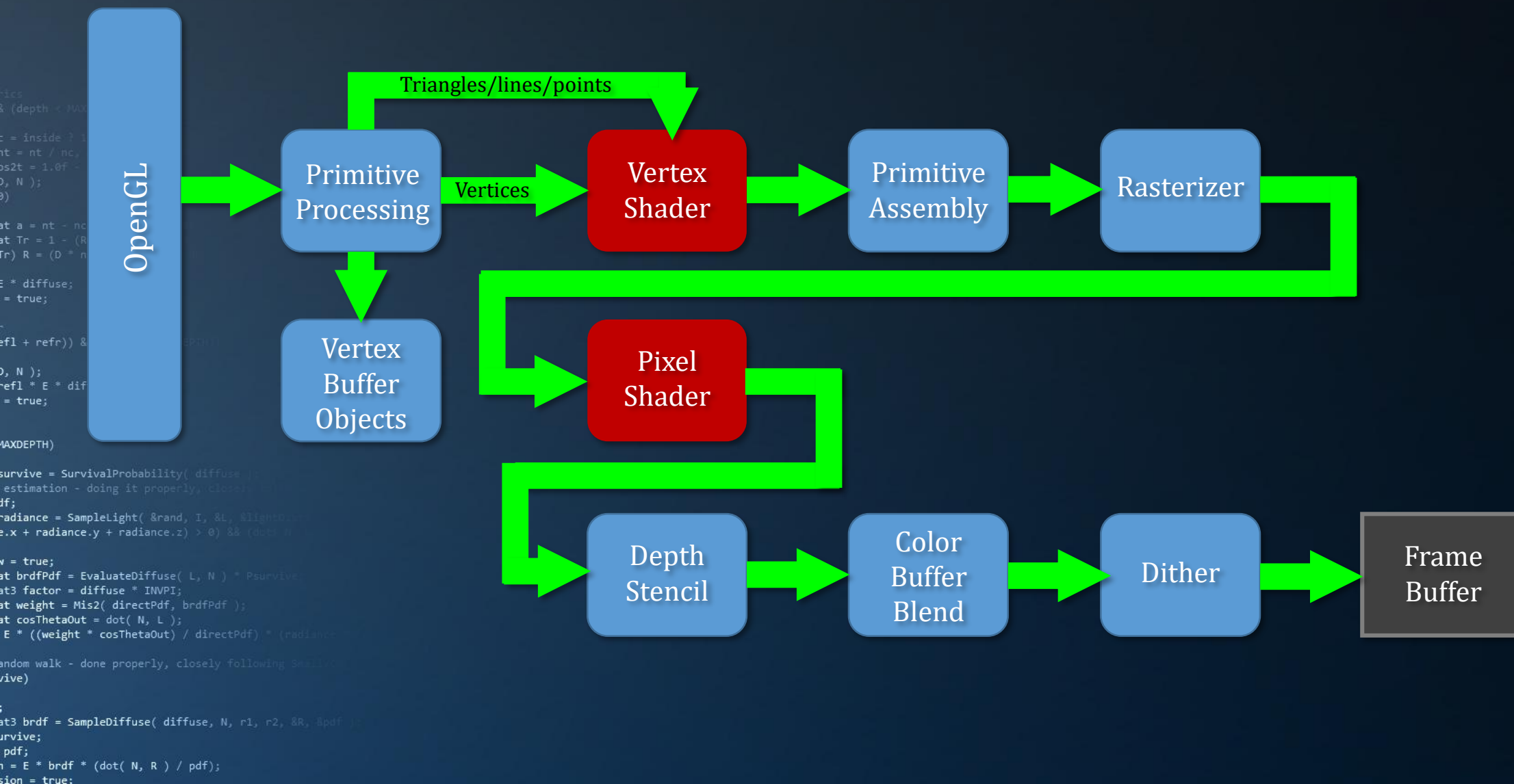
```
GL.GenBuffers(1, out vboID);
float [] vertexData = { 0, 1, depth, -1, -1, depth, 1, -1, depth };
GL.BindBuffer(BufferTarget.ArrayBuffer, vboID);
GL.BufferData<float>(BufferTarget.ArrayBuffer, ... , vertexData, ...);
GL.EnableClientState(ArrayCap.VertexArray);
GL.VertexPointer(3, VertexPointerType.Float, 12, 0);
```



# GPU Model



# GPU Model



# GPU Model

## Shaders: Consequences

The ‘transform & lighting’ stage is programmable, as in: ‘it must be programmed’.

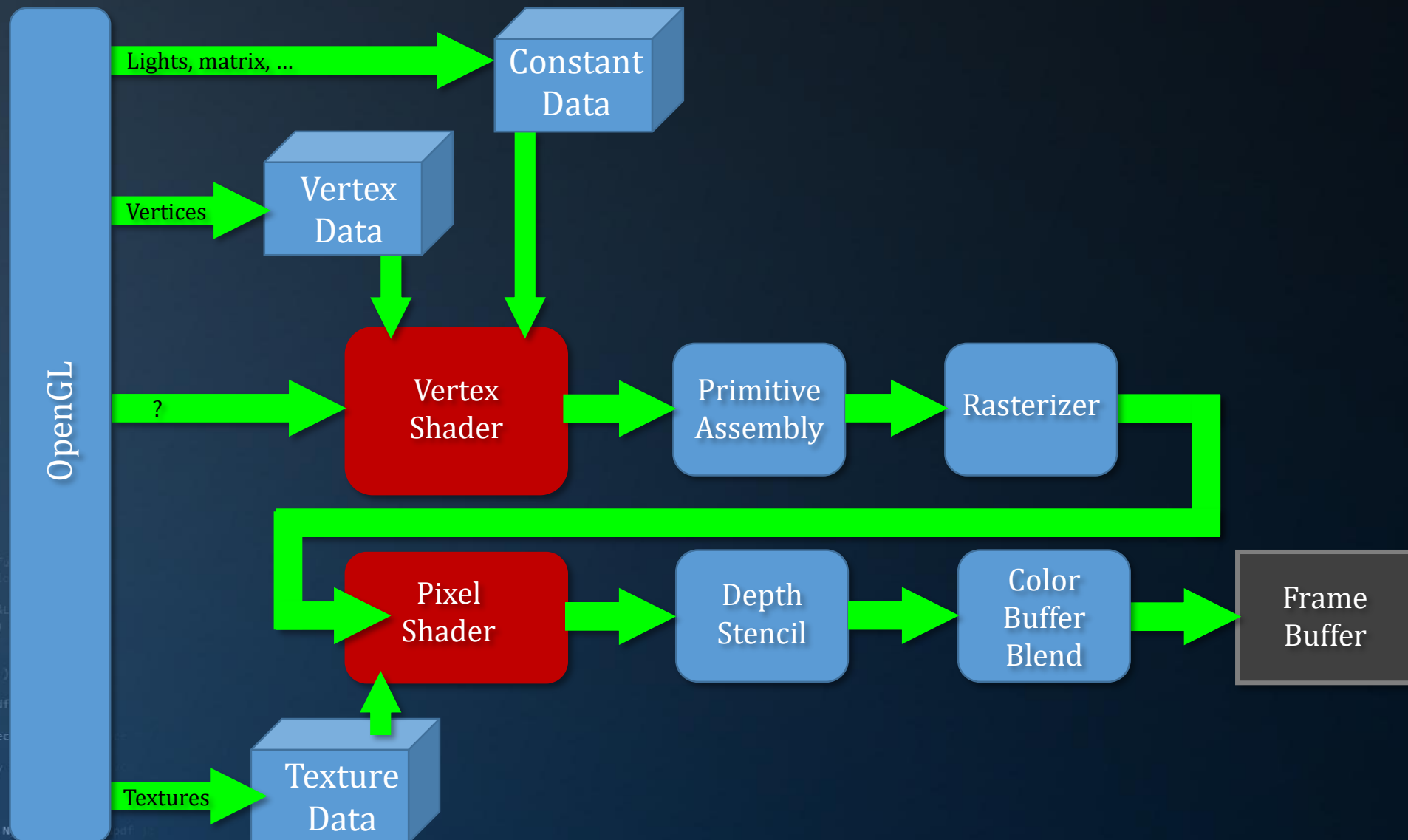
So, what happened here?

*OpenGL emulates a fixed function pipeline to support old OpenGL code.*

```
static float r = 0.0f;
public void TickGL()
{
 GL.Frustum(-1.0f, 1.0f, -1.0f, 1.0f, 1.0f, 15.0f);
 GL.Translate(0, 0, -2);
 GL.Rotate(r, 0, 1, 0);
 GL.Begin(PrimitiveType.Triangles);
 ...
 GL.End();
 r += 0.1f;
}
```



# GPU Model



## Digest:

- Modern OpenGL allows us to keep data on the GPU
- Retained mode allows OpenGL to reorder / optimize draw commands
- Vertex and pixel shaders make large parts of 'classic' OpenGL redundant



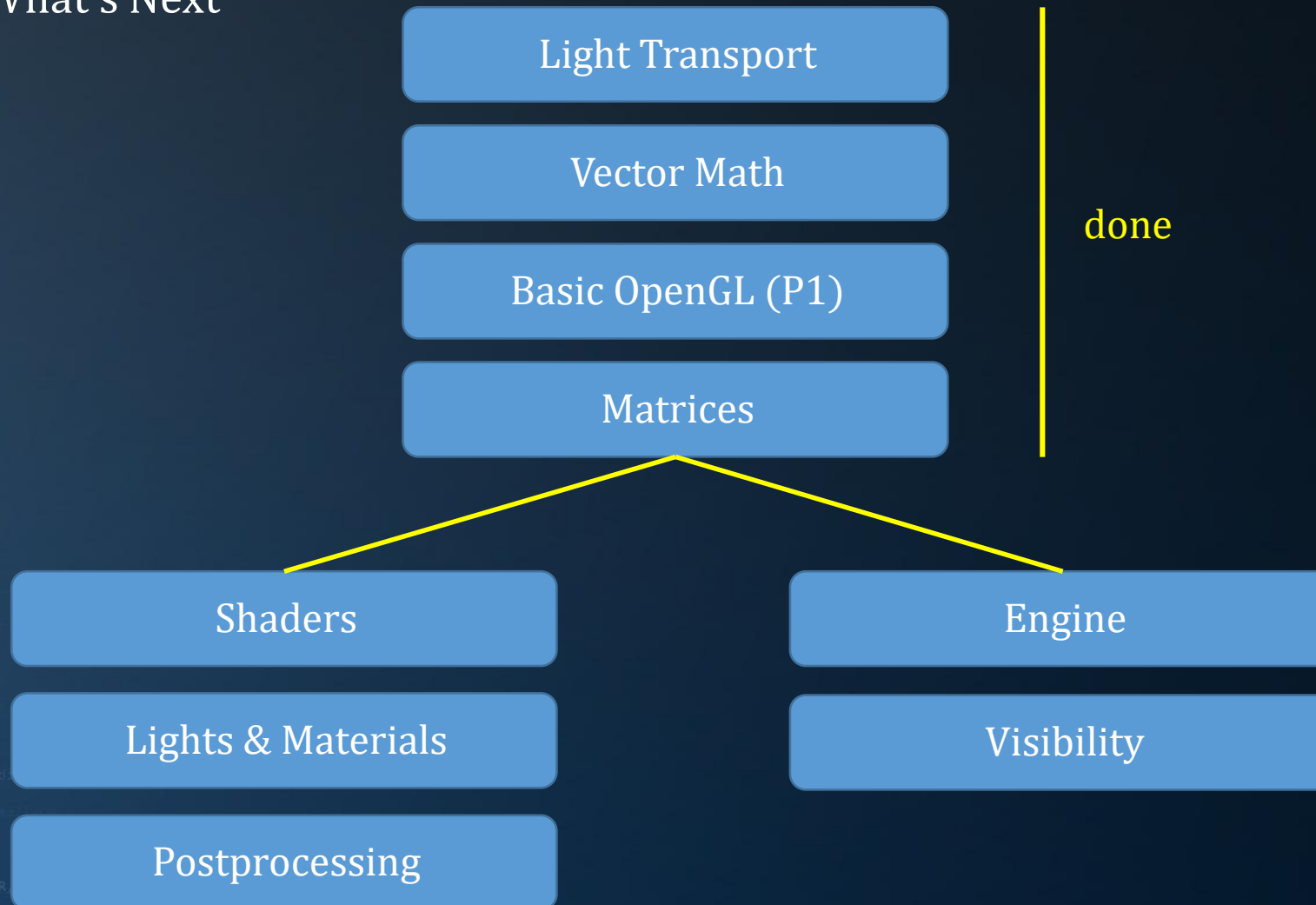
# Today's Agenda:

- Introduction
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- Assignment P3



# Upcoming

## What's Next



# Today's Agenda:

- Introduction
- OpenGL
- GPU Model
- Upcoming
- Assignment P3



# Practical

## Assignment P3

New framework! Already done for you:

- Mesh storage and rendering: mesh.cs
- .OBJ file loading: meshLoader.cs
- Shader loading, compilation, binding: shader.cs
- Texture loading: texture.cs
- Render target: renderTarget.cs
- Quad rendering: quad.cs

Assignment goals:

- Implement a scene graph
- Implement proper shaders



# Practical

## Meshes

After loading (via meshLoader):

Generate buffers:

```
GL.GenBuffers(1, out vertexBufferId / triangleBufferId / quadBufferID);
GL.BindBuffer(BufferTarget.ArrayBuffer, ...);
GL.BufferData(BufferTarget.ArrayBuffer, ...);
```



# Practical

## Meshes

To render, bind the texture to the shader:

```
int texLoc = GL.GetUniformLocation(shader.programID, "pixels");
GL.Uniform1(texLoc, 0);
GL.ActiveTexture(TextureUnit.Texture0);
GL.BindTexture(TextureTarget.Texture2D, texture.id);
```

Bind the shader:

```
GL.UseProgram(shader.programID);
```

Set matrix for vertex shader:

```
GL.UniformMatrix4(shader.uniform_mview, false, ref transform);
```



# Practical

## Meshes

Enable VertexArray usage, bind the vertex buffer, specify data layout:

```
GL.EnableClientState(ArrayCap.VertexArray);
GL.BindBuffer(BufferTarget.ArrayBuffer, vertexBufferId);
GL.InterleavedArrays(InterleavedArrayFormat.T2fN3fv3f, ...);
```

Link the vertex attributes to the shader:

```
GL.VertexAttribPointer(shader.attribute_vuvs, 2, VertexAttribPointerType.Float, false, 32, 0);
GL.VertexAttribPointer(shader.attribute_vnorm, 3, VertexAttribPointerType.Float, true, 32, 2 * 4);
GL.VertexAttribPointer(shader.attribute_vpos, 3, VertexAttribPointerType.Float, false, 32, 5 * 4);
```

Enable the attributes:

```
GL.EnableVertexAttribArray(shader.attribute_vpos);
GL.EnableVertexAttribArray(shader.attribute_vnorm);
GL.EnableVertexAttribArray(shader.attribute_vuvs);
```



# Practical

## Meshes

Bind the index array and render:

```
GL.BindBuffer(BufferTarget.ElementArrayBuffer, triangleBufferId);
GL.DrawArrays(PrimitiveType.Triangles, 0, triangles.Length * 3);
```

...But, the important part is:

```
public void Render(Shader shader, Matrix4 transform, Texture texture)
{
}
```



# Practical

## Frame Buffer Object (FBO)

```

public void Bind()
{
 GL.Ext.BindFramebuffer(FramebufferTarget.FramebufferExt, fbo);
 GL.Clear(ClearBufferMask.DepthBufferBit);
 GL.Clear(ClearBufferMask.ColorBufferBit);
}

public void Unbind()
{
 GL.Ext.BindFramebuffer(FramebufferTarget.FramebufferExt, 0);
}

```

This allows you to *render to a texture*.

Why? So we can put the texture on a screen filling quad, which we can render with a shader.

This enables post processing effects.



# Practical

## Bringing it all together

### In MyApplication.cs:

```
Mesh mesh, floor;
Shader shader;
Shader postproc;
Texture wood;
RenderTarget target;
ScreenQuad quad;
```

### We will use this data to:

- Render two meshes (‘mesh’ and ‘floor’)
- using texture ‘wood’ and shader ‘shader’
- onto render target ‘target’,
- which we use to texture ‘quad’ (which is essentially also a mesh).



# Practical

```
#version 330

// shader input
in vec2 vUV;
in vec3 vNormal;
in vec3 vPosition;

// shader output
out vec4 normal;
out vec2 uv;
uniform mat4 transform;

// vertex shader
void main()
{
 // transform vertex using supplied matrix
 gl_Position = transform * vec4(vPosition, 1.0);

 // forward normal and uv coordinate
 normal = transform * vec4(vNormal, 0.0f);
 uv = vUV;
}
```

```
#version 330

// shader input
in vec2 uv;
in vec4 normal;
uniform sampler2D pixels;

// shader output
out vec4 outputColor;

// fragment shader
void main()
{
 outputColor = texture(pixels, uv) +
 0.5f * vec4(normal.xyz, 1);
}
```



# Practical

```
#version 330
```

```
// shader input
```

```
in vec2 vUV;
```

```
in vec3 vPosition;
```

```
// shader output
```

```
out vec2 uv;
```

```
out vec2 P;
```

```
// vertex shader
```

```
void main()
```

```
{
```

```
 uv = vUV;
```

```
 P = vec2(vPosition) * 0.5 + vec2(0.5, 0.5);
```

```
 gl_Position = vec4(vPosition, 1);
```

```
}
```

```
#version 330
```

```
// shader input
```

```
in vec2 P;
```

```
in vec2 uv;
```

```
uniform sampler2D pixels;
```

```
// shader output
```

```
out vec3 outputColor;
```

```
void main()
```

```
{
```

```
 outputColor = texture(pixels, uv).rgb;
```

```
 float dx = P.x - 0.5, dy = P.y - 0.5;
```

```
 float distance = sqrt(dx * dx + dy * dy);
```

```
 outputColor *= sin(distance * 200.0f)
```

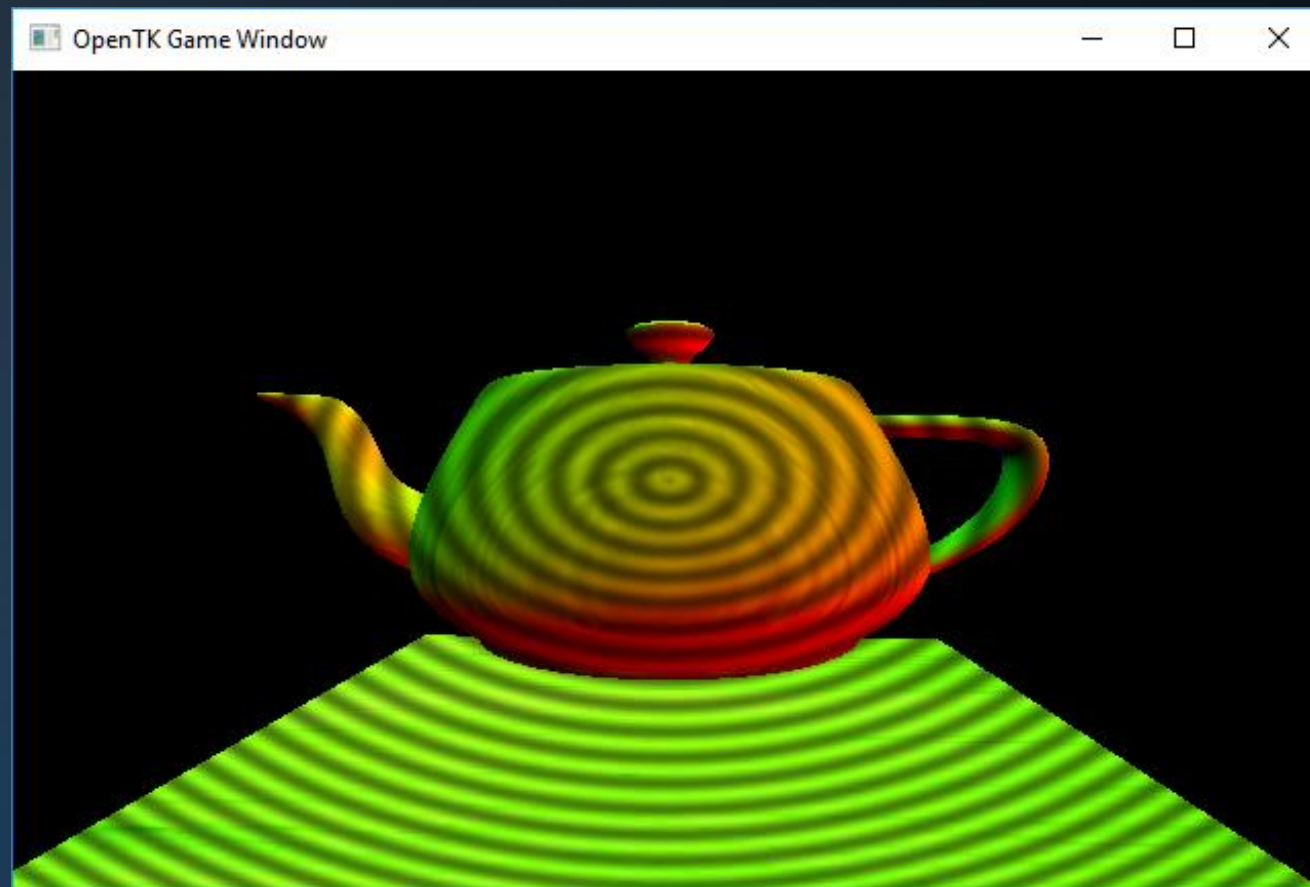
```
 * 0.25f + 0.75f;
```

```
}
```



# Practical

```
ics
& (depth < MAXDEPTH)
{
 if (inside ? 1 : 1.0f - 0.9f * dot(N, N))
 {
 nt = nt / nc, ddn = ddn * ddn;
 cos2t = 1.0f - nnt * ddn;
 D, N);
 }
 at a = nt - nc, b = nt + nc;
 at Tr = 1 - (R0 + (1 - R0) * sqrt(cos2t));
 (Tr) R = (D * nnt - N * (ddn < 0 ? 1 : -1));
 E * diffuse;
 = true;
 refl + refr)) && (depth < MAXDEPTH)
 {
 D, N);
 refl * E * diffuse;
 = true;
 }
 MAXDEPTH)
 survive = SurvivalProbability(diffuse);
 estimation - doing it properly, closely following
 df;
 radiance = SampleLight(&rand, I, &L, &align, &pdf);
 e.x + radiance.y + radiance.z) > 0) && (depth < MAXDEPTH)
 {
 w = true;
 at brdfPdf = EvaluateDiffuse(L, N) * Psurvive;
 at3 factor = diffuse * INVPI;
 at weight = Mis2(directPdf, brdfPdf);
 at cosThetaOut = dot(N, L);
 E * ((weight * cosThetaOut) / directPdf) * (radiance
 }
 random walk - done properly, closely following
 (survive)
 ;
 at3 brdf = SampleDiffuse(diffuse, N, r1, r2, &R, &pdf);
 survive;
 pdf;
 n = E * brdf * (dot(N, R) / pdf);
 sion = true;
}
```



# INFOGR – Computer Graphics

Jacco Bikker & Debabrata Panja - April-July 2019

END OF lecture 9: “OpenGL”

*Next lecture: “Shaders”*

