

```
ics
(depth < MAXDEPTH)
inside ? 1 : 0;
nt = nt / nc; ddn = abs(
s2t = 1.0f - nnt * nnt;
D, N );
)
at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) *
Tr) R = (D * nnt - N * (ddn
E * diffuse;
= true;
efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse,
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light;
e.x + radiance.y + radiance.z) > 0) && (abs(
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```

/INFOMOV/

Optimization & Vectorization

J. Bikker - April-June 2024 - Lecture 3: "Profiling"

Welcome!



```
ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * ddn);
Tr) R = (D * nnt - N * (ddn * ddn));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)

survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light);
e.x + radiance.y + radiance.z) > 0) && (depth <
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance

random walk - done properly, closely following
ive)

;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```

Today's Agenda:

- Introduction
- Metrics, Clocks and Counters
- Scalability Issues
- Environment and Tools
- Dirty Hands



Introduction

Consistent Approach

(0.) Determine optimization requirements

1. Profile: determine hotspots
2. Analyze hotspots: determine scalability
3. Apply high level optimizations to hotspots
4. Profile again.
5. Parallelize
6. Use GPGPU
7. Profile again.
8. Apply low level optimizations to hotspots
9. Repeat steps 7 and 8 until time runs out
10. Report.

Do you actually need to speed it up?
By how much?

Things to consider:

- You have a finite amount of time for this
- You don't want to break anything
- You don't want to reduce maintainability

➔ **Focus on 'low hanging fruit'** – typically a small portion of the code.

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * r);
Tr) R = (D * nnt - N * (ddn * r));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;
}

MAXDEPTH)
survive = SurvivalProbability( diffuse, r);
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &align, &N, &R, &pdf, &N );
e.x + radiance.y + radiance.z) > 0) && (depth < MAXDEPTH)
{
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance.x + radiance.y + radiance.z);
}

random walk - done properly, closely following 3rd edition
ive)

;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf, &N );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
    
```



Introduction

Consistent Approach

(0.) Determine optimization requirements

1. Profile: determine hotspots

2. Analyze hotspots: determine scalability

3. Apply high level optimizations to hotspots

4. Profile again.

5. Parallelize

6. Use GPGPU

7. Profile again.

8. Apply low level optimizations to hotspots

9. Repeat steps 7 and 8 until time runs out

10. Report.

Don't trust your intuition

- Not even when optimizing your own code.
- *Especially* not when you are proficient at optimizing.

Blind changes may *reduce* the performance of the code.

Needless to say: *use version control.*



Introduction

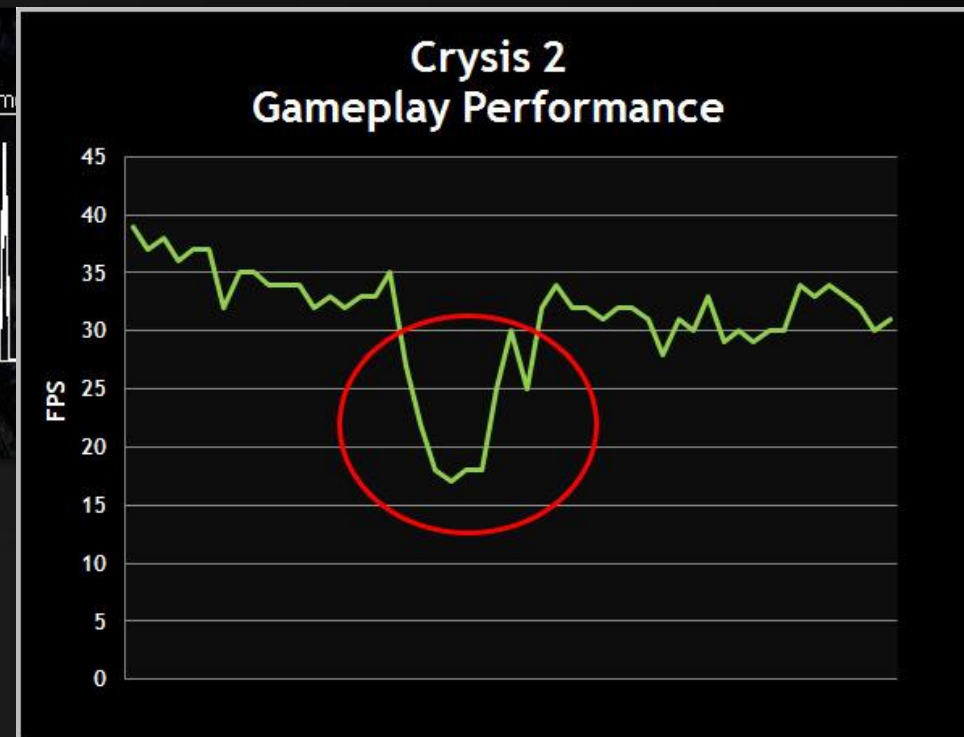
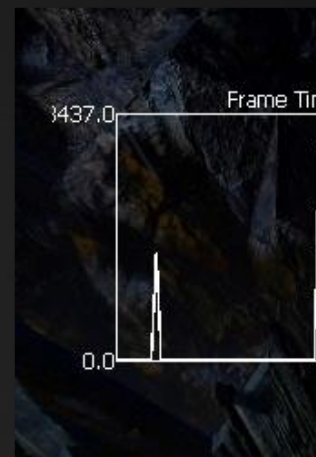
Profiling

Measuring application performance

- Using timers in the code
- Using external tools

Details:

- Overall, average or time analysis
- What to measure
- Doing proper experiment setup
- Interpreting the data
- Acting on the findings
- Repeating the whole process



Focus on 'low hanging fruit'



Introduction

Subject

Application breakdown, Tick:

```
t.reset(); Transform(); elapsed1 = t.elapsed();
t.reset(); Sort();      elapsed2 = t.elapsed();
t.reset(); Render();    elapsed3 = t.elapsed();
```

Transform:

```
for ( int i = 0; i < DOTS; i++ )
    m_Rotated[i] = m.Transform( m_Points[i] );
```

Sort:

```
for ( int i = 0; i < DOTS; i++ )
    for ( int j = 0; j < (DOTS - 1); j++ )
        if ( m_Rotated[j].z > m_Rotated[j + 1].z ) Swap( j, j + 1 );
```

Render:

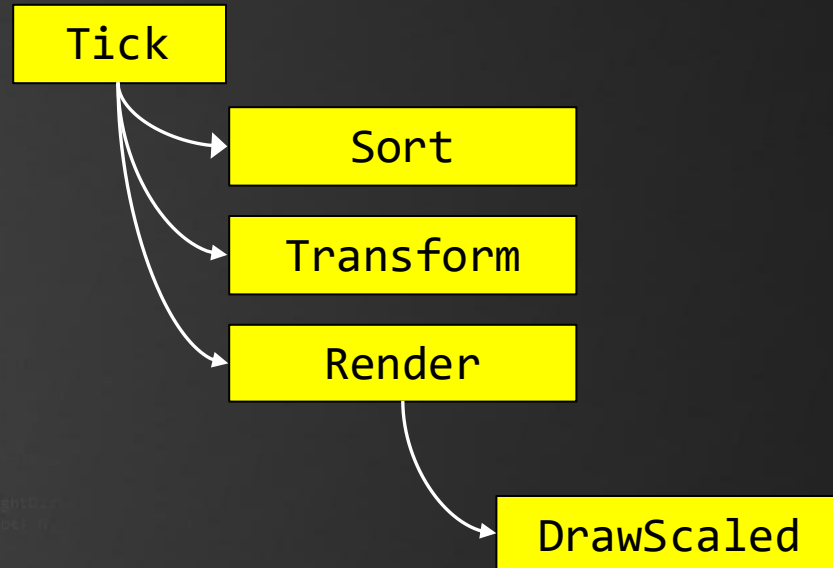
```
for ( int i = 0; i < DOTS; i++ )
    m_Dot->DrawScaled( (sx - size / 2), (sy - size / 2), size, size, screen );
```



Introduction

DotCloud

Application breakdown:



```

...ics
& (depth < MAXDEPTH)
...
c = inside ? 1 : 0;
nt = nt / nc; ddn = udot(
...s2t = 1.0f - nnt * nnt;
D, N );
...
)
...
at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) *
...Tr) R = (D * nnt - N * (ddn
...
E * diffuse;
= true;
...
efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
...
MAXDEPTH)
survive = SurvivalProbability( diffuse, i);
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light;
e.x + radiance.y + radiance.z) > 0) && (survive)
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
...
random walk - done properly, closely following
ive)
...
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



Metrics

Timers

The template includes a ‘Timer’:

```
// timer
struct Timer
{
    Timer() { reset(); }
    float elapsed() const
    {
        chrono::high_resolution_clock::time_point t2 = chrono::high_resolution_clock::now();
        chrono::duration<double> time_span = chrono::duration_cast<chrono::duration<double>>(t2 - start);
        return (float)time_span.count();
    }
    void reset() { start = chrono::high_resolution_clock::now(); }
    chrono::high_resolution_clock::time_point start;
};
```

Based on some quick research:

- Windows: 100ns
- Linux: 10ns

@ 5Ghz: 100ns \approx 500 CPU cycles.



Metrics



Timers

Note that resolution is not very important.

If it takes very little time to execute some code:

```
t.reset(); Transform(); elapsed1 = t.elapsed();
t.reset(); Sort(); elapsed2 = t.elapsed();
t.reset(); Render(); elapsed3 = t.elapsed();
```

Then we just execute it multiple times:

```
t.reset(); for( int i = 0; i < 1000; i++ ) Transform(); elapsed1 = t.elapsed();
t.reset(); for( int i = 0; i < 1000; i++ ) Sort(); elapsed2 = t.elapsed();
t.reset(); for( int i = 0; i < 1000; i++ ) Render(); elapsed3 = t.elapsed();
```

(Note that there's issues with that approach)

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        ps2t = 1.0f + nnt * (nt - 1);
        D, N );
    }
}

at a = nt - nc, b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * a);
Tr) R = (D * nnt - N * (D0 +
);

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)
survive = SurvivalProbability( diffuse, r1, r2, &R, Spdf );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, Align );
e.x + radiance.y + radiance.z > 0) && (radiance.x > 0)
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psum;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance.x > 0)
random walk - done properly, closely following
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, Spdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



Metrics

Timers

However, there is a different problem with timers.



Processor			
Name	Intel Core i9 13900KS		
Code Name	Raptor Lake	Max TDP	150.0 W
Package	Socket 1700 LGA		
Technology	10 nm	Core VID	0.893 V
Specification: 13th Gen Intel® Core™ i9-13900KS			
Family	6	Model	7
Ext. Family	6	Ext. Model	B7
Stepping	1	Revision	B0
Instructions	MMX, SSE, SSE2, SSE3, SSSE3, SSE4.1, SSE4.2, EM64T, AES, AVX, AVX2, AVX-VNNI, FMA3, SHA		
Clocks (P-Core #0)			
Core Speed	3700.00 MHz		
Multiplier	x 27.0 (8.0 - 56.0)		
Bus Speed	100.00 MHz		
Rated FSB			
Cache			
L1 Data	8 x 48 KB + 16 x 32 KB		
L1 Inst.	8 x 32 KB + 16 x 64 KB		
Level 2	8 x 2 MB + 4 x 4 MB		
Level 3	36 MBytes		
Selection	Socket #1	Cores	8P + 16E
		Threads	32

Question is...

- Is that in fact something we want to include in our experiments?
- If not, can we counter it, i.e., can we make clock speed a stable number?
- If not, can we measure something that is independent of clock speed?



Metrics

CPU Clock

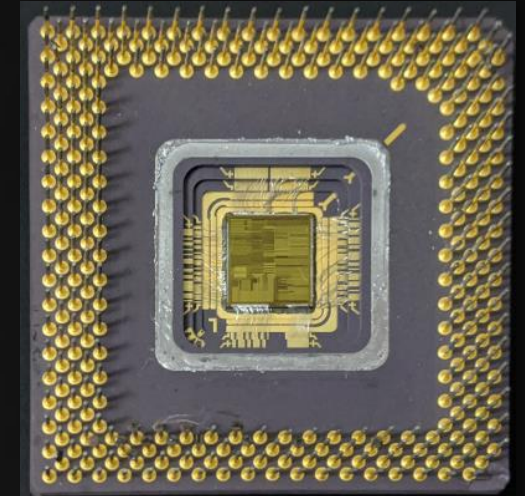
There is a way to directly access the CPU clock:

```
uint64_t start = __rdtsc();
...
uint64_t elapsed = __rdtsc() - start;
```

`__rdtsc` is an assembler instruction that *returns the number of CPU cycles since the last reset.*

Using `__rdtsc()`:

- We *still* get fluctuating results
- We still benefit from measuring longer periods



Metrics

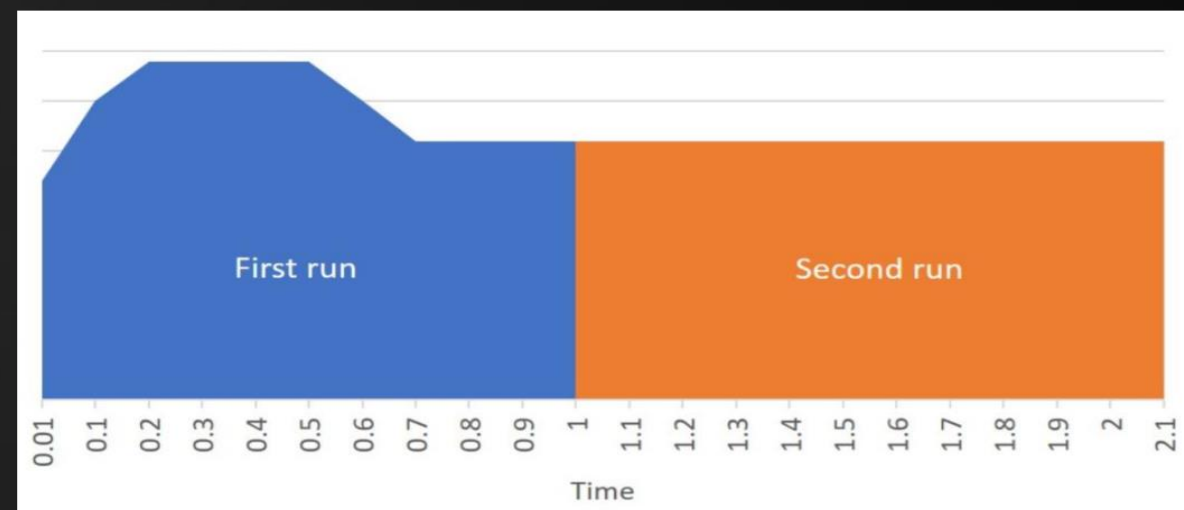
Sources of Noise

When using wallclock time, the source of noise is obvious:

- The CPU clock is not stable.

The timing variations when measuring CPU cycles are less obvious.

- OS task switching
- Caches
- Interrupts
- Subtleties of the memory system



```

ics
& (depth < MAXDEPTH)
{
    if (inside) {
        nt = nt / nc; ddn = ddn / nc;
        cos2t = 1.0f - nnt * nnt;
        D, N );
    }
}

at a = nt - nc, b = nt * n;
at Tr = 1 - (R0 + (1 - R0) * R);
Tr) R = (D * nnt - N * (ddn *
    E * diffuse;
    = true;
}

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse, r1, r2, &R, Spdf );
estimation - doing it properly, closely following Section 3.1.2
if;
radiance = SampleLight( &rand, I, &L, &align, &R, Spdf );
e.x + radiance.y + radiance.z > 0) && (cosThetaOut > 0)
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance * cosThetaOut);
random walk - done properly, closely following Section 3.1.2
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, Spdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
    
```



Metrics

Deal with Uncertainty

To get reliable results:

1. Take multiple measurements..
2. ...until standard deviation lies within desired range.
3. Mind ‘cache warming’: skip the first couple of seconds.
4. Try to use a stable testing environment.

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
    at a = nt - nc, b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) *
    Tr) R = (D * nnt - N * (D0
    E * diffuse;
    = true;
    -
    refl + refr)) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;
    MAXDEPTH)
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light;
    e.x + radiance.y + radiance.z) > 0) && (abs(
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    survive)
    ;
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;

```



```
ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * ddn);
Tr) R = (D * nnt - N * (ddn * ddn));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)

survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light);
e.x + radiance.y + radiance.z) > 0) && (depth <
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance

random walk - done properly, closely following
vive)

;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```

Today's Agenda:

- Introduction
- Metrics, Clocks and Counters
- Scalability Issues
- Environment and Tools
- Dirty Hands



Scalability

Consistent Approach

(0.) Determine optimization requirements

1. Profile: determine hotspots
2. Analyze hotspots: determine scalability
3. Apply high level optimizations to hotspots
4. Profile again.
5. Parallelize / vectorize / use GPGPU
6. Profile again.
7. Apply low level optimizations to hotspots
8. Repeat step 6 and 7 until time runs out
9. Report.

```

ics
& (depth < MAXDEPTH)
{
    if (inside & !isFront)
    {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) *
Tr) R = (D * nnt - N * (ddn
E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)
survive = SurvivalProbability( diffuse, r
estimation - doing it properly, closely
if;
radiance = SampleLight( &rand, I, &L, &light;
e.x + radiance.y + radiance.z) > 0) && (rand
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following S&#246;
vive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



Scalability

Consistent Approach

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * r);
Tr) R = (D * nnt - N * (ddn * r + 1));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;
}

MAXDEPTH)
survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, Alignment );
e.x + radiance.y + radiance.z) > 0) && (depth <
{
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
}

random walk - done properly, closely following
( survive )
{
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, Spdf );
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}

```

(0.) Determine optimization requirements

1. Profile: determine hotspots

2. Analyze hotspots: determine scalability

3. Apply high level optimizations to hotspots

4. Profile again.

5. Parallelize

6. Use GPGPU

7. Profile again.

8. Apply low level optimizations to hotspots

9. Repeat steps 7 and 8 until time runs out

10. Report.

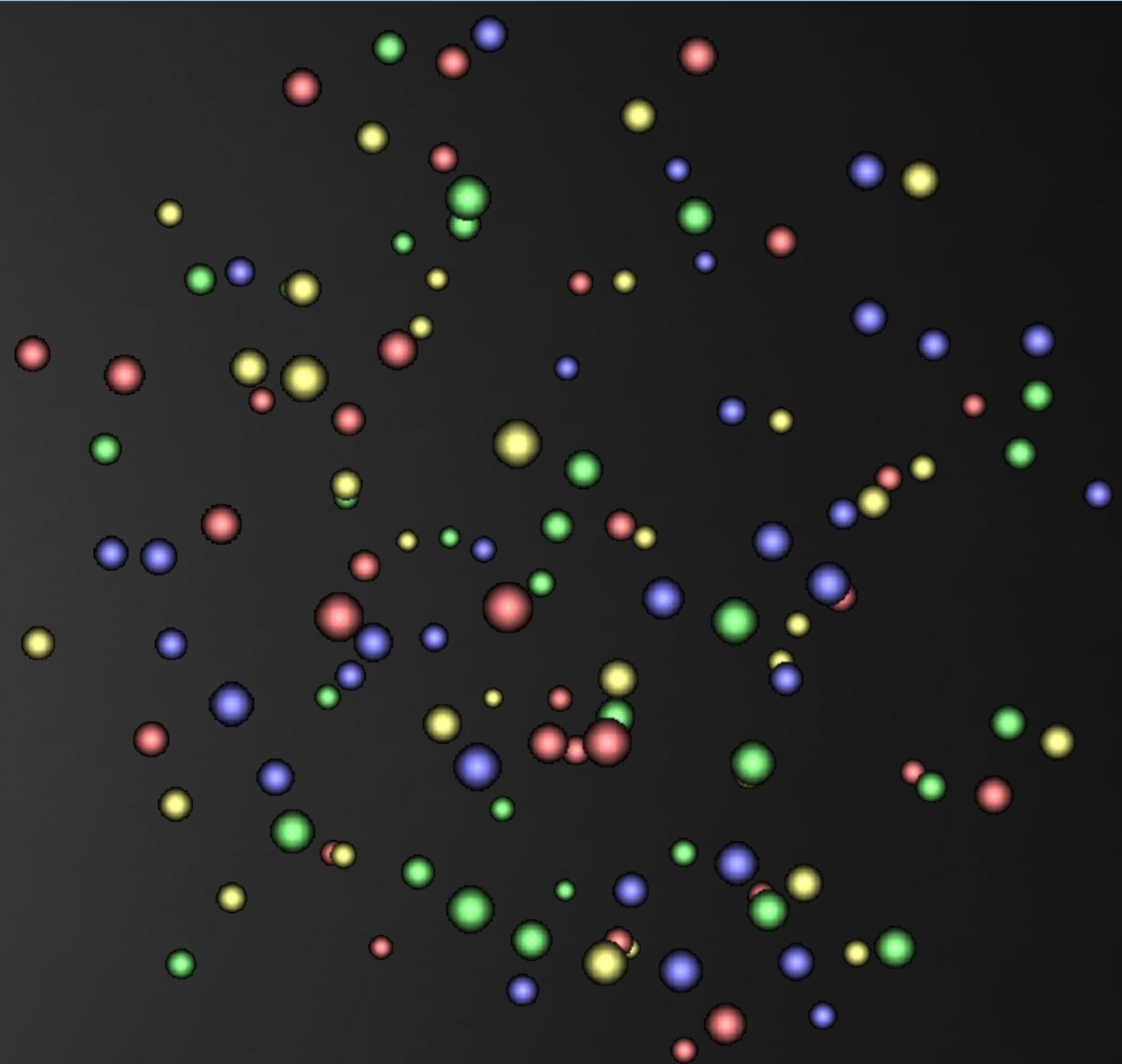


Scalability

```

ics
& (depth < MAXDEPTH)
{
  if (inside ? 1 : 0)
  {
    nt = nt / nc; ddn = ddn * ddn;
    cos2t = 1.0f - nnt * nnt;
    D, N );
  }
  at a = nt - nc, b = nt * n;
  at Tr = 1 - (R0 + (1 - R0) * a);
  Tr) R = (D * nnt - N * (ddn *
E * diffuse;
= true;
efl + refr) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light;
e.x + radiance.y + radiance.z) > 0) && (depth <
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following
ive)
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



Scalability

The Importance of Testing with the Target Workload

Code sections typically don't scale linearly when you increase the size of the dataset.

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        ps2t = 1.0f + nnt * nnt;
        D, N );
    }
}

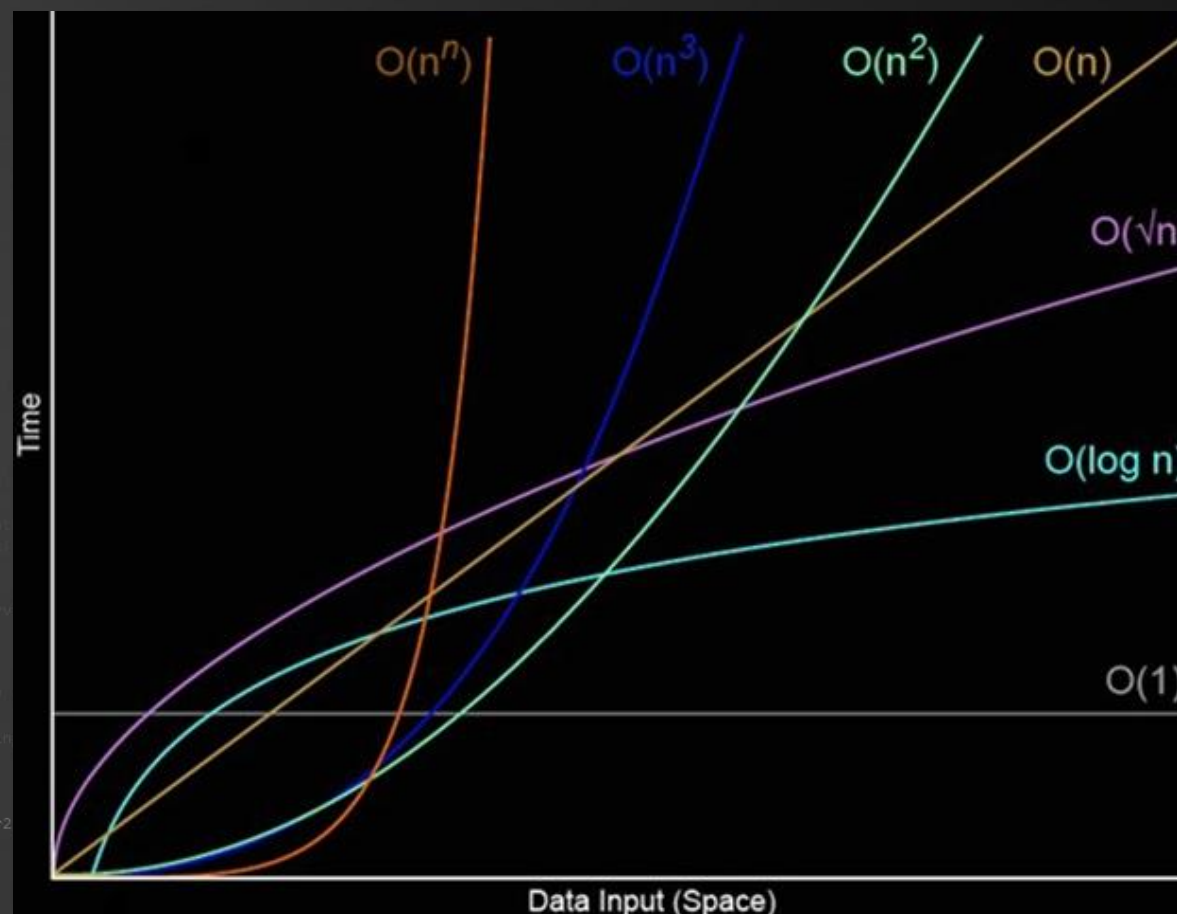
at a = nt - nc; b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * R);
Tr) R = (D * nnt - N * (ddn * nnt));

E * diffuse;
= true;

efl + refr) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;
}

MAXDEPTH)
{
    survive = SurvivalProbability( diffuse, 1);
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &light);
    e.x + radiance.y + radiance.z) > 0) && (rand.y < 0.5)
    {
        w = true;
        at brdfPdf = EvaluateDiffuse( L, N ) * Psum;
        at3 factor = diffuse * INVPI;
        at weight = Mis2( directPdf, brdfPdf );
        at cosThetaOut = dot( N, L );
        E * ((weight * cosThetaOut) / directPdf) *
    }
}

random walk - done properly, closely following
ive)
{
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2);
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}
    
```



Scalability

Improving Scalability

Remember:

Focus on low-hanging fruit.

The absolute best sorting algorithm depends on the dataset. Here:

- Somewhat sizeable
- Uniformly distributed
- Simple keys (depth: float)
- Mostly already sorted
- We don't need a perfect nor consistent sort

Optimal choice: probably Radix Sort, which can run in $O(N)$ under these circumstances.



Scalability

Improving Scalability

So:

I chose Quicksort. 😊

That seems an odd choice. Reasoning:

- Quicksort is much better than Bubblesort
- I can add Quicksort in minutes.
- I don't expect sorting to be a bottleneck after that.

The time required to add RadixSort is better spent elsewhere...

```

void Swap( vec3& a, vec3& b ) { vec3 t = a; a = b; b = t; }
int Pivot( vec3 a[], int first, int last )
{
    int p = first;
    vec3 e = a[first];
    for (int i = first + 1; i ≤ last; i++) if (a[i].z ≤ e.z) Swap( a[i], a[++p] );
    Swap( a[p], a[first] );
    return p;
}
void QuickSort( vec3 a[], int first, int last )
{
    int pivotElement;
    if (first ≥ last) return;
    pivotElement = Pivot( a, first, last );
    QuickSort( a, first, pivotElement - 1 );
    QuickSort( a, pivotElement + 1, last );
}
    
```




```
ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * r);
Tr) R = (D * nnt - N * (ddn * r));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)

survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light);
e.x + radiance.y + radiance.z) > 0) && (depth <
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance

random walk - done properly, closely following
vive)

;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```

Today's Agenda:

- Introduction
- Metrics, Clocks and Counters
- Scalability Issues
- Environment and Tools
- Dirty Hands



Tools

Profilers

- VerySleepy
- Intel VTune
- AMD µProf

Both profilers are sampling profilers:

They work by interrupting your program X times per second (typically: each millisecond).
 At this point, the profiler records at which address the CPU is executing code.

- A sampling profiler makes your software slower.
- A sampling profiler must store data, which affects the caches.
- Code that is visited infrequently may be missed by the sampling process.

```

ics
& (depth < MAXDEPTH)
{
    if ( ! inside )
        nt = nt / nc;
    double nnt = nnt * nt;
    double nnt2t = 1.0f * nnt * nt;
    double D, N );
}

at a = nt - nc; b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * R);
Tr) R = (D * nnt - N * (D0 + D1 * nnt));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)
survive = SurvivalProbability( diffuse, r1, r2, &R, Spdf );
estimation - doing it properly, closely following the
if;
radiance = SampleLight( &rand, I, &L, &light );
e.x + radiance.y + radiance.z ) > 0) && (survive)
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following the
ive)
;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, Spdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
    
```



Tools

Very Sleepy - C:\Users\bikke\AppData\Local\Temp\64D1.tmp

File View Help

Functions

Name	Exclu...	Inclusive	% Exclusive	% Inclusive	Module
Tmpl8::Sprite::DrawScaled	0.07s	0.07s	1.32%	1.32%	Tmpl8_2019-01
Tmpl8::Game::Tick	0.02s	0.14s	0.32%	2.89%	Tmpl8_2019-01
Tmpl8::Surface::Clear	0.02s	0.06s	0.32%	1.17%	Tmpl8_2019-01
Tmpl8::Game::Transform	0.00s	0.00s	0.04%	0.08%	Tmpl8_2019-01
_libm_sse2_sincosf_	0.00s	0.00s	0.04%	0.04%	Tmpl8_2019-01
SDL_main	0.00s	0.46s	0.00%	9.17%	Tmpl8_2019-01
main_getcmdline	0.00s	0.46s	0.00%	9.17%	Tmpl8_2019-01
__scrt_common_main_seh	0.00s	0.46s	0.00%	9.17%	Tmpl8_2019-01
Tmpl8::timer::get	0.00s	0.00s	0.00%	0.04%	Tmpl8_2019-01

Averages Call Stacks Filters

Main

Function Name	
Module	Tmpl8_2019-01
Source File	

Source Log

```

415 }
416
417 void Sprite::DrawScaled( float a_X, float a_Y, float a_Width, float
418 {
419     Pixel* dest = a_Target->GetBuffer() + (int)a_X + (int)a_Y * a_Ta
420     Pixel* src = GetBuffer() + m_CurrentFrame * 32;
421     0.01s for ( int y = 0; y < (int)a_Height; y++ ) for ( int x = 0; x < (
422     {
423         int v = (int)((y * 32) / a_Height);
424         0.01s int u = (int)((x * 32) / a_Width);
425         0.03s if (src[u + v * 128] & 0xffffffff)
426         0.01s     *(dest + x + y * a_Target->GetWidth()) = src[u + v * 128];
427     }
428 }
429
430 void Sprite::Tick(float dt)

```

Source file: C:\projects\dotcloud - tmp2019\surface.cpp Line 422



Tools

Profilers

VerySleepy

Intel VTune / AMD µProf

Always profile using the Release Configuration!

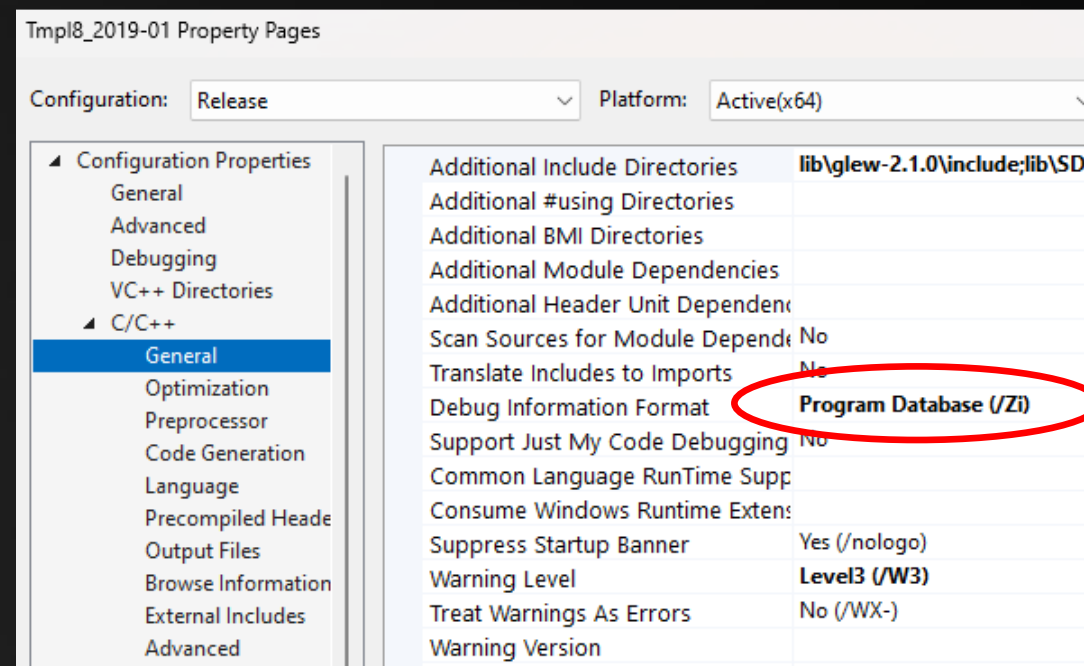
However:

All profilers need your project to be compiled with DEBUG information.

Enabling debug information in release mode in Visual Studio:

- Properties >> C/C++ >> General >> Debug information format
- Properties >> Linker >> Debugging >> Generate Debug Info

NOTE: The Visual Studio working folder is typically not where the .exe is, but where the .sln is.



Tools

Profilers

VerySleepy

Intel VTune

AMD µProf

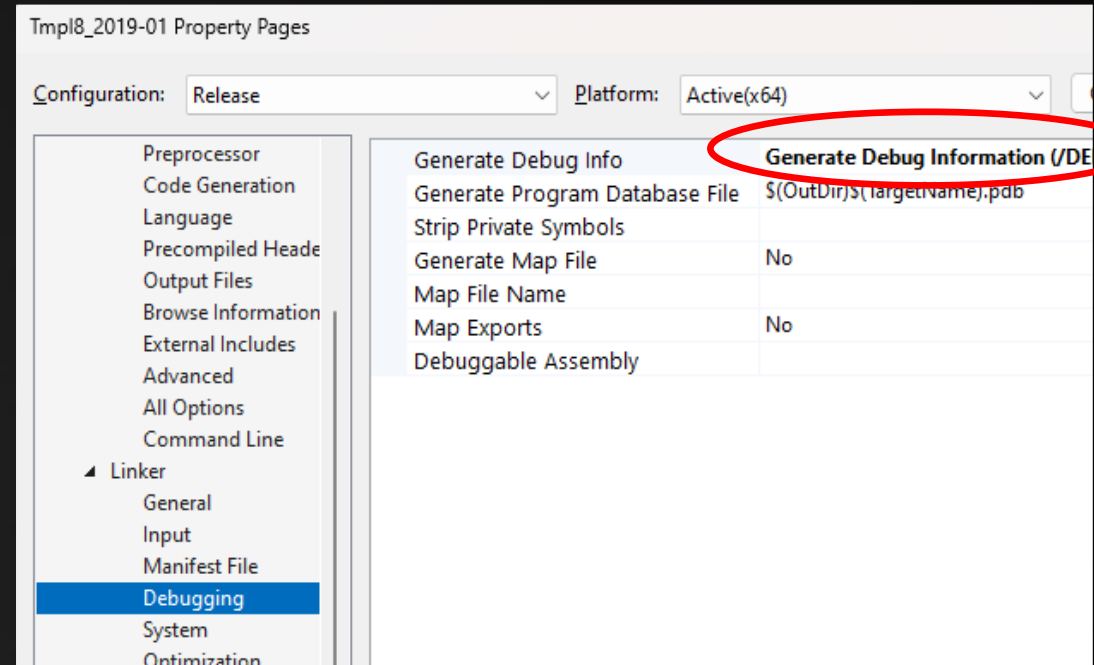
Always profile using the Release Configuration!

However:

All profilers need your project to be compiled with DEBUG information.

Enabling debug information in release mode in Visual Studio:

- Properties >> C/C++ >> General >> Debug information format
- Properties >> Linker >> Debugging >> Generate Debug Info



Tools

VerySleepy Data

Exclusive time:
time spent in the function, excluding calls to other functions.

Inclusive time:
time spent in the function and called functions.

Source code:
Tells you how much execution time is spent on a particular line. Profile longer to get more detailed results.

VerySleepy will not tell you *why* a particular function or line is ‘expensive’.

Very Sleepy - C:\Users\bikke\AppData\Local\Temp\64D1.tmp

File View Help

Functions	Name	Exclu...	Inclusive	% Exclusive	% Inclusive	Module
	Tmpl8-Sprite::DrawScaled	0.07s	0.07s	1.32%	1.32%	Tmpl8_2019-01
	Tmpl8-Game::Tick	0.02s	0.14s	0.32%	2.89%	Tmpl8_2019-01
	Tmpl8-Surface::Clear	0.02s	0.06s	0.32%	1.17%	Tmpl8_2019-01
	Tmpl8-Game::Transform	0.00s	0.00s	0.04%	0.08%	Tmpl8_2019-01
	__libm_sse2_sincosf_	0.00s	0.00s	0.04%	0.04%	Tmpl8_2019-01
	SDL_main	0.00s	0.46s	0.00%	9.17%	Tmpl8_2019-01
	main_getcmdline	0.00s	0.46s	0.00%	9.17%	Tmpl8_2019-01
	__srt_common_main_seh	0.00s	0.46s	0.00%	9.17%	Tmpl8_2019-01
	Tmpl8:timer::get	0.00s	0.00s	0.00%	0.04%	Tmpl8_2019-01

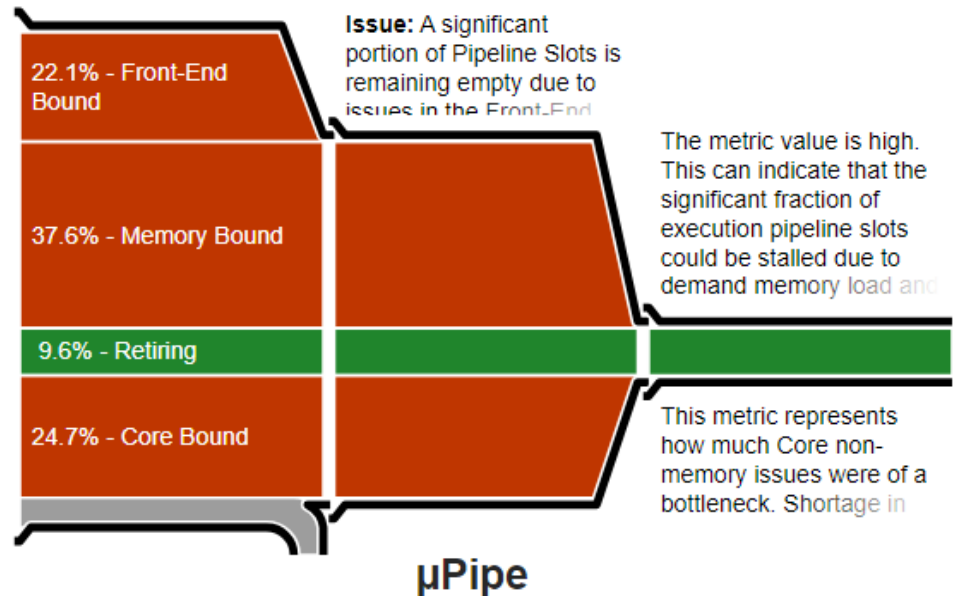
Source	Log
415	}
416	
417	void Sprite::DrawScaled(float a_X, float a_Y, float a_Width, float
418	{
419	Pixel* dest = a_Target->GetBuffer() + (int)a_X + (int)a_Y * a-Ta
420	Pixel* src = GetBuffer() + m_CurrentFrame * 32;
421	0.01s for (int y = 0; y < (int)a_Height; y++) for (int x = 0; x < (
422	{
423	int v = (int)((y * 32) / a_Height);
424	0.01s int u = (int)((x * 32) / a_Width);
425	0.03s if (src[u + v * 128] & 0xffffffff)
426	0.01s *(dest + x + y * a_Target->GetWidth()) = src[u + v * 128];
427	}
428	}
429	
430	

Source file: C:\projects\dotcloud - tmp2019\surface.cpp Line 422



Elapsed Time: 4.843s

Clockticks:	3,193,200,000
Instructions Retired:	1,461,600,000
CPI Rate:	2.185
MUX Reliability:	0.736
Retiring:	9.6% of Pipeline Slots
Front-End Bound:	22.1% of Pipeline Slots
Bad Speculation:	6.0% of Pipeline Slots
Back-End Bound:	62.4% of Pipeline Slots
Memory Bound:	37.6% of Pipeline Slots
L1 Bound:	0.0% of Clockticks
DTLB Overhead:	100.0% of Clockticks
Load STLB Hit:	100.0% of Clockticks
Load STLB Miss:	6.2% of Clockticks
Loads Blocked by Store Forwarding:	0.0% of Clockticks
Lock Latency:	1.0% of Clockticks
Split Loads:	0.0% of Clockticks
4K Aliasing:	0.2% of Clockticks
FB Full:	100.0% of Clockticks
L2 Bound:	0.0% of Clockticks
L3 Bound:	11.6% of Clockticks
Contested Accesses:	0.0% of Clockticks
Data Sharing:	0.0% of Clockticks
L3 Latency:	7.0% of Clockticks
SQ Full:	0.0% of Clockticks
DRAM Bound:	40.8% of Clockticks
Memory Bandwidth:	34.9% of Clockticks
Memory Latency:	31.1% of Clockticks
Store Bound:	1.9% of Clockticks
Core Bound:	24.7% of Pipeline Slots
Average CPU Frequency:	3.8 GHz
Total Thread Count:	16
Paused Time:	0s



This diagram represents inefficiencies in CPU usage. Treat it as a pipe with an output flow equal to the "pipe efficiency" ratio: (Actual Instructions Retired)/(Maximum Possible [Instruction Retired](#)). If there are pipeline stalls decreasing the pipe efficiency, the pipe shape gets more narrow.

Effective Physical Core Utilization: 3.5% (0.140 out of 4)

Effective Logical Core Utilization: 2.2% (0.172 out of 8)

Effective CPU Utilization Histogram

This histogram displays a percentage of the wall time the specific number of CPUs were running simultaneously. Spin and Overhead time adds to the Idle CPU utilization value.

Source

Assembly



Source Line ▲	Source	🔥 Clockticks	Instructions Retired	CPI Rate	Retiring »
416					
417	<code>void Sprite::DrawScaled(float a_X, float a_Y, float a_Width, float a_Height, Surface* a_Target)</code>				
418	<code>{</code>	0	1,800,000	0.000	
419	<code>Pixel* dest = a_Target->GetBuffer() + (int)a_X + (int)a_Y * a_Target->GetPitch();</code>				
420	<code>Pixel* src = GetBuffer() + m_CurrentFrame * 32;</code>	1,800,000	0		
421	<code>for (int y = 0; y < (int)a_Height; y++) for (int x = 0; x < (int)a_Width; x++)</code>	21,600,000	34,200,000	0.632	
422	<code>{</code>				
423	<code>int v = (int)((y * 32) / a_Height);</code>				
424	<code>int u = (int)((x * 32) / a_Width);</code>	30,600,000	106,200,000	0.288	
425	<code>if (src[u + v * 128] & 0xffffffff)</code>	100,800,000	192,600,000	0.523	
426	<code>*(dest + x + y * a_Target->GetWidth()) = src[u + v * 128];</code>	57,600,000	120,600,000	0.478	
427	<code>}</code>				
428	<code>}</code>				
429					
430	<code>void Sprite::InitializeStartData()</code>				
431	<code>{</code>				
432	<code>for (unsigned int f = 0; f < m_NumFrames; ++f)</code>				
433	<code>{</code>				
434	<code>m_Start[f] = new unsigned int[m_Height];</code>				
435	<code>for (int y = 0; y < m_Height; ++y)</code>				
436	<code>{</code>				
437	<code>m_Start[f][y] = m_Width;</code>				
438	<code>Pixel* addr = GetBuffer() + f * m_Width + y * m_Pitch;</code>				
439	<code>for (int x = 0; x < m_Width; ++x)</code>				
440	<code>{</code>				
441	<code>if (addr[x])</code>				
442	<code>{</code>				
443	<code>m_Start[f][y] = x;</code>				
444	<code>break;</code>				
445	<code>}</code>				
446	<code>}</code>				
447	<code>}</code>				
448	<code>}</code>				

Tools

VTune Data

VTune gives you a *lot* of information.

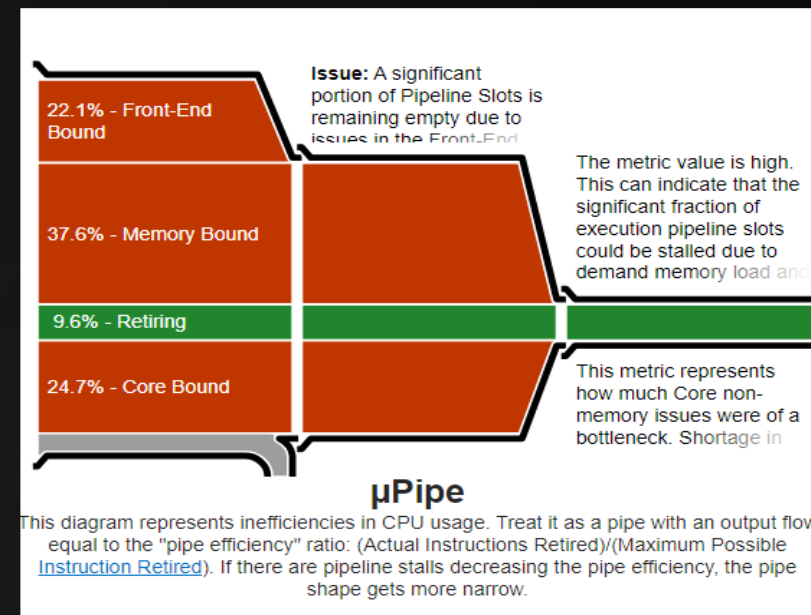
Don't expect to understand it all at once! That being said:

Executed
Retired
CPI/IPC
Micro-ops

instructions that entered the pipeline
instructions for which 'WB' was done
instructions per cycle / cycles per instruction
many instructions are converted into several *micro-ops*.
In some cases, several instructions are *fused* in a single micro-op.
More info: <https://easyperf.net/blog/2018/02/23/MacroFusion-in-Intel-CPU#micro--macro-fusion>

i	1	2	3	4	5	6
Branch (a<b)	IF	ID			EX	WB
Call foo		IF*	ID*	EX*		
// instr. foo			IF*	ID*	EX*	

t



VTune will also tell you about:

Cache misses (L1, L2, L3)
Branch mispredictions
...and a lot more.



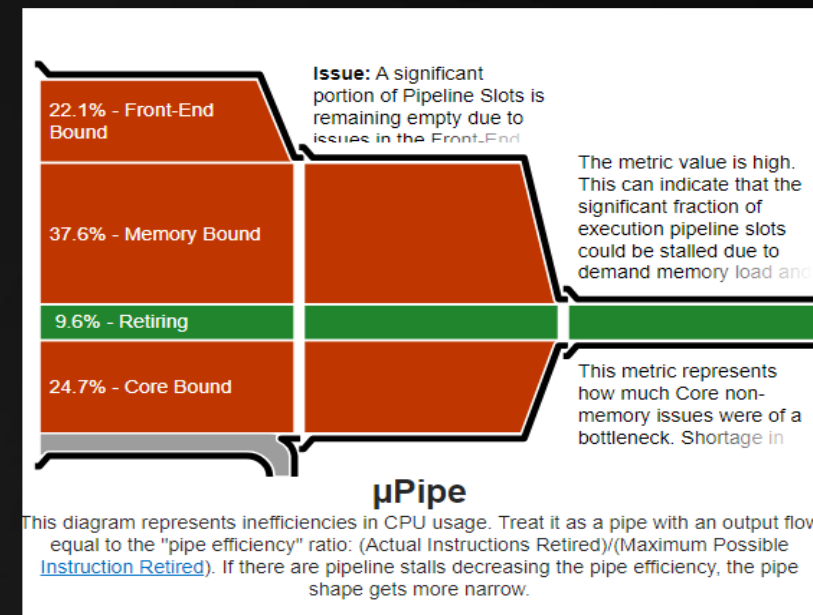
Tools

VTune Data

Intel's VTune gives you a *lot* of information.

Some tips:

1. Only look at specific data for specific problems
2. There's good online resources for VTune
3. Quite often, VerySleepy gets you everything you need...
4. A latency often shows up late:
 - E.g., when the result of a sqrt is *used*
5. Intel VTune does *not* work on AMD processors:
 - *It uses CPU-specific hardware counters.*

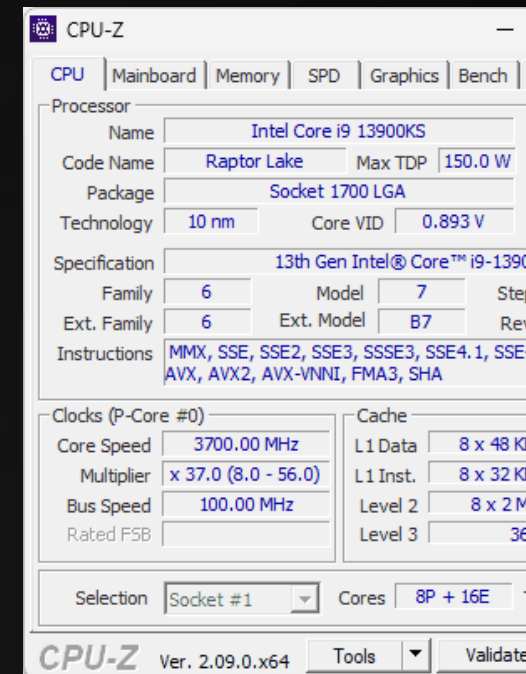


Tools

Environment

To obtain the most stable results:

- Disable all features that change the clock speed of your CPU
(warning: can be dangerous, use at your own risk)
- Windows: Create a power plan that *undervolts* the CPU significantly
(verify using CPU-Z)
- Profile the code single-threaded, if possible
(except when specifically optimizing threading behavior)
- Profile the code on a single core
(windows: SetThreadAffinityMask)



Scalability

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * ddn;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

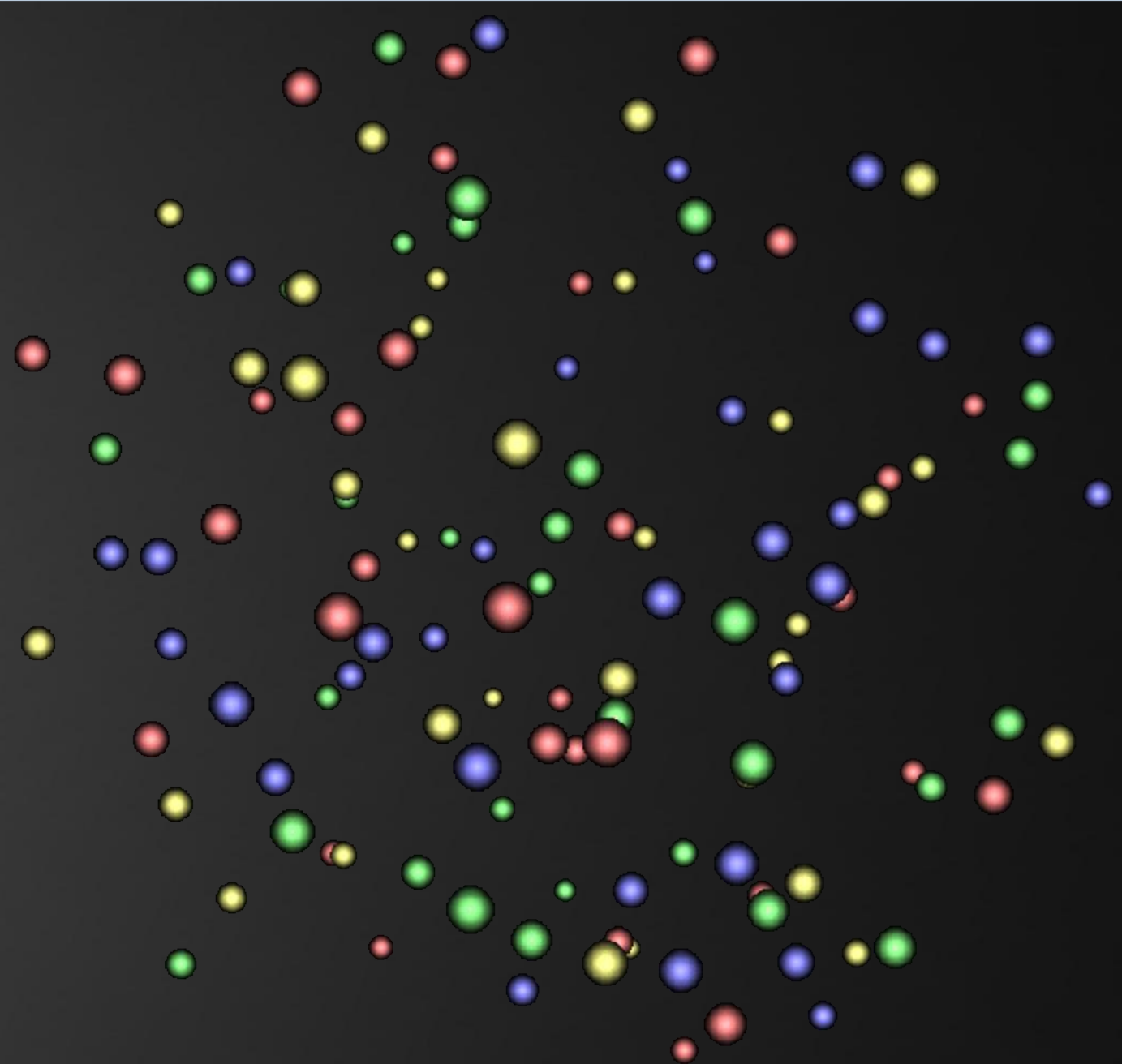
at a = nt - nc; b = nt * nc;
at Tr = 1 - (R0 + (1 - R0) * nnt);
Tr) R = (D * nnt - N * (ddn * nnt));

E * diffuse;
= true;

efl + refr) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;
}

MAXDEPTH)
{
    survive = SurvivalProbability( diffuse );
    estimation - doing it properly, closely following
    if;
    radiance = SampleLight( &rand, I, &L, &align);
    e.x + radiance.y + radiance.z > 0) && (depth <
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
}

random walk - done properly, closely following
ive)
{
    at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
    survive;
    pdf;
    n = E * brdf * (dot( N, R ) / pdf);
    sion = true;
}
    
```



Blind Stupidity

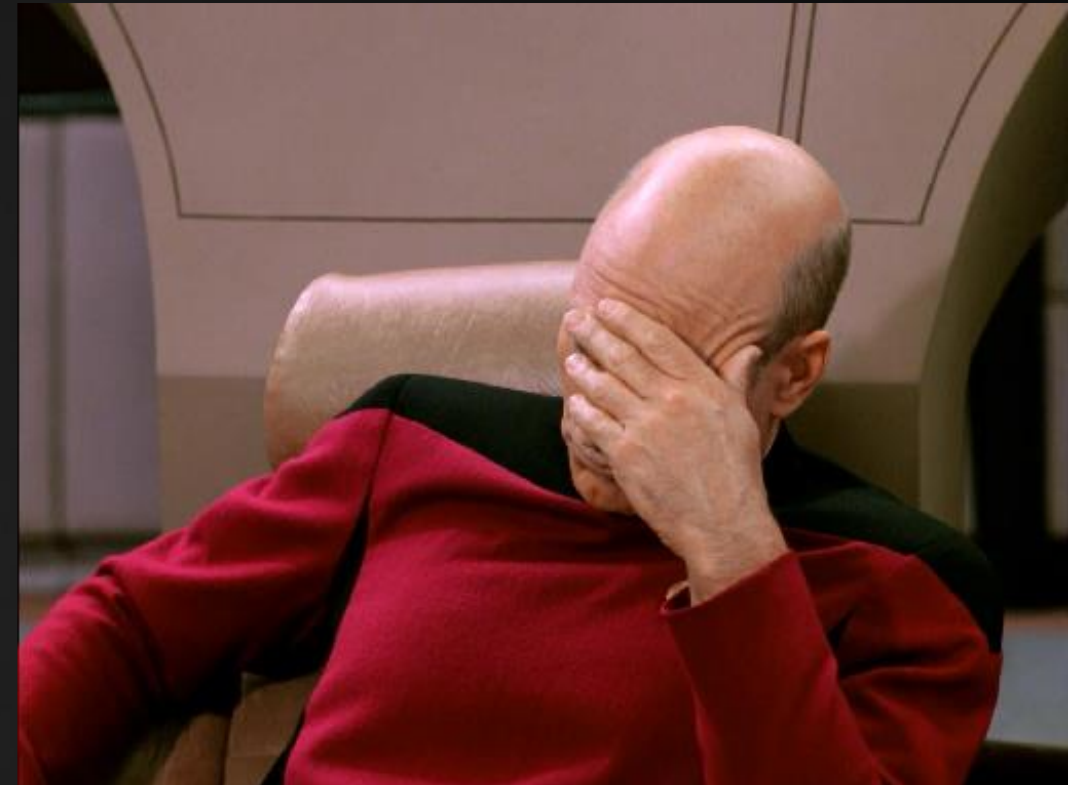
Low Level Optimization of DrawScaled

Now what?

- Plot multiple pixels at a time?
- ...

How many different ball sizes do we encounter?

...Why don't we simply pre-calculate those frames?



```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = abs(ddn);
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * ddn);
Tr) R = (D * nnt - N * (ddn > 0 ? 1 : -1));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;

MAXDEPTH)
survive = SurvivalProbability( diffuse, r1, r2, &R, $pdf );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, Align );
e.x + radiance.y + radiance.z) > 0) && (depth < MAXDEPTH)
{
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance
    random walk - done properly, closely following
    survive)
};
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, $pdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
    
```



Blind Stupidity

```

ics
& (depth < MAXDEPTH)
{
    if (inside ? 1 : 0)
    {
        nt = nt / nc; ddn = ddn * nc;
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }

    at a = nt - nc, b = nt + nc;
    at Tr = 1 - (R0 + (1 - R0) *
    Tr) R = (D * nnt - N * (ddn
    E * diffuse;
    = true;

    refl + refr) && (depth < MAXDEPTH)
    D, N );
    refl * E * diffuse;
    = true;

MAXDEPTH)

survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light;
e.x + radiance.y + radiance.z) > 0) && (abs(radiance
v = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance

random walk - done properly, closely following
ive)

;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf;
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```

“More computing sins are committed in the name of efficiency (without necessarily achieving it) than for any other single reason – including blind stupidity.” (W.A. Wulff)



Blind Stupidity

Low Level Optimization of Sprite::Draw

Pre-scaled sprites are faster than on-the-fly scaling.

But, we still have loops, and if-statements, and look-ups. I wonder...

```

ics
& (depth < MAXDEPTH)
{
    if (inside & !isLight)
    {
        nt = nt / nc; ddn = abs(ddn);
        cos2t = 1.0f - nnt * ddn;
        D, N );
    }
}

at a = nt - nc, b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * ddn);
Tr) R = (D * nnt - N * (ddn > 0 ? 1 : -1));

E * diffuse;
= true;

efl + refr)) && (depth < MAXDEPTH)
{
    D, N );
    refl * E * diffuse;
    = true;

MAXDEPTH)

survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light);
e.x + radiance.y + radiance.z) > 0) && (abs(radiance.x) > 0 || abs(radiance.y) > 0 || abs(radiance.z) > 0)
{
    w = true;
    at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
    at3 factor = diffuse * INVPI;
    at weight = Mis2( directPdf, brdfPdf );
    at cosThetaOut = dot( N, L );
    E * ((weight * cosThetaOut) / directPdf) * (radiance.x * L.x + radiance.y * L.y + radiance.z * L.z);
}

random walk - done properly, closely following
(ive)

;
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf );
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



Low Level Optimization of Sprite::Draw

Extreme Optimization:

- We simply generate a function that plots every pixel, without the need for a loop.

```
void Sprite::DrawBall( int x, int y, int size,
                    Surface* target )
{
    uint* a = target->GetBuffer() + x + y * SCRWIDTH;
    switch( size )
    {
        case 1:
            break;
        case 2:
            a[1]=1052688;
            a[800]=1052688;
            a[801]=15724527;
            break;
        case 3:
            a[801]=9737364;
            a[802]=8684676;
            a[1601]=8684676;
            a[1602]=8092539;
            break;
        case 4:
            a[2]=1052688;
            a[801]=6513507;
            a[802]=9737364;
            a[803]=4868682;
            a[1600]=1052688;
            a[1601]=9737364;
            a[1602]=15724527;
            a[1603]=7566195;
            a[2401]=4868682;
            a[2402]=7566195;
            a[2403]=3223857;
            break;
    }
}
```



Low Level Optimization of Sprite::Draw

Extreme Optimization:

- We simply generate a function that plots every pixel, without the need for a loop.

```
FILE* f = fopen( "drawfunc.h", "w" );
fprintf( f, "void Sprite::DrawBall( int x, int y, int size, Surface* target )\n" );
fprintf( f, "{\nuint* a = target->GetBuffer() + x + y * SCRWIDTH;\nswitch( size )\n{\n" );
for( int i = 0; i < 64; i++ )
{
    ...
    fprintf( f, "case %i:\n", size );
    for( int y = 0; y < size; y++ ) for( int x = 0; x < size; x++ )
    {
        int a = y * SCRWIDTH + x;
        if ( scaled[i]->GetBuffer()[x + y * size] & 0xffffffff )
            fprintf( f, "a[%i]=%i;\n", a, scaled[i]->GetBuffer()[x + y * size] & 0xffffffff );
    }
    fprintf( f, "break;\n" );
}
fprintf( f, "}\n}\n" );
```




```

ics
& (depth < MAXDEPTH)
c = inside ? 1.0f : 0.0f;
nt = nt / nc; ddn = sqrt(1 - c);
cos2t = 1.0f - nnt * ddn;
D, N );
)
at a = nt - nc; b = nt + nc;
at Tr = 1 - (R0 + (1 - R0) * ddn);
Tr) R = (D * nnt - N * (ddn * ddn));
E * diffuse;
= true;
efl + refr)) && (depth < MAXDEPTH)
D, N );
refl * E * diffuse;
= true;
MAXDEPTH)
survive = SurvivalProbability( diffuse );
estimation - doing it properly, closely following
if;
radiance = SampleLight( &rand, I, &L, &light);
e.x + radiance.y + radiance.z) > 0) && (depth <
w = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Psurvive;
at3 factor = diffuse * INVPI;
at weight = Mis2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
random walk - done properly, closely following 3D
vive)
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf);
survive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;

```



“Madness!? This is INFOMOV!”





/INFOMOV/

END of “Low Level”

next lecture: “Caches (1)”

```
... = true;
at brdfPdf = EvaluateDiffuse( L, N ) * Pdf;
at3 factor = diffuse * INVPI;
at weight = Mix2( directPdf, brdfPdf );
at cosThetaOut = dot( N, L );
E * ((weight * cosThetaOut) / directPdf) * (radiance
...
random walk - done properly, closely following
...
ive)
:
at3 brdf = SampleDiffuse( diffuse, N, r1, r2, &R, &pdf
...
urvive;
pdf;
n = E * brdf * (dot( N, R ) / pdf);
sion = true;
```

